



**RETURN BIDS TO:**  
**RETOURNER LES SOUMISSIONS À:**

**LETTER OF INTEREST**  
**LETTRE D'INTÉRÊT**

Comments - Commentaires

<b>Title - Sujet</b> NOMAD Payload	
<b>Solicitation No. - N° de l'invitation</b> W8472-185712/A	<b>Date</b> 2018-06-07
<b>Client Reference No. - N° de référence du client</b> W8472-185712	<b>GETS Ref. No. - N° de réf. de SEAG</b> PW-\$\$FX-011-26859
<b>File No. - N° de dossier</b> 011fx.W8472-185712	<b>CCC No./N° CCC - FMS No./N° VME</b>
<b>Solicitation Closes - L'invitation prend fin</b> <b>at - à 02:00 PM</b> <b>on - le 2018-07-20</b>	
<b>Time Zone</b> <b>Fuseau horaire</b> Eastern Daylight Saving Time EDT	
<b>F.O.B. - F.A.B.</b> Specified Herein - Précisé dans les présentes <b>Plant-Usine:</b> <input type="checkbox"/> <b>Destination:</b> <input type="checkbox"/> <b>Other-Autre:</b> <input checked="" type="checkbox"/>	
<b>Address Enquiries to: - Adresser toutes questions à:</b> Laporte, Christian	<b>Buyer Id - Id de l'acheteur</b> 011fx
<b>Telephone No. - N° de téléphone</b> (819) 939-3287 ( )	<b>FAX No. - N° de FAX</b> ( ) -
<b>Destination - of Goods, Services, and Construction:</b> <b>Destination - des biens, services et construction:</b>  Specified Herein Précisé dans les présentes	

Instructions: See Herein

Instructions: Voir aux présentes

**Vendor/Firm Name and Address**  
**Raison sociale et adresse du**  
**fournisseur/de l'entrepreneur**

<b>Delivery Required - Livraison exigée</b> See Herein	<b>Delivery Offered - Livraison proposée</b>
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<b>Name and title of person authorized to sign on behalf of Vendor/Firm</b> <b>(type or print)</b> <b>Nom et titre de la personne autorisée à signer au nom du fournisseur/</b> <b>de l'entrepreneur ( taper ou écrire en caractères d'imprimerie)</b>	
<b>Signature</b>	<b>Date</b>

**Issuing Office - Bureau de distribution**

Frigate Life Extension (FELEX) Project / Bureau de projet  
de prolongation de la vie des frégates (BP FELEX)  
455 Blvd de la Carriere  
Gatineau  
Quebec  
K1A 0K2



Destination Code - Code destinataire	Destination Address - Adresse de la destination	Invoice Code - Code bur.-comptable	Invoice Address - Adresse de facturation
D - 1	FORMATION COMMANDER HMC DOCKYARD Bldg D-206 Door 1 thru 13 Halifax NS HALIFAX NS B3K 5X5 CANADA	W8472	DEPARTMENT OF NATIONAL DEFENCE ATTN DGMEPM CAP - DMARP 101 COLONEL BY DR. OTTAWA Ontario K1A0K2 Canada



Item Article	Description	Dest. Code Dest.	Inv. Code Fact.	Qty Qté	U. of I. U. de D.	Unit Price/Prix unitaire		Del. Offered Liv. offerte
						Destination	FOB/FAM Plant/Usine	
1	NOMAD Payload	D - 1	W8472	2	Each	\$	\$	See Herein
2	NOMAD Payload Option	D - 1	W8472	2	Each	\$	\$	See Herein

## **Request for Information (RFI)**

### **1. Purpose**

Public Works Government Services Canada's (PWGSC) intent for this RFI is to engage Industry in a consultative process by seeking industry feedback on the Department of National Defense's (DND) requirement to procure Naval Offboard anti-Missile Active Decoy (NOMAD) systems that are designed to function in a marine environment with an existing Royal Canadian Navy (RCN) Unmanned Surface Vehicle (USV).

The information provided by industry may be used to support Canada's decision-making process such as finalizing requirements and determining the procurement strategy.

As the project progresses towards a formal Request for Proposal (RFP), this RFI will provide a continuous single point of official communication with industry. The project will use this RFI process for multiple purposes such as:

- Collaborating with industry on the Statement of Work, Technical Statement of Requirement, the procurement strategy and the bid evaluation;
- Presenting questions to industry and soliciting comments and feedback;
- Ensure all interested participants receive the same information;

#### **This initial RFI release is to:**

- a) Gauge level of competition for this type of capability;
- b) Create a dialogue between Canada and Industry with the view of determining Industry's capability to provide Naval Offboard anti-Missile Active Decoy (NOMAD) systems;
- c) Request industry feedback on the Draft Statement of Work and the Draft Technical Statement of Requirement;
- d) Understanding capability and availability of potential existing commercial solutions and their general price point based on the requirements listed below;
- e) Request Industry to provide a Rough Order of Magnitude (ROM) cost for their proposed system. ROM estimates must include all system acquisition, training and travel costs;
- f) Request Industry to provide separate timelines for system design, system demonstration, and full system delivery;
- g) Invite industry to submit questions, comments, concerns with the requirement and insight into any related alternatives.

## 2. Nature of this RFI

This RFI is neither a call for tender nor a Request for Proposal (RFP). No agreement or contract will be entered into based on this RFI. The issuance of this RFI is not to be considered in any way a commitment by Canada, nor as authority to potential respondents to undertake any work that could be charged to Canada. This RFI is not to be considered as a commitment to issue a subsequent solicitation or to award contract(s) for the work described herein.

Although the information collected may be provided as commercial-in-confidence (and, if identified as such, will be treated accordingly by Canada), Canada may use the information for budgetary purposes and to assist in drafting the Statement of Work or any other documents. All documents may be subject to change at the discretion of Canada.

Respondents are encouraged to identify, in the information they share with Canada, any information that they feel is proprietary, third party or personal information. Please note that Canada may be obligated by law (e.g. in response to a request under the Access to Information and Privacy Acts) to disclose proprietary or commercially-sensitive information concerning a respondent (for more information: <http://laws-lois.justice.gc.ca/eng/acts/a-1/> ).

Respondents are asked to identify if their response, or any part of their response, is subject to the Controlled Goods Regulations.

Participation in this RFI is encouraged, but is not mandatory. There will be no short-listing of potential suppliers for the purposes of undertaking any future work resulting from this RFI. Similarly, participation in this RFI is not a condition or prerequisite for the participation in any potential subsequent solicitation.

Respondents will not be reimbursed for any cost incurred by participating in this RFI.

## 3. Background Information:

1.2.1 The NEAR-U (Naval Electronic Attack Recapitalization – Unmanned) project is one of the initiatives to revitalize the EA capability. The goal of NEAR-U project is to implement and test a potential solution to improve the naval platform's survivability by incorporating a NOMAD system into an Unmanned Surface Vehicle (USV) platform. DND will procure and integrate NOMAD systems into existing RCN Unmanned Surface Vehicles. The NOMAD system will be tested and evaluated as off-board active decoys or jammers for ship and task group Anti-Ship Missile Defence, as well as EW test set for radar testing and training.

#### **4. Requirement Overview:**

A NOMAD system is defined as a set of components designed and integrated into a USV to provide jamming capability against Anti-Ship Missile threats, and as well as, radar testing and training capacity.

The purpose of the NOMAD system is two-fold:

- 1) Anti-Ship Missile Defence (ASMD) in a self-protection and Task Group (TG) setting and
- 2) Radar testing and Training.

The NOMAD system will be integrated in existing RCN USV platforms. The USV and the NOMAD system will be launched, recovered, and remotely controlled from the Controlling Platform. Line-of-Sight control will be maintained with the Controlling Platform.

#### **5. Legislation, Trade Agreements, and Government Policies:**

The following is indicative of some of the legislation, trade agreements and government policies that could impact any follow-on solicitation(s):

a) This procurement may not be subject to the trade agreements as the National Security Exception has been sought;

b) Comprehensive Land Claim Agreements (CLCA): (if applicable);

The provisions of the Comprehensive Land Claims Agreements will not apply to this procurement unless work is performed and / or goods are delivered within a land claim settlement area.

c) This procurement will be subject to the Controlled Goods Program. For further information on the CGP, visit: <http://ssi-iss.tpsgc-pwgsc.gc.ca/dmc-cgd/index-eng.html>;

d) The Federal Contractors Program for Employment Equity will apply to this procurement. For further information on the Federal Contractors Program for Employment Equity, visit: <https://buyandsell.gc.ca/policy-and-guidelines/supply-manual/annex/5/1>;

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File No. - N° du dossier  
011FX.W8472-185712

Buyer ID - Id de l'acheteur  
011fx  
CCC No./N° CCC - FMS No./N° VME

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## 6. Estimated Project Schedule:

- Request For Information (RFI): June/July 2018
- RFP issued: Fall 2018
- Bid Evaluation: Fall 2018
- Contract Award: Winter 2018

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## **7. Important Notes to Respondents:**

Interested Respondents may submit their responses and questions to the PSPC Contracting Authority, identified below via email:

Christian Laporte  
Supply Team Leader  
Public Services and Procurement Canada  
Acquisitions Branch  
Marine Services and Small Vessels  
Address: 455, De la Carrière Blvd  
Telephone: 819-939-3287  
E-mail: [Christian.laporte@pwgsc.gc.ca](mailto:Christian.laporte@pwgsc.gc.ca)

A point of contact for the Respondent should be included in the package.  
Changes to this RFI may occur and will be advertised on [Buyandsell.gc.ca](http://Buyandsell.gc.ca). Canada asks Respondents to visit [Buyandsell.gc.ca](http://Buyandsell.gc.ca) regularly to check for changes, if any.

All enquiries and other communications related to this RFI shall be directed exclusively to the PSPC Contracting Authority.

All enquiries must be submitted to the Contracting Authority no later than ten (10) calendar days before the RFI closing date. Enquiries received after that time may not be answered.

Because this is not a bid solicitation, Canada reserves the right to respond to enquiries pertinent to the requirement.

Please include the appropriate RFI paragraph number in any comments or questions that you provide/ask.

Please provide your feedback using an Excel file and return the Excel file to the PWGSC Contracting Authority.

## **8. Language of Response**

Correspondence, questions and responses may be submitted in either official language of Canada.

## **9. Review Team**

A review team composed of representatives of the Department of National Defence and PSPC will review the responses.

Canada reserves the right to hire any independent consultant, or use any Government resources that it considers necessary to review any response.

Not all members of the review team will necessarily review all responses.

## **10. Closing date for the RFI**

The RFI will remain active until **20<sup>th</sup> of July 2018**.

Responses to this RFI are to be submitted to the PSPC Contracting Authority identified above.

## **11. List of Annexes**

- **Annex 1 – Draft Statement of Work**
- **Annex 2 – Draft Technical Statement of Requirement**

**DRAFT**  
**STATEMENT OF WORK**

**Naval Offboard anti-Missile Active Decoy (NOMAD)  
System**

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## 1 SCOPE

### 1.1 OBJECTIVE

- 1.1.1 The Department of National Defence (DND) has a requirement to procure NOMAD systems that are designed to function in a marine environment with existing Royal Canadian Navy (RCN) Unmanned Surface Vehicles (USV).

### 1.2 BACKGROUND

- 1.2.1 The NEAR-U (Naval Electronic Attack Recapitalization – Unmanned) project is one of the initiatives to revitalize the Electronic Attack (EA) capability. The goal of NEAR-U project is to implement and test a potential solution to improve the naval platform's survivability by incorporating a NOMAD system into an Unmanned Surface Vehicle (USV) platform. DND will procure and integrate NOMAD systems into existing RCN Unmanned Surface Vehicles. The NOMAD system will be tested and evaluated as off-board active decoys or jammers for ship and task group Anti-Ship Missile Defence, as well as Electronic Warfare test set for radar testing and training.

### 1.3 LIST OF ACRONYMS

ASM	Anti-Ship Missile
ASMD	Anti-Ship Missile Defence
BITE	Built-In Test Equipment
BW	Bandwidth
CA	Contract Authority
CDRL	Contract Data Requirement List
CEIL	Contract End Item List
dB	decibel
dBW	decibel Watt
DID	Deliverable Item Description
DND	Department of National Defence
DRFM	Digital Radio Frequency Memory
DRI	Detection Recognition Identification
EA	Electronic Attack
EW	Electronic Warfare
ECP	Engineering Change Proposal
EO	Electro-Optical
ERP	Effective Radiated Power
FAT	Factory Acceptance Test
FPR	Final Progress Review
FSR	Field Service Representative
GHz	Gigahertz
GFI	Government Furnished Information
HAT	Harbor Acceptance Trial
HAZMAT	Hazardous Materials
HVU	High Value Unit
HPoT	Horizontal Pixels on Target

IAW	In Accordance With
LRU	Lowest Replaceable Unit
MACA	Months After Contract Award
MOTS	Military-Off-The-Shelf
MTSC	Meggitt Training Systems Canada
MSDS	Material Safety Data Sheets
NEAR-U	Naval Electronic Attack Recapitalization - Unmanned
NOMAD	Naval Offboard anti-Missile Active Decoy
OEM	Original Equipment Manufacturer
PM	Project Manager
PA	Procurement Authority
PPB	Provisioning Parts Breakdown
PRF	Pulse Repetition Frequency
PRI	Pulse Repetition Interval
PRM	Progress Review Meeting
PSR	Project Status Report
PSPC	Public Services and Procurement Canada
PW	Pulse Width
QAR	Quality Assurance Representative
RCN	Royal Canadian Navy
RGS	Range Gate Steal
RGPO	Range Gate Pull Off
RSPL	Recommended Spare Parts List
Rx	Receive
SAT	Sea Acceptance Trial
SOW	Statement of Work
SPTD	Supplementary Provisioning Technical Documentation
TA	Technical Authority
TBD	To Be Determined
TDP	Technical Data Package

TG	Task Group
TRM	Technical Review Meeting
TSOR	Technical Statement of Requirements
Tx	Transmit
USV	Unmanned Surface Vehicles
VGS	Velocity Gate Steal
VGPO	Velocity Gate Pull Off
VPoT	Vertical Pixels on Target
W	Watt

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## **2 APPLICABLE DOCUMENTS**

### **2.1 APPLICABILITY**

2.1.1 The following documents support the SOW and must be considered as supplemental if not specifically identified in the text. In an event of conflicts between the documents referenced below and the content of this SOW, the content of this SOW must take precedence. Where no versions or effective date of any reference is given, the applicable version or effective date at the time of the Contract Award must be used.

### **2.2 DND PUBLICATIONS**

1	C-01-100-100/AG-005, Adoption of Commercial and Foreign Government Publications
2	C-01-100-100/AG-006, Writing, Format, and Production of Technical Publications
3	C-01-000-103/AG-000, Guide to the Canadian Government Cataloguing System
4	C-02-006-009/AG-000, Field and Technical Service Representatives (FSR/TSR) Requirements and Terms of Reference
5	D-01-400-001/SG-000, Engineering Drawing Practices
6	D-01-400-002/SF-000, Drawings, Engineering, and Associated Lists
7	D-01-100-226/SF-001, Specification for Preparation of Test Sheets for Shipboard Systems and Equipment
8	D-01-100-202/SF-000, Preparation of Equipment Descriptions
9	D-01-100-203/SF-000, Preparation of Operation Instructions
10	D-01-100-214/SF-000, Preparation of Provisioning Documentation for Canadian Forces Equipment

### **2.3 OTHER PUBLICATIONS**

1	MIL-STD-810, Environmental Engineering Considerations and Laboratory Tests
2	Humpback USV-T Payload Integration Interface Control
3	Humpback USV-T Hardpoints Drawings

### **3 REQUIREMENTS**

#### **3.1 GENERAL**

- 3.1.1 The Contractor must supply two (2) NOMAD systems that meet the requirements of the Technical Statement of Requirements (TSOR).
- 3.1.2 The Contractor must carry out all of the work required to design, manufacture, deliver, and test NOMAD systems which meet the specifications of the TSOR.
- 3.1.3 The Contractor must provide waterproof, stackable, impact-resistant, and durable containers for onboard storage and transportation of the mast-mounted components of the NOMAD system.
- 3.1.4 The Contractor must provide Material Safety Data Sheets (MSDS) for all parts, assemblies and components that contain Hazardous Materials (HAZMAT).

#### **3.2 PROGRAM MANAGEMENT (PM)**

- 3.2.1 The Contractor will name a Project Manager (PM), placing the authority and responsibility for overall project management under a single point of contact. The PM must ensure the timely and efficient allocation of the Contractor's resources to meet the requirements of the SOW. The PM must have full responsibility for the operations of the Contractor and its sub-Contractors in the performance of the Work and must be authorized to accept on behalf of the Contractor any notice, consent, order, direction, decision or other communication that may be given to the Contractor.
- 3.2.2 The Contractor must provide a preliminary project schedule, as per DID PM-001, indicating the sequence and completion dates of project milestones, deliverables, and project tasks based on Contract Award as "day 0".
- 3.2.3 Kick-Off Meeting: Within one month of Contract Award, the Contractor must conduct a project Kick-Off Meeting, as per CDRL Appendix 1, DID PM-002, at the Contractor's facility. The discussions must include but not be limited to:
  - 3.2.3.1 The Project Schedule and Milestones;
  - 3.2.3.2 The Technical Specification;
  - 3.2.3.3 Critical path activities;
  - 3.2.3.4 Plans for the upcoming activities;
  - 3.2.3.5 Risk management concerns and mitigation actions; and
  - 3.2.3.6 Any other contractual or programmatic issues associated with the project as mutually agreed between the Technical Authority (TA), Procurement Authority (PA), Public Services and Procurement Canada (PSPC) Contracting Authority (CA) and the Contractor.

- 3.2.4 Progress Review Meetings (PRM): The Contractor must hold, at the minimum, one (1) PRM meeting per year, at the Contractor's facility or at DND location. The locations, dates, and times for meetings will be mutually agreed on by the TA, PA, PSPC CA, and the Contractor. The PRM meeting will address the following:
- 3.2.4.1 Discussions on progress to date of the work.
  - 3.2.4.2 Variation from planned progress and the corrective actions to be taken during the next reporting period.
  - 3.2.4.3 Discussions of foreseeable problems and proposed solutions, including an assessment of their impact on the Contract in terms of schedule, technical performance and risks.
- 3.2.5 Technical Review Meetings (TRM): The Contractor must host a TRM meeting no later than 6 months after Contract Award or as mutually agreed on by the TA. TRMs may be held more frequently at the request of the DND TA or the Contractor, should the need arise. Best effort should be made to have the TRM scheduled immediately preceding the PRM.
- 3.2.6 Minutes - The Contractor must keep Minutes as per CDRL Appendix 1, DID PM-003, for all meetings. The Minutes will record the content of the meeting including agreements reached and action items. A draft copy of the Minutes will be distributed to the PSPC CA, DND TA, and PA for review within five (5) working days after the meeting. Comments will be provided to the Contractor, within five (5) working days after the receipt of the draft copy, to be incorporated for distribution and signature by the PSPC CA, DND TA, and PA. For the TRMs, only the DND TA signature is required.
- 3.2.7 Progress Report - The Contractor must monitor the progress of the project and deliver Project Status Reports (PSR's) according to CDRL Appendix 1, DID PM-004.

### 3.3 INTEGRATION

- 3.3.1 The Contractor must design the NOMAD system to be mechanically integratable to the existing RCN's USV platform, with pre-defined mounting points and spaces allocated for the integration of the NOMAD system. The details of the mounting points and allocated spaces are provided in "*Humpback USV-T Hardpoints Drawings*".
- 3.3.2 The Contractor must design the NOMAD system to be electrically integratable to the existing RCN's USV platform in accordance with "*Humpback USV-T Payload Integration Interface Control*".
- 3.3.3 The Contractor must conduct the system engineering activities to produce a design that integrates the NOMAD system into the USV platform in accordance with the TSOR.

### 3.4 TEST AND TRIALS

- 3.4.1 Factory Acceptance Tests (FAT): The Contractor must provide copies of the FAT procedures and the expected test results consistent with CDRL Appendix 1, DID FAT-001.
  - 3.4.1.1 The FAT must be conducted by the Contractor for each NOMAD system and witnessed by DND TA or DND-authorized representatives.
  - 3.4.1.2 Upon completion of the FAT activities, the Contractor must provide a trial report in accordance with CDRL Appendix 1, DID TR-001 to report the results of the trial for each system unit to DND prior to its shipment.
- 3.4.2 Harbour Acceptance Trials (HATs): The Contractor must provide HAT procedures to verify the installation and integration of each NOMAD system into the USV, in accordance with CDRL Appendix 1, DID HAT-001.
  - 3.4.2.1 The HAT must be conducted by the Contractor for each NOMAD system and witnessed by the DND TA or DND-authorized representatives. The location of HAT will be on either East coast or West coast and will be determined by DND TA.
  - 3.4.2.2 Upon completion of the HAT activities, the Contractor must provide a trial report in accordance with DID TR-001 to report the results of the trials.

### **3.5 TRAINING AND TRAINING MATERIALS**

- 3.5.1 Operator's and Maintainer's Course: The Contractor must develop and deliver an operator-maintainer training course. The course must be offered at DND facilities, within the time period agreed by DND TA and the Contractor.
  - 3.5.1.1 The course must accommodate a class size up to 10 students.
  - 3.5.1.2 The course must provide theory, operation instructions, and maintenance instructions.
  - 3.5.1.3 The course must include interpretation of fault codes, where applicable, and carrying out repairs using a deliverable spares kit, if applicable.
  - 3.5.1.4 The course must include instructions and precautions to be observed in order to reduce downtime and improve the availability of the system.
  - 3.5.1.5 Training Materials: The Contractor must supply all training materials in accordance with CDRL Appendix 1, DID TRG-002. The supplied material must be used to conduct operator and shipboard maintenance courses for the ship's personnel by DND instructors.
  - 3.5.1.6 Course Reports: The Contractor must prepare Training Course Activity Reports for the Operator and Maintainer courses in accordance with CDRL Appendix 1, DID TRG-001.

### **3.6 INTEGRATED LOGISTIC SUPPORT**

- 3.6.1 The Contractor must provide Provisioning Documentation, including the Provisioning Parts Breakdown (PPB), Recommended Spare Parts List (RSPL), and Supplementary Provisioning Technical Documentation (SPTD) in accordance with CDRL Appendix 1, DID PD-001.
- 3.6.2 The Contractor must supply operation and maintenance manuals, modified to reflect the delivered NOMAD system configuration, in accordance with CDRL Appendix 1, DID PUB-001.
- 3.6.3 The Contractor must prepare and deliver the Technical Data Package (TDP) in accordance with CDRL Appendix 1, DID TDP-001.

### **3.7 TECHNICAL SUPPORT**

3.7.1 The Contractor may be tasked to provide field engineering support and technical advice throughout the project. The conditions requiring technical support may include, but not limited to:

3.7.1.1 Engineering support;

3.7.1.2 Technical investigations;

3.7.2 In the condition of equipment malfunctions or damage, the Contractor may be tasked to investigate any malfunction. The TA must be notified within five (5) working days from the time the Contractor determines the root cause of the damage. A copy of the Contractor's internal investigation must be sent to the TA.

3.7.3 The Contractor must submit an Activity Report after the completion of the work, in accordance with CDRL Appendix 1, DID FSR-001.

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**DRAFT**  
**TECHNICAL STATEMENT**  
**OF**  
**REQUIREMENT**  
**(TSOR)**

**Naval Offboard anti-Missile Active Decoy**  
**(NOMAD)**  
**System**



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**REFERENCES**

- a. MIL-STD-810: Environmental Engineering Considerations and Laboratory Tests
- b. Humpback USV-T Payload Integration Interface Control
- c. Humpback USV-T Hardpoints Drawings

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**LIST OF ACRONYMS**

ASM	Anti-Ship Missile
ASMD	Anti-Ship Missile Defence
BW	Bandwidth
CA	Contract Authority
CDRL	Contract Data Requirement List
CEIL	Contract End Item List
dB	decibel
dBW	decibel Watt
DID	Deliverable Item Description
DND	Department of National Defence
DRFM	Digital Radio Frequency Memory
DRI	Detection Recognition Identification
EA	Electronic Attack
EW	Electronic Warfare
ECP	Engineering Change Proposal
EO	Electro-Optical
ERP	Effective Radiated Power
FAT	Factory Acceptance Test
FPR	Final Progress Review
FSR	Field Service Representative
GHz	Gigahertz
GFI	Government Furnished Information
HAT	Harbor Acceptance Trial
HAZMAT	Hazardous Materials
HPoT	Horizontal Pixels on Target
HVU	High Value Unit
IAW	In Accordance With

LRU	Lowest Replaceable Unit
MACA	Months After Contract Award
MOTS	Military-Off-The-Shelf
MTSC	Meggitt Training Systems Canada
MSDS	Material Safety Data Sheets
NEAR-U	Naval Electronic Attack Recapitalization - Unmanned
NOMAD	Naval Offboard anti-Missile Active Decoy
OEM	Original Equipment Manufacturer
PM	Project Manager
PA	Procurement Authority
PPB	Provisioning Parts Breakdown
PRF	Pulse Repetition Frequency
PRI	Pulse Repetition Interval
PRM	Progress Review Meeting
PSR	Project Status Report
PSPC	Public Services and Procurement Canada
PW	Pulse Width
QAR	Quality Assurance Representative
RCN	Royal Canadian Navy
RGS	Range Gate Steal
RGPO	Range Gate Pull Off
RSPL	Recommended Spare Parts List
Rx	Receive
SAT	Sea Acceptance Trial
SOW	Statement of Work
SPTD	Supplementary Provisioning Technical Documentation
TA	Technical Authority
TBD	To Be Determined
TDP	Technical Data Package
TG	Task Group

TRM	Technical Review Meeting
TSOR	Technical Statement of Requirements
Tx	Transmit
USV	Unmanned Surface Vehicles
VGS	Velocity Gate Steal
VGPO	Velocity Gate Pull Off
VPoT	Vertical Pixels on Target
W	Watt

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## 1 INTRODUCTION

### 1.1 OBJECTIVE

- 1.1.1 The objective of this Technical Statement of Requirements (TSOR) is to state the performance and technical requirements for the NOMAD system.

### 1.2 SYSTEM DESCRIPTION

- 1.2.1 A NOMAD system is defined as a set of components designed and integrated into a USV to provide jamming capability against Anti-Ship Missile threats, and as well as, radar testing and training capacity. For the purpose of this TSOR, the components of the NOMAD system are categorized into the following groups:

- 1.2.1.1 The mast and mast-mounted components: The mast and the components of the NOMAD system that are mounted on the mast of the USV.

- 1.2.1.2 USV-inboard components: The components of the NOMAD system that are mounted inside the USV.

- 1.2.1.3 The NOMAD controller: A wireless controller hosted onboard the Controlling Platform that remotely controls the NOMAD payload mounted on the USV.

- 1.2.2 The purpose of the NOMAD system is two-fold: 1) Anti-Ship Missile Defence (ASMD) in a self-protection and Task Group (TG) setting and 2) Radar testing and Training. The NOMAD system will be integrated in existing RCN USV. The USV, with its mounted NOMAD payload, will be launched, recovered, and remotely controlled from the Controlling Platform. The NOMAD payload will be controlled by the NOMAD controller, independent of the USV itself. Line-of-Sight control of both the USV and the NOMAD payload will be maintained with the Controlling Platform.

- 1.2.3 The USV platform is an existing RCN USV, with pre-defined mounting points and spaces allocated for the integration of the NOMAD system. The details of the pre-defined mounting points and allocated spaces are provided in "*Humpback USV-T Hardpoints Drawings*".

- 1.2.4 When the USV is stowed on board the Controlling Platform, the mast and the mast-mounted components will be stored in containers to allow for storage of USVs in their current stacked configuration. The USV-inboard components will remain inside the USV. Before launching operations, the mast and the mast-mounted components of the NOMAD system will be mounted on the USV, on board the Controlling Platform. Conversely, the USV with its NOMAD payload will be recovered from the sea by the Controlling Platform. Once on board, the mast and mast-mounted components of the NOMAD system will be removed from the USV and prepared for storage.

## 2 SYSTEM REQUIREMENTS

### 2.1 GENERAL CAPABILITIES

- 2.1.1 The jammer module of the NOMAD system must be Military-Off-the-Shelf (MOTS) equipment. The jammer module generates RF jamming signals and provides the EW techniques. It includes, but not limited to, Digital Radio Frequency Memory (DRFM) and up/down converters.
- 2.1.2 The jammer module of the NOMAD system must be or must have been operational on at least one mobile platform supporting military operations<sup>1</sup>.
- 2.1.3 The NOMAD system must be designed such that the users can program the system with the appropriate jamming response, based on the provided documentation on the theory of operation of the system.
- 2.1.4 The NOMAD system must be mechanically integratable to the existing RCN USV, with pre-defined mounting points and allocated spaces as provided in “*Humpback USV-T Hardpoints Drawings*”.
- 2.1.5 The NOMAD system must be electrically integratable to the existing RCN USV in accordance with “*Humpback USV-T Payload Integration Interface Control*”.
- 2.1.6 The NOMAD system must be modular such that it can be mounted on the USV, utilizing the mast assembly and the allocated spaces inside the USV. The locations of the mounting points and available spaces inside the USV are provided in “*Humpback USV-T Hardpoints Drawings*”.
- 2.1.7 The mast and mast-mounted components of the NOMAD system must be able to be manually mounted onto the USV or removed from the USV by a maximum of two (2) trained personnel and within 1 hour.
- 2.1.8 The mast and mast-mounted components of the NOMAD system must be able to be stored onboard and transported securely in waterproof, stackable, impact-resistant, and durable containers. Each container together with its contents must be less than 1500 mm (L) x 750 mm (W) x 500 mm (D) in dimensions and weight no more than 40 kg.
- 2.1.9 The NOMAD system must be able to provide minimum transmit Effective Radiated Power (ERP) throughout the required azimuthal and elevation coverage while the USV is maneuvering. The required azimuthal coverage is 360 degrees. The required elevation coverage is  $\pm 15$  degrees about the horizon.
- 2.1.10 The NOMAD system must include modular real-time, trainable, and stabilized video surveillance capability.

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<sup>1</sup> Military operation is an activity or a series of activities related to the carrying out of a strategic, operational, tactical, service, training, or administrative military mission.

- 2.1.10.1 The video surveillance capability must include, at a minimum, a daylight Electro-Optical (EO) camera.
- 2.1.10.2 The video surveillance capability must have a variable continuous zoom.
- 2.1.10.3 The video surveillance capability must provide the DRI (Detection Recognition Identification) level for Detection of at least 4 VPoT (Vertical Pixels on Target) and 7 HPoT (Horizontal Pixels on Target) for the target of dimensions 1m x 1.75m, at a range of 2000m, in day condition.
- 2.1.10.4 The video surveillance capability must provide the DRI level for Recognition of at least 16 VPoT and 28 HPoT for the target of dimensions of 1m x 1.75m, at a range of 1500m, in day condition.

## **2.2 NOMAD REQUIREMENTS**

- 2.2.1 The NOMAD system must have built-in test capability to verify the health status of the NOMAD system and confirm the integrity of the RF transmit and receive operations before launch.
- 2.2.2 The NOMAD system must be capable of recording information about the performance of the NOMAD system. The information to be recorded include, but not limited to, on/off times, EW techniques used, operating frequency, and designated threat information such as ID and frequency.
- 2.2.3 The NOMAD system must be capable of operating continuously in stand-by mode for no less than 12 hours at a time. Stand-by mode is a mode in which the NOMAD system is powered on and is ready for Radio Frequency (RF) Tx/Rx operations.

2.2.4 The NOMAD system must be designed for and capable of achieving the following physical requirements specified in Table 1 – NOMAD System Physical Requirements.

No.	Characteristics	Requirement	Notes
1	Antenna Height	1.5 m or higher	Height of antenna above the gunnel of the USV.
2	Total Weight of the NOMAD system.	< 125 kg	Total weight of the mass, mass-mounted components, and USV-inboard components.  The requirement of Total Weight (2.2.4 Line No. 2) has to be satisfied prior to considering the requirements of Weight of the mast and mast-mounted components (2.2.4 Line No. 3) and Weight of USV-inboard components (2.2.4 Line No. 4).
3	Weight of the mast and mast-mounted components	< 55 kg	Total weight of the mast and all mass-mounted components.
4	Weight of USV-inboard components	< 75 kg	Total weight of all USV-inboard components, including cables and components' mounts.
5	Power Input	< 1000 W	Total power input requirement for all components.  (As the largest power drain is the high powered amplifier, the system should be able to operate at lower levels for the majority of the time when the NOMAD system is in standby mode.)

**Table 1 – NOMAD System Physical Requirements**

2.2.5 The NOMAD system must provide DRFM-based jamming capability and be capable of achieving the following performance requirements specified in Table 2 – NOMAD System Performance Requirements.

No.	Characteristics	Requirement	Notes
1	Tunable Frequency	8 – 17 GHz	
2	Effective Radiated Power (ERP)	> 30 dBW	At either a horizontally or vertically polarized target.  100 % duty cycle.
3	Antenna Isolation	Yes	Must be sufficient to prevent feedback (Ring-Around).
4	Antenna Stabilization	Yes	Must be sufficient to accommodate $\pm 15$ degrees roll about the horizon at rate up to 50 deg/sec while maintaining ERP at the horizon.
5	Simultaneous TX/RX	Not Required	
6	Instantaneous Bandwidth	$\geq 1$ GHz	
7	Receiver Dynamic Range	> 60 dB	
8	Receiver Sensitivity	< -90 dBW	The point of Receiver Sensitivity is at the face of the receive antenna.
9	Transmit Spurious Signal Level	< -40 dBC	
10	Pulse Repetition Frequency (PRF) Range	200 Hz to 20 KHz	
11	Pulse Width	25 ns to CW	
12	Range Offset	-70 $\mu$ s to +70 $\mu$ s	
13	Range Offset Resolution	< 10 ns	
14	Doppler Range	$\pm 25$ MHz	Frequency Chirp Range.
15	Doppler Resolution	< 30 Hz	
16	Number of Primary Independent Targets	$\geq 4$	False target generation.
17	Number of Secondary targets per Primary	$\geq 32$	
18	Minimum Throughput Delay	< 400 ns	

**Table 2 – NOMAD System Performance Requirements**

2.2.6 The NOMAD system must be designed for and capable of providing the following programmable and callable EW techniques as specified in Table 3 – EW Techniques Requirements.

<b>No.</b>	<b>EW Techniques</b>	<b>Requirement</b>	<b>Notes</b>
1	Jamming Mode	- Both coherent and non-coherent mode	- Coherent Jamming mode is the mode in which the NOMAD system generates and transmits coherent jamming signals by manipulating the amplitude and/or phase of the received signal.
2	Wideband Noise (with programmable bandwidth)	- EW techniques Requirement - Noise BW programmable from 1 MHz to at least 500 MHz, in 1MHz step	- Tuneable frequency is from 8 GHz to 17 GHz.
3	Noise Cover Pulse	- EW techniques Requirement	
4	Range Gate Steal (RGS)	- EW techniques Requirement	
5	Target Generation	- EW techniques Requirement	- Multiple repeat of partial or whole captured pulse with amplitude modulation.
6	Frequency Shift	- EW techniques Requirement	
7	Multiple False Targets	- EW techniques Requirement	- Asynchronous and synchronous.

**Table 3 – EW Techniques Requirements**

### 2.3 INTERFACE REQUIREMENTS

- 2.3.1 The NOMAD system must have an external wireless interface and a shipboard controller that are capable of two-way wireless transmission of control signals and data over a minimum distance of 2000 meters.
- 2.3.2 The NOMAD system must be capable of operating and conducting all assigned tasks simultaneously with another operating NOMAD system that is controlled from the same Controlling Platform.
- 2.3.3 The bearing information on the jamming designation that the Controlling Platform provides to the NOMAD system will be true bearing. Other information that can be provided to the NOMAD system includes Threat ID, Threat Frequency, and Technique Number.
- 2.3.4 The NOMAD system must be able to radiate the jamming signal in the desired direction in less than three (3) seconds after receiving the command and designation information from the Controlling Platform.

### 2.4 ENVIRONMENTAL REQUIREMENTS

- 2.4.1 The NOMAD system must be capable of operating and conducting all assigned tasks in the shipboard Electromagnetic Interference (EMI) environment, without interfering with the existing shipboard systems on the Controlling Platform.
- 2.4.2 The NOMAD system must be capable of operating and conducting all assigned tasks under the operating environment described in Table 4 – Operating Environment.

<b>Operating Environment</b>				
<b>No.</b>	<b>Environmental Characteristics</b>	<b>Max</b>	<b>Min</b>	<b>Recommended Test Method</b>
1	Free Air Temperature	+37C	-20C	Mil-Std 810
2	Relative Humidity	95%	0%	Mil-Std 810
3	Rain	0.8 mm per minute		
4	Drip	IAW Procedure III, Method 506.5 of Mil-Std 810		Mil-Std 810
5	Maximum Platform Accelerations	17 g		
6	Sea State	3	0	See Appendix 1 for the definition of sea state in terms of wave height and wind conditions.

**Table 4 – Operating Environment**

2.4.3 The NOMAD system must be operable without degradation after being exposed to the surviving environment described in Table 5 – Surviving Environment.

<i>Surviving Environment</i>				
<i>No.</i>	<i>Environmental Characteristics</i>	<i>Max</i>	<i>Min</i>	<i>Recommended Test Method</i>
1	Free Air Temperature	48C	-20C	Mil-Std 810
2	Relative Humidity	100%	0%	Mil-Std 810
3	Salt Fog	IAW Method 509.5 of Mil-Std 810		Mil-Std 810
4	Sea State	4	0	See Appendix 1 for the definition of sea state in terms of wave height and wind conditions.

**Table 5 – Surviving Environment**

## **2.5 INFORMATION SECURITY REQUIREMENTS**

2.5.1 The NOMAD system must have services to protect sensitive information. Services or functions such as data encryption, self-destruct, or self-wiping function may be employed.

**APPENDIX 1 – DEFINITION OF SEA STATE**

Sea State	Significant Wave Height (m)	Modal Wave Period (sec)			
		Open Ocean		Littoral	
		T <sub>5%</sub>	T <sub>95%</sub>	T <sub>5%</sub>	T <sub>95%</sub>
3	1.25	6.3	14.8	5.1	11.8
4	2.5	6.9	15.2	6.5	12.7
5	4	8.3	15.5	8.2	13.6
6	6	10.3	16.2	9.3	13.6
7	9	13.1	18.5	11	17.1
8	14	16.4	18.6	--	--
9	17.7	20	25.7	--	--

The Bretschneider spectrum shall be used for Open Ocean seaways. The JONSWAP spectrum (gamma=2) shall be used for Littoral seaways.

Steady mean ambient wind speed, acting concurrently with the waves, shall be taken as:  $1.823H_s + 3.45$  (m/sec) at 19.5 m elevation, where  $H_s$  is the significant wave height.

**Table 6 – Definition of Sea State**