

Sea Tel 6012-36 VSAT Antenna System Installation Manual



EAR Controlled - ECCN EAR99

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Sea Tel is an ISO 9001:2008 registered company. Certificate Number 13690 originally issued on March 14, 2011 and renewed / reissued on March 10, 2014.

R&TTE CE

The Series 12 Maritime Satellite Earth Station complies with the requirements of directive 1999/5/EC of the European Parliament and of the Council of 9 March 1999 on Radio equipment and Telecommunication Terminal Equipment. A copy of the R&TTE Declaration of Conformity for this equipment is contained in this manual.



The Sea Tel Series 12 antennas will meet the off-axis EIRP spectral density envelope set forth in FCC 47 C.F.R. § 25.222(a)(1)(i) when the input power density limitations, listed in our FCC Declaration, are met..

These antenna systems also contain FCC compliant supervisory software to continuously monitor the pedestal pointing accuracy and use it to control the "Transmit Mute" function of the satellite modem to satisfy the provisions of FCC 47 C.F.R. § 25.222(a)(1)(iii).

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Revision History

REV	ECO#	Date	Description	By
A		August 11, 2016	Production Release	MDN

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R&TTE Declaration of Conformity

Sea Tel Inc. declares under our sole responsibility that the products identified below are in compliance with the requirements of:

DIRECTIVE 1999/5/EC of the European Parliament and of the Council of 9 March 1999 on Radio equipment and Telecommunication Terminal Equipment and the mutual recognition of their conformity.

Product Names: **3612 Ku Band 8/16 Watt Tx/Rx Maritime Satellite Earth Station**
 4009 MK3 Ku Band 16 Watt Tx/Rx Maritime Satellite Earth Station
 5012 Ku Band 8/16 Watt Tx/Rx Maritime Satellite Earth Station
 6012 Ku Band 8/16 Watt Tx/Rx Maritime Satellite Earth Station

These products have been assessed to Conformity Procedures, Annex IV, of the above Directive by application of the following standards:

EMC:

EMC standard for Radio Equipment (Maritime)
EMC standard for Radio Equipment (Common)
EMC standard for Radio Equipment (General)
Marine Navigational and Radio Communication
Equipment and Systems – General Requirements:

ETSI EN 301 843-1 V1.4.1 (2004-06)

ETSI EN 301 489-1 V1.4.1 (2002-08)

ETSI EN 300 339 (1998-03)

IEC EN 60945:2002

Satellite Earth Stations and System (SES):

Harmonized EN for Very Small Aperture
Terminals (VSAT):
Harmonized EN for satellite Earth Stations
on board Vessels (ESVs)

ETSI EN 301 428-1 V1.3.1 (2006-02)

ETSI EN 302 340 V1.1.1 (2006-04)

Safety:

Safety of Information Technology Equipment:

IEC EN 60950-1:2001 (1st Edition)

Certificates of Assessment were completed and are on file at NEMKO USA Inc, San Diego, CA and BACL Labs, Santa Clara, CA.



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Date: 03-04-2013



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FCC Declaration of Conformity

1. Sea Tel, Inc. designs, develops, manufactures and services marine stabilized antenna systems for satellite communication at sea. These products are in turn used by our customers as part of their Ku-band Earth Station on Vessels (ESV) networks.
2. FCC regulation 47 C.F.R. § 25.222 defines the provisions for blanket licensing of ESV antennas operating in the Ku Band. This declaration covers the requirements for meeting § 25.222 (a)(1) by the demonstrations outlined in paragraphs (b)(1)(i) and (b)(1)(iii). The requirements for meeting § 25.222 (a)(3)-(a)(7) are left to the applicant. The paragraph numbers in this declaration refer to the 2009 version of FCC 47 C.F.R. § 25.222.
3. Sea Tel hereby declares that the antennas listed below will meet the off-axis EIRP spectral density requirements of § 25.222 (a)(1)(i) with an N value of 1, when the following Input Power spectral density limitations are met:

*0.6 Meter Ku Band, Models 2406 and USAT-24 are limited to	-21.6 dBW/4kHz
*0.75 Meter Ku Band, Models 3011 and USAT-30 are limited to	-21.6 dBW/4kHz
0.9 Meter Ku Band, Model 3612 is limited to	-20.3 dBW/4kHz
1.0 Meter Ku Band, Models 4003/4006/4009/4010 are limited to	-16.3 dBW/4kHz
1.0 Meter Ku Band Model 4012 is limited to	-16.6 dBW/4kHz
1.2 Meter Ku Band, Models 4996/5009/5010/5012 are limited to	-14.0 dBW/4kHz
1.5 Meter Ku Band, Models 6006/6009/6012 are limited to	-14.0 dBW/4kHz
2.4 Meter Ku Band, Models 9797/9711/ 9711IMA are limited to	-14.0 dBW/4kHz
4. Sea Tel hereby declares that the antennas referenced in paragraph 3 above, will maintain a stabilization pointing accuracy of better than 0.2 degrees under specified ship motion conditions, thus meeting the requirements of § 25.222 (a)(1)(ii)(A). Those antennas marked with * will maintain a stabilization pointing accuracy of better than 0.3 degrees. The Input Power spectral density limits for these antenna have been adjusted to meet the requirements of § 25.222 (a)(1)(ii)(B).
5. Sea Tel hereby declares that the antennas referenced in paragraph 3 above, will automatically cease transmission within 100 milliseconds if the pointing error should exceed 0.5 degrees and will not resume transmission until the error drops below 0.2 degrees, thus meeting the requirements of § 25.222 (a)(1)(iii).
6. Sea Tel maintains all relevant test data, which is available upon request, to verify these declarations.

Peter Blaney, Chief Engineer
Sea Tel, Inc
Concord, CA

1. SERIES 12 KU-BAND SYSTEM CONFIGURATION(S).....	1-1
1.1. SERIES 12 BASIC SYSTEM INFORMATION	1-1
1.2. SYSTEM CABLES	1-1
1.3. OTHER INPUTS TO THE SYSTEM.....	1-1
1.4. SIMPLIFIED BLOCK DIAGRAM OF A SERIES 09MK3 OR 12 KU-BAND SYSTEM	1-1
1.5. DUAL ANTENNA CONFIGURATION.....	1-2
1.6. AUTOMATIC BEAM SWITCHING (ABS).....	1-3
1.7. OPENAMIP™, ROAM OR VACP	1-3
1.8. FCC COMPLIANCE.....	1-3
2. SITE SURVEY.....	2-1
2.1. SITE SELECTION ABOARD THE SHIP	2-1
2.2. ANTENNA SHADOWING (BLOCKAGE) AND RF INTERFERENCE.....	2-1
2.3. MOUNTING FOUNDATION.....	2-2
2.3.1. Mounting on Deck or Deckhouse.....	2-2
2.3.2. ADE Mounting Considerations	2-2
2.3.3. Sizing of the support pedestal.....	2-2
2.4. MOUNTING HEIGHT	2-3
2.5. MAST CONFIGURATIONS	2-3
2.5.1. Vertical Masts	2-3
2.5.2. Raked Masts.....	2-4
2.5.3. Girder Masts	2-4
2.5.4. Truss Mast	2-4
2.6. SAFE ACCESS TO THE ADE.....	2-5
2.7. BELOW DECKS EQUIPMENT LOCATION	2-5
2.8. CABLES.....	2-5
2.8.1. ADE/BDE Coaxial Cables.....	2-5
2.8.2. Antenna Power Cable	2-6
2.8.3. Air Conditioner Power Cable	2-6
2.8.4. ACU Power Cable/Outlet.....	2-6
2.8.5. Gyro Compass Cable.....	2-6
2.9. GROUNDING.....	2-6
3. INSTALLATION.....	3-1
3.1. UNPACKING AND INSPECTION	3-1
3.2. ASSEMBLY NOTES AND WARNINGS	3-1
3.3. INSTALLING THE ADE.....	3-2
3.3.1. Prepare the 76" Radome Assembly.....	3-2
3.3.2. Install 76" Radome to mounting deck.....	3-3
3.4. GROUNDING THE PEDESTAL.....	3-3
3.5. REMOVING THE SHIPPING/STOW RESTRAINTS PRIOR TO POWER-UP	3-4
3.5.1. Removing the AZ Shipping/Stow Restraint	3-4
3.5.2. Removing the EL Shipping/Stow Restraint	3-5
3.5.3. Removing the CL Shipping/Stow Restraint	3-7
3.6. CONNECTING THE ABOVE DECKS EQUIPMENT	3-8
3.6.1. Pedestal Coax Cables	3-8
3.6.2. Pedestal Power Cable	3-8
3.7. INSTALLING THE BELOW DECKS EQUIPMENT.....	3-8
3.7.1. General Cautions & Warnings	3-8
3.8. CONNECTING THE BELOW DECKS EQUIPMENT.....	3-8
3.8.1. Connecting the BDE AC Power Cables.....	3-8
3.8.2. Connecting the ADE-BDE Coax Cables.....	3-8
3.8.3. Media Xchange Point™ (MXP) Connections	3-9

3.8.4.	Other BDE connections	3-10
3.9.	FINAL CHECKS.....	3-10
3.9.1.	Visual/Electrical inspection.....	3-10
3.9.2.	Electrical - Double check wiring connections.....	3-10
3.10.	SETUP - MEDIA XCHANGE POINT™ (MXP)	3-11
4.	CONFIGURING A COMPUTER FOR THE MXP	4-1
5.	SETUP – SHIP'S GYRO COMPASS	5-1
5.1.	SETTING THE GYRO TYPE.....	5-1
5.2.	IF THERE IS NO SHIPS GYRO COMPASS.....	5-2
6.	SETUP – AZIMUTH TRIM.....	6-1
7.	SETUP – BLOCKAGE & RF RADIATION HAZARD ZONES.....	7-1
7.1.	RADIATION HAZARD AND BLOCKAGE MAPPING.....	7-1
7.2.	PROGRAMMING INSTRUCTIONS:.....	7-2
8.	CONFIGURING THE SATELLITE MODEM INTERFACE.....	8-1
8.1.	SATELLITE MODEM INTERFACE	8-1
8.1.1.	Reflector setting.....	8-1
8.1.2.	Modem Type setting.....	8-2
8.1.3.	Modem I/O setting.....	8-2
8.1.4.	Modem I/O – Custom Settings.....	8-2
8.2.	QUICK REFERENCE: COMMON MODEM LOCK & MUTE SETTINGS.....	8-5
9.	SETUP – TARGETING.....	9-1
9.1.	AUTO TRIM	9-1
9.2.	MANUALLY OPTIMIZING TARGETING.....	9-2
10.	SETUP – SATELLITE CONFIGURATION.....	10-1
10.1.	SEARCHING PATTERNS.....	10-1
10.1.1.	Default “Spiral” (Box) Search Pattern	10-1
10.1.2.	Inclined Orbit Search Pattern	10-1
10.1.3.	Sky Search Pattern	10-2
10.2.	TX POL SELECT.....	10-2
10.3.	BAND SELECT.....	10-2
10.4.	X-POL / Co-POL SELECT.....	10-2
10.5.	SELECTING/CONFIGURING YOUR SATELLITE CONFIGURATION.....	10-2
11.	QUICK START OPERATION.....	11-1
11.1.	IF SATELLITE SIGNAL IS FOUND AND NETWORK LOCK IS ACHIEVED:.....	11-1
11.2.	IF NO SIGNAL IS FOUND:.....	11-1
11.3.	IF SATELLITE SIGNAL IS FOUND BUT NETWORK LOCK IS NOT ACHIEVED:.....	11-2
11.4.	TO TARGET A DIFFERENT SATELLITE.....	11-4
12.	OPTIMIZING CROSS-POL ISOLATION.....	12-1
12.1.	OPTIMIZING CROSS-POL ISOLATION.....	12-1
13.	STOWING THE ANTENNA.....	13-1
13.1.	INSTALLING THE STOW RESTRAINTS.....	13-1
13.1.1.	Installing the AZ Shipping/Stow Restraint	13-1
13.1.2.	Installing the EL Shipping/Stow Restraint.....	13-2
13.1.3.	Installing the CL Shipping/Stow Restraint	13-3
13.2.	REMOVING THE SHIPPING/STOW RESTRAINTS PRIOR TO POWER-UP.....	13-4
13.2.1.	Removing the AZ Shipping/Stow Restraint	13-4
13.2.2.	Removing the EL Shipping/Stow Restraint.....	13-5
13.2.3.	Removing the CL Shipping/Stow Restraint	13-7
14.	6012-36 TECHNICAL SPECIFICATIONS.....	14-1
14.1.	ABOVE DECKS EQUIPMENT	14-1
14.2.	BELOW DECKS EQUIPMENT	14-7

14.3. REGULATORY COMPLIANCE.....	14-10
14.4. CABLES.....	14-11
14.4.1. Antenna L-Band IF Coax Cables (Customer Furnished).....	14-11
14.4.2. Multi-conductor Cables (Customer Furnished)	14-11
14.4.3. AC Power Cable Above Decks (Customer Furnished)	14-11
14.4.4. Gyro Compass Interface Cable (Customer Furnished)	14-12
15. DRAWINGS	15-1
15.1. MODEL SPECIFIC DRAWINGS.....	15-1

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1. Series 12 Ku-Band System Configuration(s)

The Series 12 Ku-Band Stabilized Antenna system is to be used for Transmit/Receive (TX/RX) satellite communications. It is comprised of two major groups of equipment: the Above Decks Equipment (ADE) and the Below Decks Equipment (BDE). There will also be interconnecting cables between the ADE & BDE and cables to provide other inputs to the system.

It is initially equipped for Ku-Band operation; however, an optional Ka-Band upgrade kit is available for when the Ka-Band services are available.

1.1. Series 12 Basic System Information

Series 09 antennas are available in three dish sizes (Diameter – active area):

- 1.0 M (40 inch)
- 1.2 M (50.0 inch)
- 1.5 M (60 inch)

Each dish size is available in multiple configurations:

- Variety of BUC manufacturers and power output capabilities
- Variety of BUC/HPA power output capabilities
- Cross-Pol feed assembly
- Optional Co-Pol diplexer and LNB
- Choice of single fixed frequency, dual-band, tri-band or Quad-Band LNB(s)

The Series 12 antennas are available in multiple tuned radome sizes:

- 131.3 cm (50 inches) Diameter
- 155 cm (60 inch) Diameter
- 1.76 M (66 inch) Diameter
- 201.59cm (76 inch) Diameter
- 205.23cm (81 inch) Diameter **[Air Conditioning available for this radome ONLY]**

1.2. System Cables

AC power and coaxial cables are discussed in other chapters and their specifications are in the specifications chapter.

1.3. Other Inputs to the System

Multi-conductor cables from Ship's Gyro Compass, GPS, phone, fax and computer equipment may be connected in the system.

1.4. Simplified Block Diagram of a Series 09MK3 or 12 Ku-Band System

Your Series 12 Ku-Band TXRX system consists of two major groups of equipment: an above-decks group and a below-decks group. Each group is comprised of, but is not limited to, the items listed below. All equipment comprising the Above Decks is incorporated inside the radome assembly and is integrated into a single operational entity. For inputs, this system requires only an unobstructed line-of-sight view to the satellite, Gyro Compass input and AC electrical power.

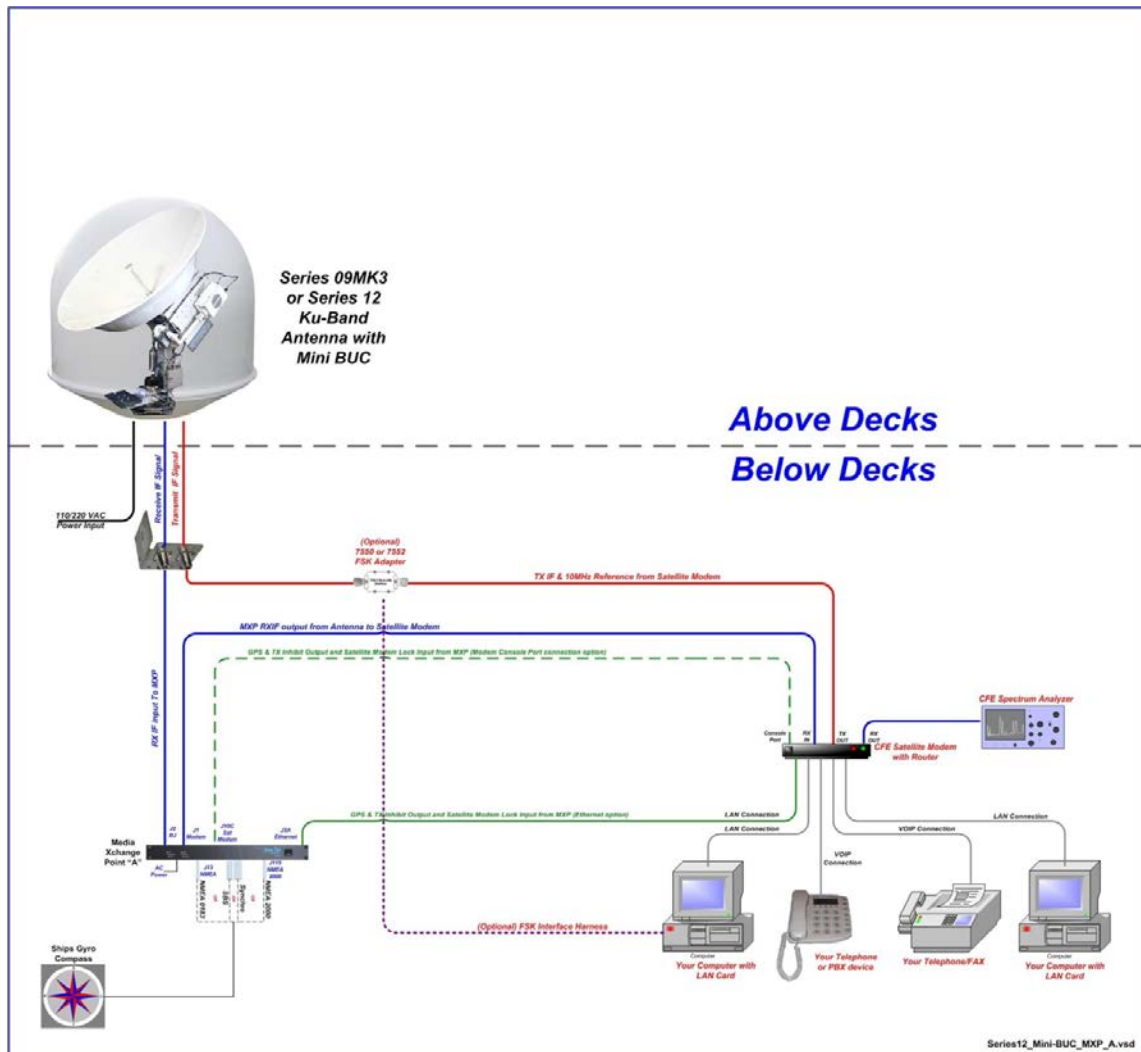
A. Above-Decks Equipment (all shown as the ADE) Group

- Stabilized antenna pedestal
- Antenna Reflector
- Feed Assembly with Cross-Pol and Co-Pol LNBs
- 8W Ku-Band Solid State Block Up-Converter (BUC)
- Radome Assembly

B. Below-Decks Equipment Group

- Media Xchange Point™ (MXP)
- Customer Furnished Equipment - Satellite Modem and other below decks equipment required for the desired communications purposes (including LAN and VOIP equipment).

- Appropriate Coax, Ethernet, and telephone cables

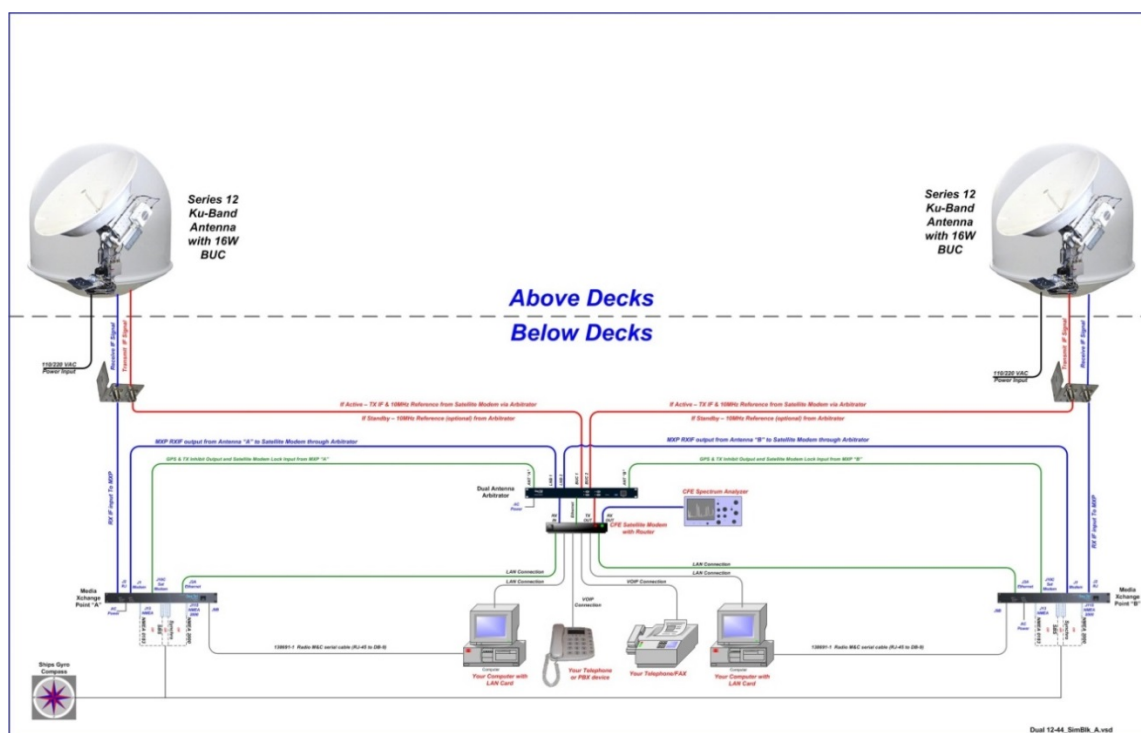


1.5. Dual Antenna Configuration

Due to very large blockage conditions, you may need to install a dual antenna configuration to provide uninterrupted services. Two full antenna systems are installed and the MXP control outputs are connected to an arbitrator switch panel which then is connected to the below decks equipment. The connection scheme is required for MXP "A" to control ONLY Antenna "A" AND MXP "B" to control ONLY Antenna "B".

You will program the blockage zone(s) for each of the two antennas (refer to Setup – Blockage Zones). The blockage output from each MXP is fed to the arbitrator. The blockage output is a transistor "short" to ground when the antenna is within a programmed blockage zone and is an "open" when not blocked.

When one antenna is blocked, its blockage output will command the arbitrator panel to switch services to the modem from that antenna to the other antenna. The arbitrator panel provides a logic latch to prevent excess switching when the ship heading is yawing, therefore, causing if the antenna to be repeat blocked – unblocked – blocked.



1.6. Automatic Beam Switching (ABS)

ABS is a method of communicating remotely via an overhead channel, or locally from the modem, to reconfigure the ACU(s) to use a different beam on the same satellite or to use a different satellite. The modems include commands which allow remotely setting all of the necessary parameters and to command the targeting of the desired satellite.

1.7. OpenAMIP™, ROAM or VACP

These each have standardized language incorporated into their (iDirect, Comtech & STM) modems which communicates automatic beam switching settings from their options file to the Sea Tel ACU(s). This provides the network a means of controlling automatic beam switching by the settings in the options file in the remote modem.

1.8. FCC Compliance

This antenna system, with current software, contain FCC compliant supervisory software to continuously monitor the pedestal pointing error. This supervisory software will trip an error flag, which will automatically cease transmission within 100 milliseconds, if the pointing error should exceed 0.5 degrees. Transmission will not resume until the pointing error drops below 0.2 degrees.

To be compliant with these FCC requirements, the “Transmit Mute” output of the Sea Tel below decks controller must be connected to the “Mute Input” of the satellite modem via serial or via an Ethernet connection to the modem.

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2. Site Survey

There are three objective of the site survey. The first is to find the best place to mount the antenna and the BDE. The second is to identify the length and routing of the cables and any other items or materials that are required to install the system. The third is to identify any other issues that must be resolved before or during the installation.

2.1. Site Selection Aboard The Ship

The radome assembly should be installed at a location aboard ship where:

- The antenna has a clear line-of-sight to view as much of the sky (horizon to zenith at all bearings) as is practical.
- X-Band (3cm) Navigational Radars:
 - The ADE should be mounted more than 0.6 meters/2 feet from 2kW (24 km) radars
 - The ADE should be mounted more than 2 meters/8 feet from 10kW (72 km) radars
 - The ADE should be mounted more than 4 meters/12 feet from 160kW (250km) radars
- S-Band (10cm) Navigational Radars:
 - If the ADE is/has C-Band it should be mounted more than 4 meters/12 feet from the S-band Radar.
- The ADE should not be mounted on the same plane as the ship's radar, so that it is not directly in the radar beam path.
- The ADE should be mounted more than 2.5 meters/8 feet from any high power MF/HF antennas (<400W).
- The ADE should be mounted more than 4 meters/12 feet from any high power MF/HF antennas (1000W).
- The ADE should also be mounted more than 4 meters/12 feet from any short range (VHF/UHF) antennae.
- The ADE should be mounted more than 2.5 meters/8 feet away from any L-band satellite antenna.
- The ADE should be mounted more than 3 meters/10 feet away from any magnetic compass installations.
- The ADE should be mounted more than 2.5 meters/8 feet away from any GPS receiver antennae.
- Another consideration for any satellite antenna mounting is multi-path signals (reflection of the satellite signal off of nearby surfaces arriving out of phase with the direct signal from the satellite) to the antenna. This is particularly a problem for the onboard GPS, and/or the GPS based satellite compass.
- The ADE and the BDE should be positioned as close to one another as possible. This is necessary to reduce the losses associated with long cable runs.
- This mounting platform must also be robust enough to withstand the forces exerted by full rated wind load on the radome.
- The mounting location is robust enough that it will not flex or sway in ships motion and be sufficiently well re-enforced to prevent flex and vibration forces from being exerted on the antenna and radome.
- If the radome is to be mounted on a raised pedestal, it **MUST** have adequate size, wall thickness and gussets to prevent flexing or swaying in ships motion. In simple terms it must be robust.

If these conditions cannot be entirely satisfied, the site selection will inevitably be a "best" compromise between the various considerations.

2.2. Antenna Shadowing (Blockage) and RF Interference

At the transmission frequencies of this satellite antenna system, any substantial structures in the way of the beam path will cause significant degradation of the signal. Care should be taken to locate the ADE so that it has direct line-of-sight with the satellite without any structures in the beam path through the full 360 degree ships turn. Wire rope stays, lifelines, small diameter handrails and other accessories may pass through the beam path in limited numbers; however, even these relatively insignificant shadows can produce measurable signal loss at these frequencies.

2.3. Mounting Foundation

2.3.1. Mounting on Deck or Deckhouse

While mounting the ADE on a mast is a common solution to elevate the ADE far enough above the various obstructions which create signal blockages, sometimes the best mounting position is on a deck or deckhouse top. These installations are inherently stiffer than a mast installation, if for no other reason than the design of the deck/deckhouse structure is prescribed by the ship's classification society. In the deck/deckhouse design rules, the minimum plating and stiffener guidelines are chosen to preclude high local vibration amplitudes.

Most installations onto a deck or deckhouse structure will require a mounting pedestal to raise the ADE above the deck for radome hatch access and to allow the full range of elevation (see ADE mounting considerations above). Some care must be taken to ensure the mounting pedestal is properly aligned with the stiffeners under the deck plating.

2.3.2. ADE Mounting Considerations

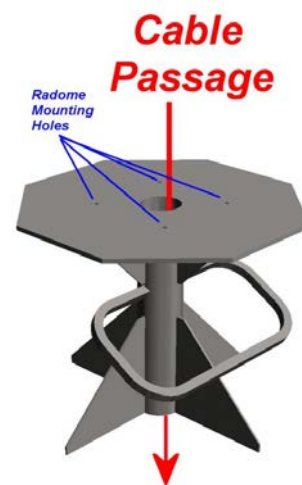
Mounting the radome directly on the deck or platform prevents access to the hatch in the base of the radome unless an opening is designed into the mounting surface.

If there is no access to the hatch, the only way to service the antenna is to remove the radome top. Two people are required to take the top off of the radome without cracking or losing control of it, but even with two people a gust of wind may cause them to lose control and the radome top may be catastrophically damaged (see repair information in the radome specifications).

If access to the hatch cannot be provided in the mounting surface, provide a short ADE support pedestal to mount the ADE on which is tall enough to allow access into the radome via the hatch.

Ladder rungs must be provided on all mounting stanchions greater than 3-4 feet tall to allow footing for personnel safety when entering the hatch of the radome.

The recommended cable passage in the 50, 60 and 66 inch radomes is through the bottom center of the radome base, down through the ADE support pedestal, through the deck and into the interior of the ship.



2.3.3. Sizing of the support pedestal

The following should be taken into account when choosing the height of a mounting support stand:

1. The height of the pedestal should be kept as short as possible, taking into account recommendations given in other Sea Tel Guidelines.
2. The minimum height of the pedestal above a flat deck or platform to allow access into the radome for maintenance should be 0.6 meters (24 inches).
3. The connection of the ADE mounting plate to the stanchion and the connection of the pedestal to the ship should be properly braced with triangular gussets (see graphic above). Care should be taken to align the pedestal gussets to the ship's stiffeners as much as possible. Doublers or other reinforcing plates should be considered to distribute the forces when under-deck stiffeners are inadequate.
4. The diameter of the pedestal stanchion shall not be smaller than 100 millimeters (4 inches). Where the ADE base diameter exceeds 1.5 meters (60 inches), additional stanchions (quantity greater than 3) should be placed rather than a single large stanchion.
5. Shear and bending should be taken into account in sizing the ADE mounting plate and associated gussets.
6. Shear and bending must be taken into account when sizing the pedestal to ship connection.
7. All welding should be full penetration welds –V-groove welds with additional fillet welds – with throats equivalent to the thickness of the thinnest base material.
8. For an ADE mounted greater than 0.6 meters (24 inches) above the ship's structure, at least one (1) foot rung should be added. Additional rungs should be added for every 0.3 meter (12 inches) of pedestal height above the ship's structure.
9. For an ADE mounted greater than 3 meters (9 feet) above the ship's structure, a fully enclosing cage should be included in way of the access ladder, starting 2.3 meters (7 feet) above the ship's

structure.

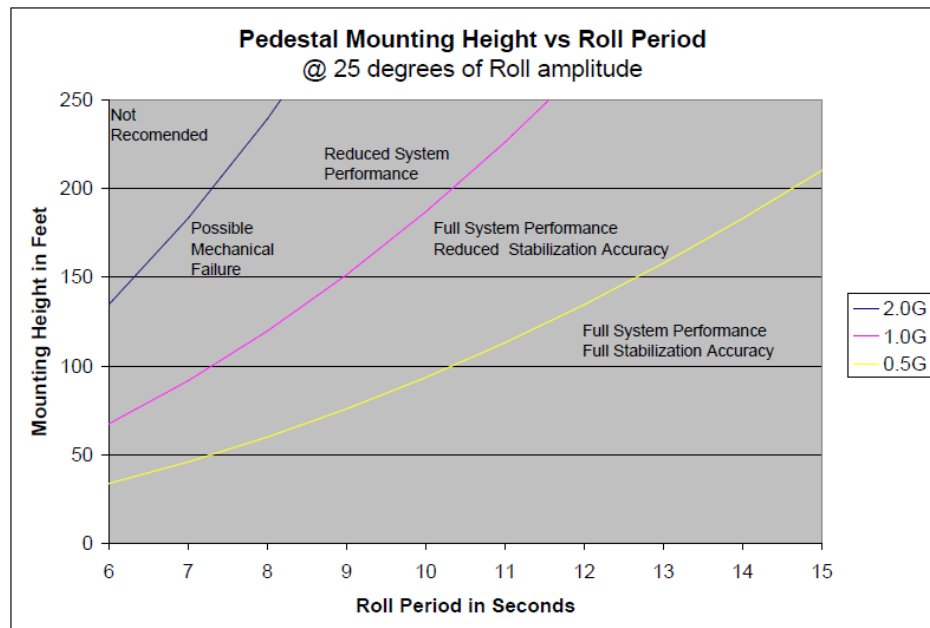
2.4. Mounting Height

The higher up you mount the antenna above the pivot point of the ship the higher the tangential acceleration (g-force) exerted on the antenna will be (see chart below).

When the g-force exerted on the antenna is low, antenna stabilization and overall performance are not affected.

If the g-force exerted on the antenna is high enough ($> 1\text{ G}$), antenna stabilization and overall performance are affected.

If the g-force exerted on the antenna is excessive (1-2 Gs), the antenna does not maintain stabilization and may be physically damaged by the g-force.



2.5. Mast Configurations

Sea Tel recommends mounting the ADE in a location that has both a clear line-of-sight to the target satellites in all potential azimuth/elevation ranges and sufficient support against vibration excitement. If possible, mounting the ADE pedestal directly to ship deckhouse structures or other box stiffened structures is preferred. However, in many cases, this imposes limits on the antenna system's clear line-of-sight.

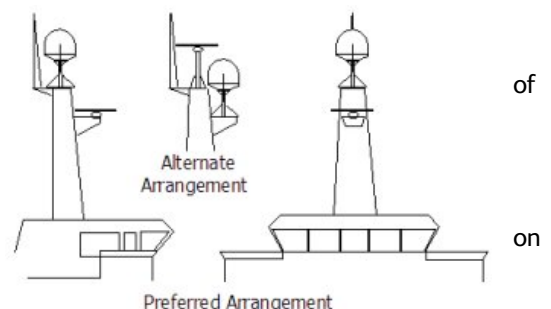
Often the solution for providing the full azimuth/elevation range the antenna needs is to mount the ADE on the ship's mast. Unfortunately, masts do not consider equipment masses in design and often have harmonic frequencies of their own.

There are many designs of masts used on ships – masts are nearly as unique in design as the ship is – but the designs often fall into a few categories. These categories can be addressed in terms of typical responses and problems with regards to vibration and mounting of ADE. The most common categories of masts are:

2.5.1. Vertical Masts

Vertical masts are a very ancient and common mast design. In essence, it is the mast derived from the sailing mast and adapted for mounting the ever-increasing array of antennae which ships need to communicate with the world. This drawing of a vertical mast shows the preferred mounting of the ADE center-line above the plane of the radar. Alternatively the ADE is mounted below the plane the radar signal

Vertical masts are most commonly found on cargo ships – they are simple, inelegant and functional. They are also fairly stiff against torsional reaction and lateral vibrations, as long as the ADE is mounted a stiff pedestal near the vertical centerline of the mast. If centerline mounting is impractical or otherwise prohibited, the mast platform the ADE is



mounted on should be checked for torsional vibration about the centerline of the mast and the orthogonal centerline of the platform.

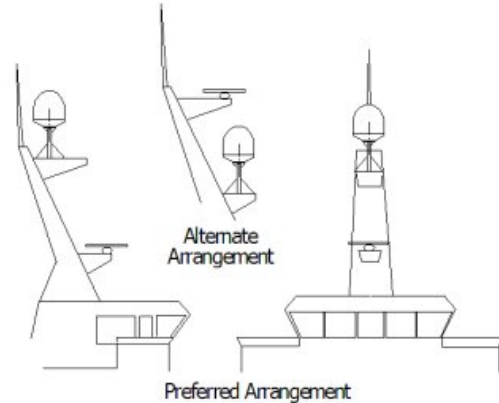
If the estimated natural frequency of the mast or platform is less than 35 Hertz, the mast or platform should be stiffened by the addition of deeper gussets under the platform or behind the mast.

2.5.2. Raked Masts

Raked masts are found on vessels where the style or appearance of the entire vessel is important. Again, the inclined mast is a direct descendant from the masts of sailing ships – as ship owners wanted their vessels to look more unique and less utilitarian, they ‘raked’ the masts aft to make the vessel appear capable of speed. This drawing shows a raked mast, again with the preferred ADE mounting above the radar and alternate with the ADE below the radar.

Raked masts pose special problems in both evaluating the mast for stiffness and mounting of antennae. As can be seen in the drawing, all antennae must be mounted on platforms or other horizontal structures in order to maintain the vertical orientation of the antenna centerline.

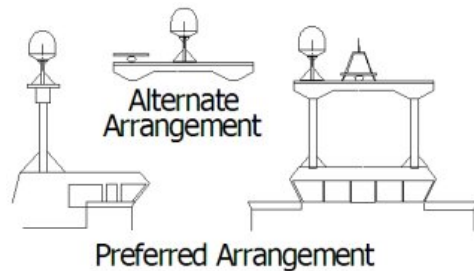
This implies a secondary member which has a different natural frequency than the raked mast’s natural frequency. In order to reduce the mass of these platforms, they tend to be less stiff than the main box structure of the raked mast. Thus, they will have lower natural frequencies than the raked mast itself. Unfortunately, the vibratory forces will act through the stiff structure of the raked mast and excite these lighter platforms, to the detriment of the antenna.



2.5.3. Girder Masts

Girder masts are large platforms atop a pair of columns. Just like girder constructions in buildings, they are relatively stiff athwart ship – in their primary axis but less stiff longitudinally and torsionally. An example of a girder mast is shown in this drawing, with the preferred ADE mounting outboard and above the radar directly on one of the columns and alternate with the ADE centered on the girder above the plane of the radar.

The greatest weakness of girder masts is in torsion – where the girder beam twists about its vertical centerline axis. As with all mast designs discussed so far, mounting the antenna in line with the vertical support structure will reduce the vibration tendencies. Mounting the antenna directly above the girder columns provides ample support to the antenna pedestal and locates the antenna weight where it will influence the natural frequency of the mast the least.

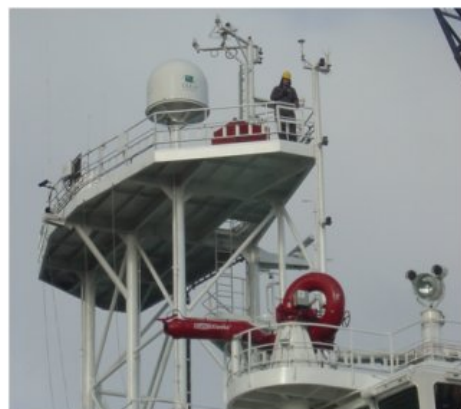


2.5.4. Truss Mast

Truss masts are a variant on the girder mast concept. Rather than a pair of columns supporting a girder beam, the construction is a framework of tubular members supporting a platform on which the antennae and other equipment are mounted. A typical truss mast is shown in this photograph.

Like a girder mast, truss masts are especially stiff in the athwart ship direction. Unlike a girder mast, the truss can be made to be nearly as stiff in the longitudinal direction. Truss masts are particularly difficult to estimate the natural frequency – since a correct modeling includes both the truss structure of the supports and the plate/diaphragm structure of the platform. In general, the following guidelines apply when determining the adequate support for mounting an antenna on a truss mast:

1. Antenna ADE pedestal gussets should align with platform stiffeners which are at least 200 millimeters in depth and 10 millimeters in thickness.



2. When possible, the antenna ADE pedestal column should align with a vertical truss support.
3. For every 100 kilograms of ADE weight over 250 kilograms, the depth of the platform stiffeners should be increased by 50 millimeters and thickness by 2 millimeters.

Sea Tel does not have a recommended arrangement for a truss mast – the variability of truss mast designs means that each installation needs to be evaluated separately.

2.6. Safe Access to the ADE

Safe access to the ADE should be provided. Provisions of the ship's Safety Management System with regard to men aloft should be reviewed and agreed with all personnel prior to the installation. Installations greater than 3 meters above the deck (or where the access starts at a deck less than 1 meter in width) without cages around the access ladder shall be provided with means to latch a safety harness to a fixed horizontal bar or ring.

The access hatch for the ADE shall be oriented aft, or inboard, when practical. In any case, the orientation of the ADE access hatch shall comply with the SMS guidelines onboard the ship. Nets and other safety rigging under the ADE during servicing should be rigged to catch falling tools, components or fasteners.

2.7. Below Decks Equipment Location

The Antenna Control Unit, Terminal Mounting Strip and Base Modem Panel are all standard 19" rack mount, therefore, preferred installation of these items is in such a rack. The ACU mounts from the front of the rack. The Terminal Mounting Strip and Base Modem Panel mount on the rear of the rack.

The Satellite Modem, router, VIOP adapter(s), telephone equipment, fax machine, computers and any other associated equipment should be properly mounted for shipboard use.

Plans to allow access to the rear of the ACU should be considered.

2.8. Cables

During the site survey, walk the path where the cables will be installed. Pay particular attention to how cables will be installed; such as what obstacles they will be routed around, difficulties that will be encountered and the overall length of the cables. The ADE should be installed using good electrical practice. Sea Tel recommends referring to IEC 60092-352 for specific guidance in choosing cables and installing cables onboard a ship. Within these guidelines, Sea Tel will provide some very general information regarding the electrical installation.

In general, all cable shall be protected from chaffing and secured to a cableway. Cable runs on open deck or down a mast shall be in metal conduit suitable for marine use. The conduit shall be blown through with dry air prior to passing cable to ensure all debris has been cleared out of the conduit and again after passing the cable to ensure no trapped moisture exists. The ends of the conduit shall be sealed with cable glands (preferred), mastic or low VOC silicon sealant after the cables have been passed through.

Cables passing through bulkheads or decks shall be routed through approved weather tight glands.

2.8.1. ADE/BDE Coaxial Cables

The first concern with the coaxial cables installed between the ADE & BDE is length. This length is used to determine the loss of the various possible coax, Heliac or fiber-optic cables that might be used. You should always provide the lowest loss cables to provide the strongest signal level into the satellite modem.

Be sure that the shield(s) of the coaxes are not in contact with the ships ground.

The coaxes must be of adequate conductor cross-sectional surface area for the length of the cable run and that the loop resistance of the cable run is less than 2.0 ohms. Copper clad iron center conductor cables should never be used.

Signal cable shall be continuous from the connection within the ADE radome, through the structure of the ship to the BDE. Splices, adapters or dummy connections will degrade the signal level and are discouraged.

Be careful of sharp bends that kink and damage the cable. Use a proper tubing bender for Heliac bends. Penetrations in watertight bulkheads are very expensive, single cable, welded penetrations that must be pressure tested.

Always use good quality connectors that are designed to fit properly on the cables you are using. Poor quality connectors have higher loss, can allow noise into the cable, are easily damaged or fail prematurely.

In as much as is possible, don't lay the coaxes on power cables. Don't lay the coaxes on, or directly beside, the cables from a second Sea Tel antenna, Inmarsat antenna and/or GPS antenna that are also passing L-band frequencies. Don't lay the coaxes on, or directly beside, radar cables that may inject pulse repetition noise –as error bits - into your cables.

2.8.2. Antenna Power Cable

Be cautious of length of the run, for voltage loss issues, and assure that the gauge of the wires is adequate for the current that is expected to be drawn (plus margin). Antenna power is recommended (but not required) to be from a UPS, generally the same one that supplies power to the below decks equipment.

Power cables shall comply with the provisions of IEC 60092-350 and -351 as practical. Power cables may be routed through the same conduit as the signal cable from the junction box to the base of the ADE. Power cables shall pass through separate radome penetrations from the signal cable.

The power cable shall be continuous from the UPS (or closest circuit breaker) to the ADE connections within the radome. The power circuits shall be arranged so that 'active,' 'common' and 'neutral' (ground) legs are all made or broken simultaneously. All circuit legs shall be carried in the same cable jacket.

2.8.3. Air Conditioner Power Cable

If your system includes a marine air conditioner (available with the 81 inch radome ONLY), run an AC power cable to it from a breaker, preferably from a different phase of the electrical system than supplies power to the ADE & BDE. Be EXTREMELY cautious of length of the run for voltage loss and gauge of the wires for the current that is expected to be drawn.

Power cable shall comply with the provisions of IEC 60092-350 and -351 in so far as practical. Power cables may be routed through the same conduit as the signal cable from the junction box to the base of the ADE. Power cables shall pass through separate radome penetrations from the signal cable.

The power cable shall be continuous from the closest circuit breaker to the ADE connections within the radome. The power circuits shall be arranged so that 'active,' 'common' and 'neutral' (ground) legs are all made or broken simultaneously. All circuit legs shall be carried in the same cable jacket.

2.8.4. ACU Power Cable/Outlet

The AC power for the ACU and the ADE is not required to be from a UPS (same one that supplies power to the ADE), but it is recommended.

Power cable shall comply with the provisions of IEC 60092-350 and -351 in so far as practicable.

2.8.5. Gyro Compass Cable

Use good quality shielded cables (twisted pairs, individually foil wrapped, outer foil with braid overall is best). You only need 2-wire for NMEA signal, 4-wire for Step-By-Step and 5-wire for Synchro ... always use shielded cable. Be cautious of length and gauge of the run for voltage loss issues.

2.9. Grounding

All metal parts of the ADE shall be grounded to bare metal that is common to the hull of the ship. This is most commonly accomplished by attaching a ground wire/cable from the upper base plate ground point to a ground stud on the mounting pedestal/stanchion/mast near the base of the radome. Preservation of the bare metal contact point should be done to prevent loss of ground due to rust and/or corrosion.

Grounding by exposing bare metal under all mounting bolts of the under-side of the radome base prior to final tightening does NOT provide adequate grounding of the ADE.

Grounding should be ensured throughout the entire mounting to the hull. While it is presumed the deckhouse is permanently bonded and grounded to the hull, in cases where the deckhouse and hull are of different materials a check of an independent ground bonding strap should be made. Masts should be confirmed to be grounded to the deckhouse or hull.

3. Installation

Your antenna pedestal comes completely assembled in its radome. This section contains instructions for unpacking, final assembling and installing of the equipment. It is highly recommended that trained technicians install the system.


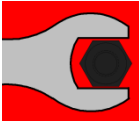
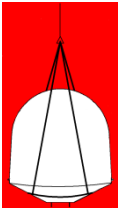
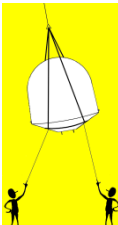
The installation instructions for your system are below.

3.1. Unpacking and Inspection

Exercise caution when unpacking the equipment.

1. Unpack the crates. Carefully inspect the radome surface for evidence of shipping damage.
2. Unpack all the boxes.
3. Inspect everything to assure that all materials have been received and are in good condition.

3.2. Assembly Notes and Warnings

	<p>NOTE: All nuts and bolts should be assembled using the appropriate Loctite thread-locker product number for the thread size of the hardware.</p> <table><tr><th>Loctite #</th><th>Description</th></tr><tr><td>222</td><td>Low strength for small fasteners.</td></tr><tr><td>242</td><td>Medium strength</td></tr><tr><td>638</td><td>High strength for motor shafts & sprockets.</td></tr><tr><td>2760</td><td>Permanent strength for up to 1" diameter fasteners.</td></tr><tr><td>290</td><td>Wicking, High strength for fasteners which are already assembled.</td></tr></table>	Loctite #	Description	222	Low strength for small fasteners.	242	Medium strength	638	High strength for motor shafts & sprockets.	2760	Permanent strength for up to 1" diameter fasteners.	290	Wicking, High strength for fasteners which are already assembled.								
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	<p>WARNING: Assure that all nut and bolt assemblies are tightened according to the tightening torque values listed below:</p> <table><tr><th>SAE Bolt Size</th><th>Inch Pounds</th><th>Metric Bolt Size</th><th>Kg-cm</th></tr><tr><td>1/4-20</td><td>75</td><td>M6</td><td>75.3</td></tr><tr><td>5/16-18</td><td>132</td><td>M8</td><td>150</td></tr><tr><td>3/8-16</td><td>236</td><td>M10</td><td>270</td></tr><tr><td>1/2-13</td><td>517</td><td>M12</td><td>430</td></tr></table>	SAE Bolt Size	Inch Pounds	Metric Bolt Size	Kg-cm	1/4-20	75	M6	75.3	5/16-18	132	M8	150	3/8-16	236	M10	270	1/2-13	517	M12	430
SAE Bolt Size	Inch Pounds	Metric Bolt Size	Kg-cm																		
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3/8-16	236	M10	270																		
1/2-13	517	M12	430																		
	<p>WARNING: Hoisting with other than a webbed four-part sling may result in catastrophic crushing of the radome. Refer to the specifications and drawings for the fully assembled weight of your model antenna/radome and assure that equipment used to lift/hoist this system is rated accordingly.</p>																				
	<p>CAUTION: The antenna/radome assembly is very light for its size and is subject to large swaying motions if hoisted under windy conditions. Always ensure that tag lines, attached to the radome base frame, are attended while hoisting the antenna assembly to its assigned location aboard ship.</p>																				

3.3. Installing the ADE

The antenna pedestal is shipped completely assembled in its radome. Please refer to the entire Site Survey chapter of this manual.

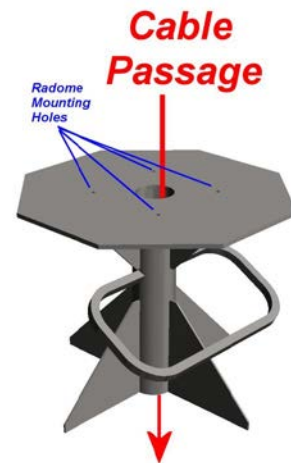
Base Hatch Access - Mounting the radome directly on the deck or platform prevents access to the hatch in the base of the radome unless an opening is designed into the mounting surface to allow such entry. If there is no access to the hatch the only way to service the antenna is to remove the radome top. Two people are required to take the top off of the radome without cracking or losing control of it, but even with two people a gust of wind may cause them to lose control and the radome top may be catastrophically damaged (see repair information in the radome specifications) or lost.

If access to the hatch cannot be provided in the mounting surface, provide a short ADE mounting stanchion to mount the ADE on which is tall enough to allow access into the radome via the hatch.

Ladder rungs must be provided on all mounting stanchions greater than 3-4 feet tall to allow footing for personnel safety when entering the hatch of the radome.

Cable Passage - The radome base is designed with a bottom center cable passage and Roxtec® Multidiameter® blocks for cable strain relief. The recommended cable passage in the 50, 60, 61 and 66 inch radomes is through the bottom center of the radome base, down through the ADE mounting stanchion, through the deck and into the interior of the ship.

Bottom center cable passage is recommended, however, a strain relief kit is provided with the system if off-center cable entry is required. **Note: Strain relief installation procedure, provided in the Drawings chapter, MUST be followed to assure that the cored holes are properly sealed to prevent moisture absorption and de-lamination of the radome base.**

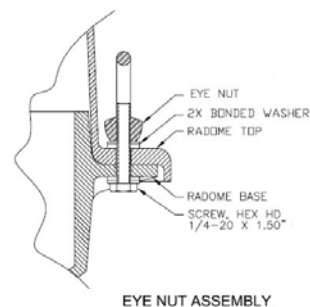


3.3.1. Prepare the 76" Radome Assembly

1. Remove the side walls of the radome crate.
2. Lift the pallet using a forklift and/or jacks.
3. From the underside of the pallet, remove the four shipping bolts which attach the ADE to its' pallet. Discard this shipping hardware.



4. Remove four equally spaced bolts around the radome flange. Save these nuts and bolts to be reinstalled later.
5. Install four lifting eyebolts in the vacant holes in the flange of the radome.. (Hardware provided in the radome installation kit). Keep the original perimeter bolt hardware to be reinstalled after the ADE has been installed.



6. Attach shackles and four part web lifting sling arrangement to the eyebolts.
7. Attach a suitable length tagline to one of the eyebolts.
8. After hoisted into place the lifting eyes are to be removed and replaced with the stainless hardware that was removed in step 4 (the eyes are galvanized with bare thread that will rust if left exposed to the weather).



3.3.2. Install 76" Radome to mounting deck.

The antenna pedestal is shipped completely assembled, restrained for shipping, in its radome.

1. Man the tag line(s).
2. Remove four equally spaced bolts around the radome flange. Save these nuts and bolts to be re-installed later.
3. Install four lifting eyebolts in the vacant holes in the flange of the radome. (Hardware provided in the radome installation kit). Keep the original perimeter bolt hardware to be reinstalled after the ADE has been installed.
4. Attach shackles and four part web lifting sling arrangement to the eyebolts.
5. Attach a suitable length tagline to one of the eyebolts.
6. Hoist the antenna assembly off the shipping pallet, by means of a suitably sized crane or derrick, to allow access to bottom of radome assembly.
7. Open the hatch by pressing the round release button in the center of the black latches and gently push the hatch up into the radome. Place the hatch door (gel coat surface up) inside the radome on the far side of the antenna pedestal.
8. Inspect the pedestal assembly and reflector for signs of shipping damage.
9. Peel the paper off of the mounting pad (provided in the radome installation kit) to expose the sticky side of the pad, align it to the mounting holes and press it in place on the underside of the radome base.
10. Using Loctite 271, install the twelve mounting bolts (provided in 123549-2 mounting kit) into the radome base. **ALL twelve mounting holes must be used when securing above decks equipment to vessel.**
11. Hoist the antenna assembly up onto the ship and hover above the mounting site on the ship.
12. Route AC power, ground strap/cable (see Grounding info below) and IF coax cables through the cable passage in center of the bottom of the radome base and through the cable channel under the lower base plate of antenna. Allow enough service loop to terminate these cables to the circuit breaker assembly and connector bracket respectively (see cable termination information below).
13. Lower radome assembly into the mounting holes, positioned with the BOW reference of the radome parallel with centerline of the ship. Any variation from actual alignment can be compensated with the Home Flag Offset and AZIMUTH TRIM adjustment, so precise alignment is not required.
14. Using Loctite 271, install the twelve fender washers and hex nuts (provided in mounting kit) from the underside of the mounting surface.
15. Remove the tag lines.
16. Remove the lifting sling.
17. Remove the four lifting eye nuts and reinstall the original perimeter bolt hardware (the eyes are galvanized with bare thread that will rust if left exposed to the weather). Save the lifting eye hardware in case lifting of the ADE is required in the future.

3.4. Grounding the Pedestal

The antenna pedestal must be grounded to the hull of the ship. A grounding point is provided on the upper base plate to ground the pedestal. A ground wire, of appropriate gauge for it's length, must be provided to ground the pedestal to the mounting platform that it will be bolted to (this is usually on or near the mounting surface). This mounting must also be electrically common with the hull of the vessel.

If a longer ground connection is required to reach a common metal connection to the hull, you must provide that longer cable/strap that is of sufficient gauge and length to ground the pedestal to the nearest grounding point of the hull.

Solid strap is the conductor of choice for low impedance RF ground connections because the RF currents tend to flow along the outer surface and the strap has a large smooth surface area to take full advantage of this effect.

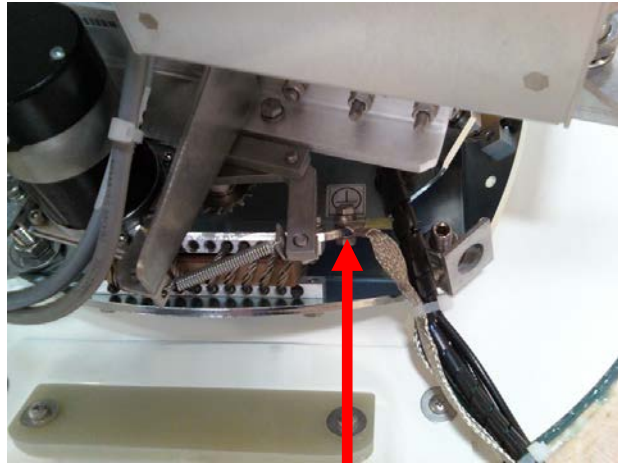
Braid is the conductor of choice where flexibility is required. Sea Tel uses braid to cross axes of the antenna pedestal and to connect various subassemblies together.

Wire is the easiest to install and connect and is readily available with a weather protective jacket. 4 awg and 6 awg bare solid copper wire is commonly used as safety grounds and very basic lightning protection grounds. 2 awg stranded wire is often used for lightning grounding and bonding and it much more flexible.

1. Connect the ground wire (of adequate gauge for the length) to a burnished ground point on, or near, the mounting surface. This burnished grounding point must be electrically common with the hull. Bi-metal coupling plate may be required to get good electrical coupling to the hull of the ship. Protective coating should be applied to prevent the grounding point, and ground wire, from rusting or corroding.

NOTE: Minimum gauge should not be smaller than **10 AWG**, even for a short cable run.

2. Route the ground cable/strap up through the radome base with the coax and power cables.
3. Route the ground strap/cable through one of the Roxtec® Multidiameter® blocks with the other power and coax cables.
4. Connect the grounding strap/cable to the burnished ground point on the upper base plate.



3.5. Removing the Shipping/Stow Restraints *PRIOR* to Power-Up

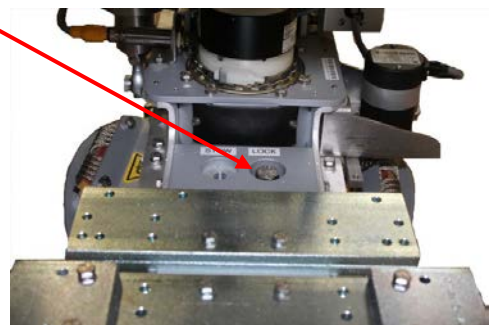
The order the restraints are removed is not critical.



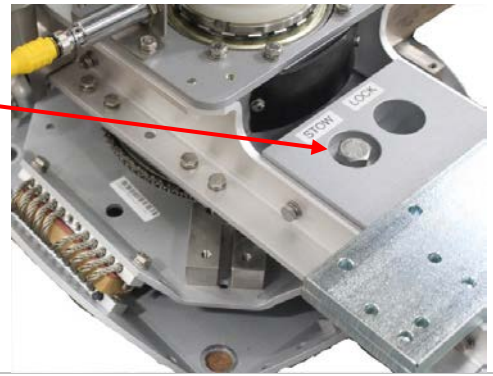
CAUTION: There are three shipping/stow restraints on this antenna pedestal that **MUST** be removed, **before energizing** the antenna, for normal operation.

3.5.1. Removing the AZ Shipping/Stow Restraint

1. The AZ shipping/stow restraint is formed by a pin bolt that is lowered into a channel in a stowage block on the upper plate of the pedestal (as shown).
2. To un-stow the antenna, remove the pin bolt from the LOCK position.



3. Install the pin bolt into the STOW hole and tighten. This assures that it does not get lost and will be ready for re-use if the antenna needs to be stowed again at a later date.
4. Verify that the antenna is able to rotate freely in azimuth.



3.5.2. Removing the EL Shipping/Stow Restraint

1. The EL shipping/stow restraint is formed by a stow pin-bolt mounted through a bracket and is engaged into a hole/slot in the elevation driven sprocket when the dish is at zenith (90 degrees elevation).
2. In the stowed position, the hardware from left to right is stow pin-bolt head, washer, bracket, washer, hex nut, hex nut so that the pin section of the stow pin-bolt is inserted into the hole in the elevation driven sprocket.

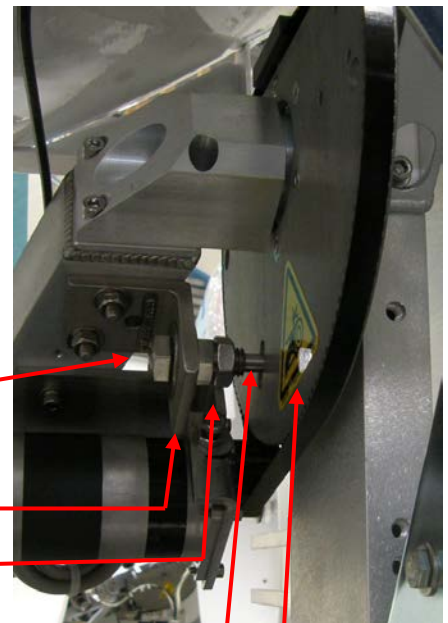
EL Stow Pin-Bolt head

Bracket

2 Hex Nuts

Pin inserted into Elevation Driven Sprocket

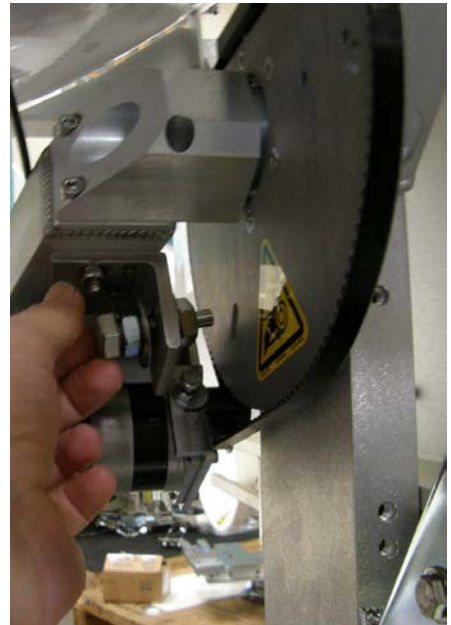
Elevation Driven Sprocket



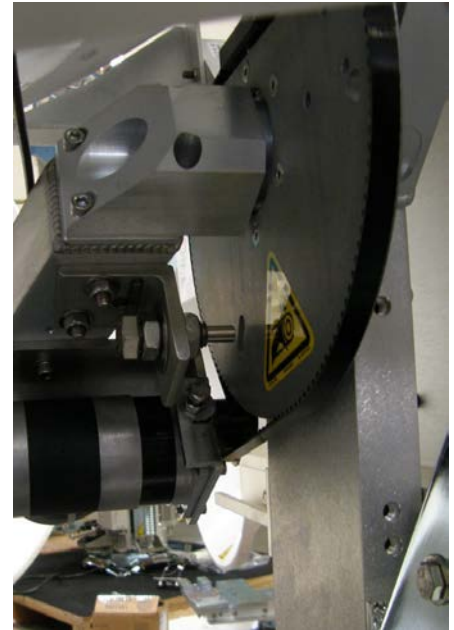
3. To un-restrain the elevation axis of the antenna, unthread the two hex nuts. Using a $\frac{3}{4}$ " open end wrench, remove the hex nuts and washer from the stow pin-bolt.
4. Remove the stow pin-bolt from the bracket.



5. Remove the washer from the stow pin-bolt and thread one of the two hex nuts onto the bolt and tighten.
6. Put one of the washers onto the stow pin-bolt and insert it into the bracket toward the elevation driven sprocket.
7. Put the other washer, and then the other hex nut onto the bolt.



8. Tighten the hex nut to prevent the hardware from loosening while in the un-stowed configuration.
9. Verify that the antenna rotates freely through its full elevation range of motion.



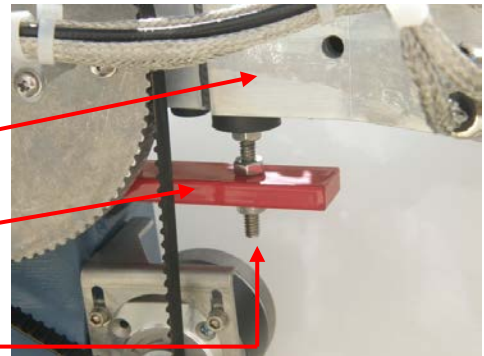
3.5.3. Removing the CL Shipping/Stow Restraint

1. The CL shipping/stow restraint is formed by a red locking bar with adjustable bumpers at each end of the bar. This mechanism is placed under the cross-level beam to lock it in place.

Cross-Level Beam

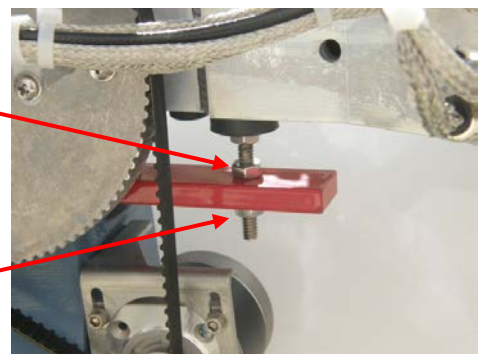
CL Shipping/Stow bar

Adjustable CL Locking Bumpers (only one end shown)



2. To un-restrain the cross-level axis of the antenna use a 7/16" open end wrench to loosen the nut on the top side of the locking bar (either end of the bar).

3. Remove the bottom nut off of that adjustable bumper.
4. Remove the adjustable bumper from the locking bar.



5. Extract the locking bar from the underside of the cross-level beam and retain these parts for later re-use if it becomes necessary to stow the antenna.
6. Verify that the antenna rotates (tilts left and right from level) freely through its full cross-level range of motion.

3.6. Connecting the Above Decks Equipment

Refer to the System Block Diagram.

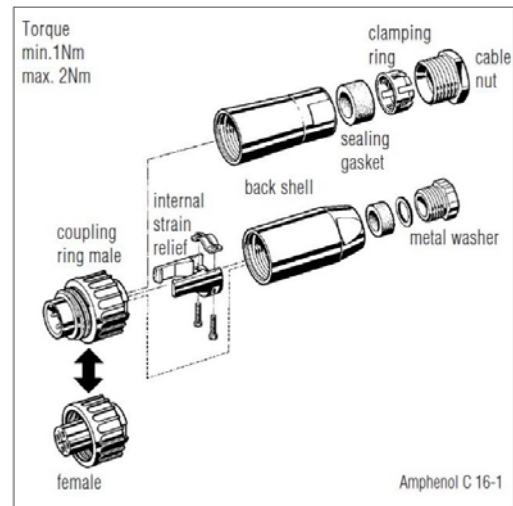
3.6.1. Pedestal Coax Cables

1. Route the coax cables to the interconnect bracket in the base of the radome.
2. Connect the TXIF cable to the TX connector on the bracket.
3. Connect the RXIF cable to the RX connector on the bracket.

3.6.2. Pedestal Power Cable

Route the pedestal power cable into the radome, through a proper strain relief gland.

1. Trim the AC Input Power wires to equal length as needed.
2. Slide the back-shell pieces of the input power circular connector onto the body of the power cable.
3. Refer to the circuit breaker box drawing provided inside the breaker box:
4. Strip each wire (as needed), insert it into the pin in the appropriate location of the body of the connector and tighten the retainer screw.
5. Assemble the back-shell onto the input power connector.
6. Plug the input power cable into the input of the circuit breaker box.



3.7. Installing the Below Decks Equipment.

3.7.1. General Cautions & Warnings



CAUTION - Electrical Shock Potentials exist on the Gyro Compass output lines. Assure that the Gyro Compass output is turned **OFF** when handling and connecting wiring to the MXP.



CAUTION - Allow only an authorized dealer to install or service the Sea Tel System components. Unauthorized installation or service can be dangerous and may invalidate the warranty.

3.8. Connecting the Below Decks Equipment

Connect this equipment as shown in the System Block Diagram. Install the equipment in a standard 19 inch equipment rack or other suitable location. Optional slide rails are available.

3.8.1. Connecting the BDE AC Power Cables

Connect the AC Power cables that supply power to the Below Decks Equipment (MXP, BDE Fiber Enclosure, TXRX Dual Antenna Arbitrator, Satellite Modem, phone, fax, computer and all other equipment) to an outlet strip fed from a suitably rated breaker or UPS.

3.8.2. Connecting the ADE-BDE Coax Cables

Connect the TXIF Cable to the TX connector on the ADE-BDE coax interconnect bracket.
Connect the TXIF Cable to the TX connector on the ADE-BDE coax interconnect bracket.

3.8.3. Media Xchange Point™ (MXP) Connections



Ships AC Mains - Connect the power cord from the rear panel of the MXP to AC voltage power source (UPS power recommended).

J1 Modem - Previously connected to the RX INPUT connector on the rear panel of the Timing Rack.

J2 RJ - Previously connected to the J4 RXIF Output (to ICU) connector on the rear panel of the Dual Modem Arbitrator.

J3 A/B & J4 A/B - Ethernet 4 Port 10/100 switch - Ethernet connections to computer, satellite modem LAN devices as desired. Connect a CAT5 cable from J3A to an open RJ-45 connection on the CFE Router.

J5 SFP Fiber Interface - SFP Gigabit Ethernet connection.

J6 Mini-USB Computer M&C Connection - Mini-USB Antenna M&C connection, if desired.

J7 USB Host - Not connected - -Future development.

J8 Console - Antenna M&C Serial connections.

J9 A/B Serial - Computer RJ-45 Serial M&C connections. A is mapped to the Radio serial M&C port of the ICU and B is mapped to the Pass through serial M&C port of the ICU.

J10C Modem - RJ-45 Serial M&C connection to DAC A Input on the TX/RX Dual Antenna Arbitrator.

J10D OBM - RJ-45 Serial M&C connection to Out of Band Management equipment, if used.

J11 Gyro - Terminal Strip for SBS or Synchro Gyro Compass interface connections. Wiring is:

Pin 1	Synchro R1
Pin 2	Synchro R2
Pin 3	Synchro S3 / SBS A
Pin 4	Synchro S2 / SBS B
Pin 5	Synchro S1 / SBS C
Pin 6	SBS COM

J13 NMEA 0183 - NMEA 0183 I/O connections. J11 NMEA port on the rear panel is used for NMEA 0183 Gyro Compass input to the MXP. The +12 VDC output is only intended to power a very low current consumption device, do NOT exceed **125ma MAX**. Wiring is:

Pin 1	RX+ NMEA
Pin 2	RX- NMEA
Pin 3	TX- NMEA
Pin 4	N/C
Pin 5	GND
Pin 6	N/C
Pin 7	GND
Pin 8	TX+ NMEA
Pin 9	+12 VDC (125ma MAX)

If your NMEA 0183 Gyro Compass outputs RS-422:

- Connect its' TX+ output to J10 pin 1 (RX+)
- Connect its' TX- output to J10 pin 2 (RX-)

If your NMEA 0183 Gyro Compass outputs RS-232:

- Connect its' GND output to J10 pin 1 (RX+)

- Connect a jumper from pin 1 to J10 pin 5 (GND)
- Connect its' TXD output to J10 pin 2 (RX-)

J12 Aux 232 - Auxiliary wired RS-232 connection. Wiring is:

Pin 1 - GND	Ground
Pin 2 - Aux IN1	Modem Lock Input 1 - See modem setup chapter.
Pin 3 - Aux IN2	Modem Lock Input 2 - See modem setup chapter.
Pin 4 - GND	Ground
Pin 5 - SW1	Blockage/Modem Mute Output 1 - See blockage & modem setup chapters.
Pin 6 - SW2	Blockage/Modem Mute Output 2 - See blockage & modem setup chapters.
Pin 7 - SW3A	Dry Contact set 2 - Dry alarm contacts used to provide (programmable) alarm output to other equipment/systems. Switched outputs have ability to use 4.7K pull up or Pull Down and can provide Current sink of 0.5 amps max. Contacts are Normally Open for No Alarm state and are Closed/Shorted when the programmed alarm state exists.
Pin 8 - SW3B	
Pin 9 - SW4A	Dry Contact set 1 - Same as dry alarm contact set 2.
Pin 10 - SW4B	

J14 Aux 232 - Antenna M&C Serial connections. The +12 VDC output is only intended to power a very low current consumption device, do NOT exceed **125ma MAX**. Wiring is:

Pin 1	N/C
Pin 2	RD
Pin 3	TD
Pin 4	N/C
Pin 5	GND
Pin 6	N/C
Pin 7	RTS
Pin 8	CTS
Pin 9	+12 VDC (125ma MAX)

J15 NMEA 2000 - NMEA 2000 I/O connection. **RESERVED FOR FUTURE USE**

3.8.4. Other BDE connections

Connect your other Below Decks Equipment (ie, telephone, fax machine and computer equipment) to complete your configuration.

3.9. Final Checks

3.9.1. Visual/Electrical inspection

Perform a visual inspection of your work to assure that everything is connected properly and all cables/wires are secured.

3.9.2. Electrical - Double check wiring connections

Double check all your connections to assure that it is safe to energize the equipment.

3.10. Setup - Media Xchange Point™ (MXP)

Now that you have installed the hardware, you will need to setup, calibrate and commission the antenna.

You may also need to load/update the modem option file, which is not part of the scope of this manual, contact the airtime provider NOC for guidance.

At the very least, you will need to set up the antenna system for:

- Connect & configure a ships computer for accessing the MXP.
- The gyro compass signal being provided by the ship.
- Check/Set Home Flag.
- Set up Blockage zone(s) as needed.
- Set up / configure all satellites that the system might use as the ship travels, even if there is only one. If your system will be using iDirect OpenAMIP you will not need to create satellite configurations.
- Acquire the desired satellite.
- Optimize targeting (Auto or manual trim).
- Arrange for commissioning & cross-pol isolation testing with the NOC.
- Conduct cross-pol isolation testing with the NOC.
- Conduct other commissioning testing with the NOC (ie P1dB compression point).
- If this is a Dual Antenna installation configuration, you will have to balance the TX levels of the two antennas while online with the NOC (refer to procedure in the Dual Antenna Arbitrator manual).
- It is strongly recommended that you download, and save, the system INI file (contains all of the system parameters for the ICU and the MXP). Save this file in a convenient location on your computer.

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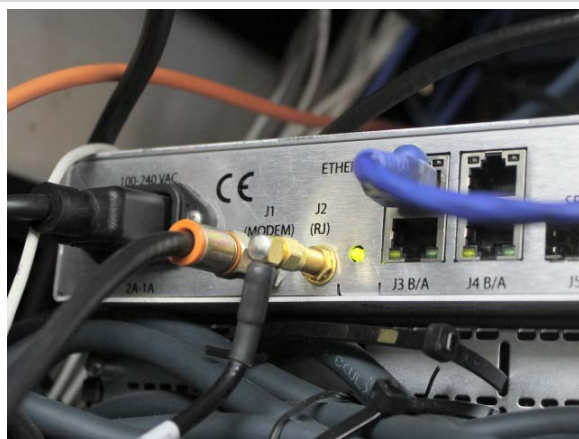
4. Configuring a Computer for the MXP

The first thing you need to do is to configure your computer so that it will display the MXP screens. Follow these instructions to accomplish that.

1. Connect a LAN cable to the back of your computer.



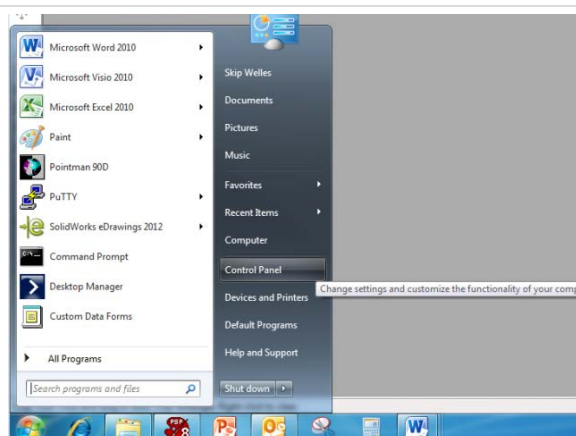
2. Connect the other end of the LAN cable to the back of the MXP.



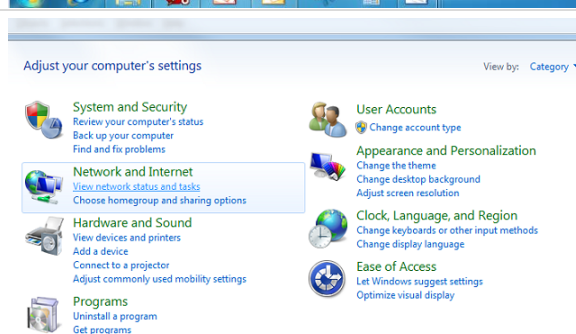
3. Power on the MXP.



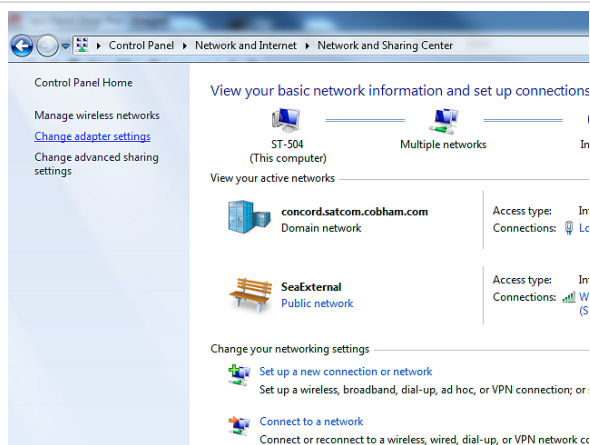
4. From your computer desktop, click the Control Panel button.



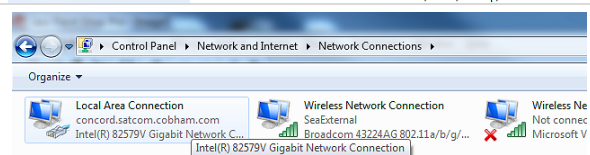
5. Click on "View network status and tasks".



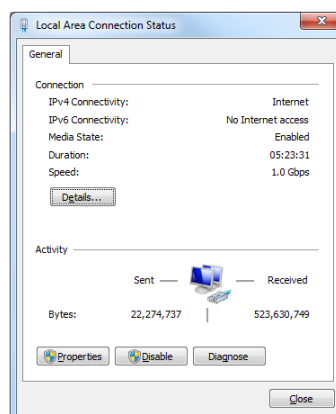
6. Click "Change adapter settings".



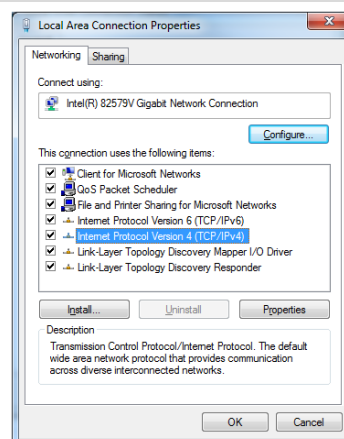
7. Click on "Local Area Connection."



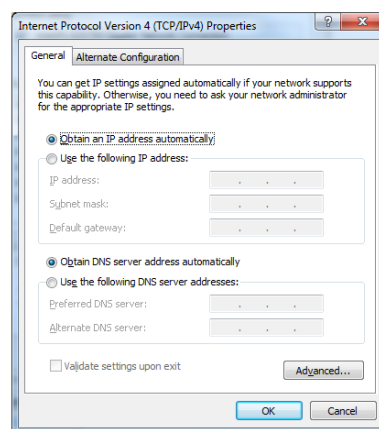
8. Click on "Properties".



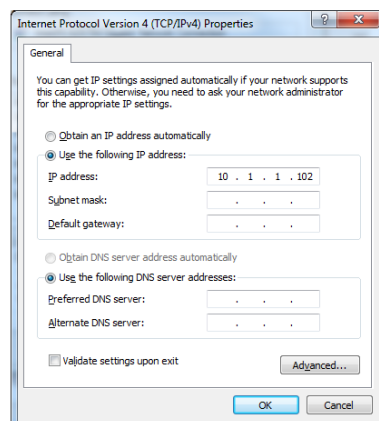
9. Click on "Internet Protocol Version 4 (IPv4)".



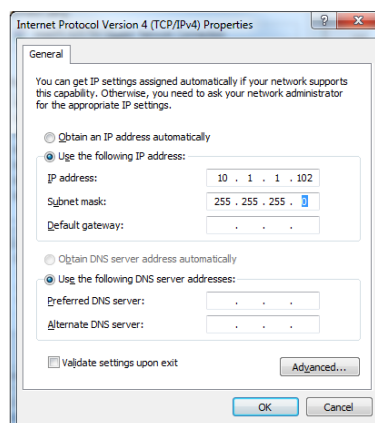
10. Click on "Use the following IP address:



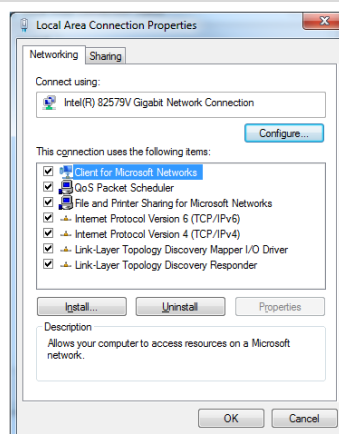
11. In the IP Address boxes, enter "10.1.1.102" (This is for the IP address of your computer).
NOTE: You could use 101, 102, 103, etc. as long as it is not the same as the address of the MXP, which is "10.1.1.100" (default).



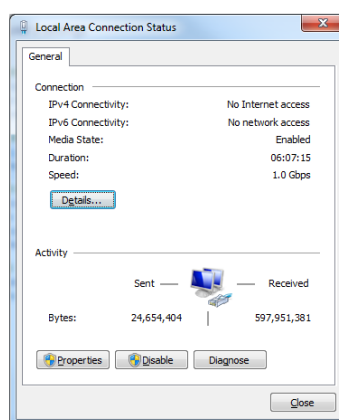
12. On the second line, enter Subnet Mask of "255.255.255.0".
13. Then click the "OK" button.



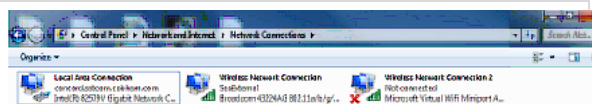
14. Back at the Local Area Connection Properties screen, click the "OK" button.



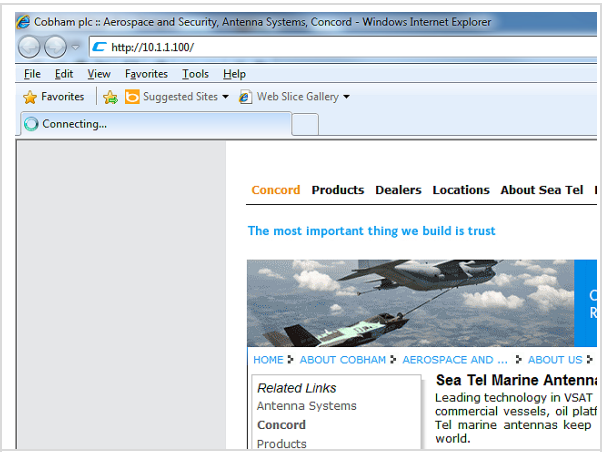
15. Click the "Close" button.



16. Close the Control Panel.



17. Open your browser, and enter the URL: "10.1.1.100".



18. At the log in screen enter the user name & password. User name and password are case sensitive.

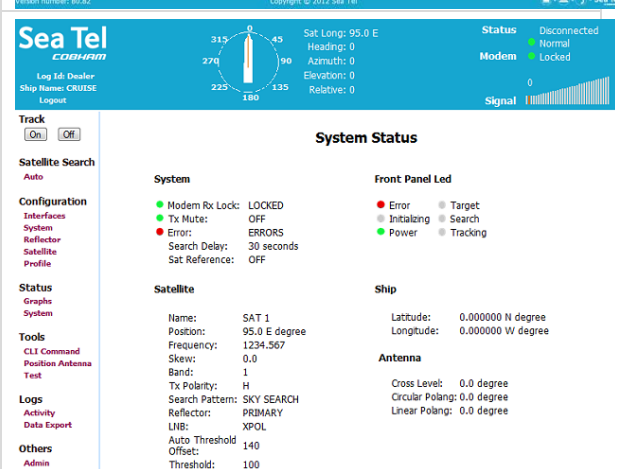
Dealer password seatel3

SysAdmin password seatel2

User password seatel1



19. After you log in you will see the System Status screen



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5. Setup – Ship's Gyro Compass

The Ships Gyro Compass connection provides true heading (heading of the ship relative to true North) input to the system. This allows the ICU to target the antenna to a "true" Azimuth position to acquire any desired satellite.

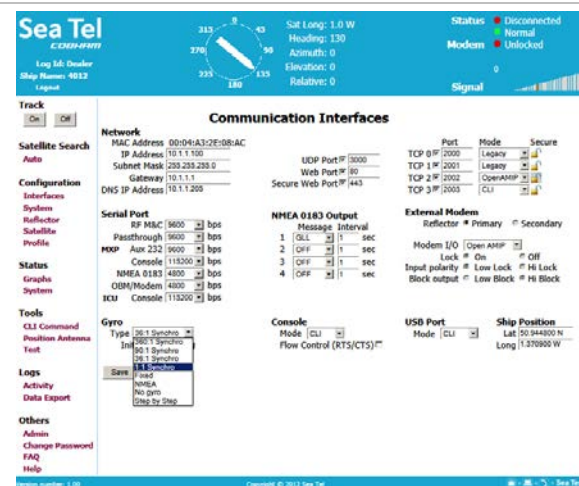
After targeting, this input keeps the antenna stabilized in Azimuth (keeps it pointed at the targeted satellite Azimuth).

5.1. Setting the Gyro Type

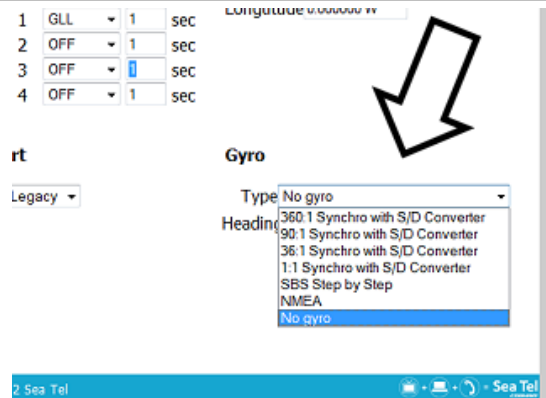
The GYRO TYPE parameter selects the type of gyro compass interface signal, the appropriate hardware connections, and the ratio of the expected input signal for ship turning compensation. Default GYRO TYPE parameter for all systems is Step-By-Step so that the ICU will properly follow for Step-By-Step or NMEA gyro signals.

If the Ships Gyro Compass output is Synchro, or there is NO Gyro Compass, the GYRO TYPE parameter must be set correctly to properly read and follow the Ships Gyro Compass signal that is being provided. To manually update the Gyro Type parameter:

1. Go to the Communications Interface screen.
2. Click the Gyro Type drop down menu..



3. Select the correct Gyro type.



4. Click Save, at the bottom left area of the screen.

5.2. If there is NO Ships Gyro Compass

Without heading input to the system the MXP will NOT be able to easily target, or stay stabilized ON, a “true” azimuth pointing angle. This will make satellite acquisition much more difficult and the true azimuth value that any given satellite should be at will not be displayed correctly.

This mode of operation is NOT recommended for ships or any other vessel that turns in the water. A better solution would be to provide a Satellite Compass (multiple GPS Antenna device) to provide true heading input to the ACU. These devices are readily available and are much less expensive than a Gyro Compass.

If there is NO Gyro Compass (ie on a large stationary rig which is anchored to the ocean floor) set the GYRO TYPE parameter to “No Gyro” or to “Fixed”.

Fixed mode is used when you do not have a gyro compass, but the ship/vessel/rig is stationary at a fixed heading that you can manually enter for satellite targeting. This allows you to use a standard (small) search pattern and acquire the satellite relatively quickly.

No gyro mode is used when you do not have a gyro compass, the ship does turn and you will use “Sky Search” to initially acquire the satellite. The Sky Search drives the antenna to the calculated elevation angle and then drives azimuth CW 360 degrees, steps elevation up and then drives azimuth CCW 360 degrees and continues to alternately steps elevation up/down and drives azimuth alternately CW/CCW 360 degrees. Because of this large search area, acquiring the satellite will take MUCH longer than if you have valid heading input.

1. Go to the Reflector Configuration page
2. To change: Set the Scan Rate parameter to 5 deg/sec.

3. Turn on SAT REF Mode. (It must be turned on.)

Satellite Search
Auto
Manual

Configuration
Interfaces
System
Reflector
Satellite
Profile

Status
Graphs
System

Tools
CLI Command
Position Antenna
Test

Logs
Activity
Data Export

Others
Admin
Change Password
FAQ
Help

System Configuration

Blockage Zones

Zone	Description	REL start	deg	REL end	deg
Zone1	[Enter Description]	0.0	deg	0.0	de
Zone2	[Enter Description]	0.0	deg	0.0	de
Zone3	[Enter Description]	0.0	deg	0.0	de
Zone4	[Enter Description]	0.0	deg	0.0	de

Miscellaneous

Home Flag 0.0

Sat Ref Mode ☒ On ☐ Off

Auto Sat Load ☐ On ☒ Off

Power Up ☐ On ☒ Off

Search Failure ☐ On ☒ Off

Profile Number 0

System SN 000000000000000000

Ship Name [Enter Ship Name]

Antenna Name [Enter Description]

Advanced Settings

Vlm Ratio 2

Slow Scan Vlimit 0.1 deg/sec

Step Resolution 0.1 deg

Antenna Model [MODELID]

Number of Reflectors 1

Drive Orientation

EL	CL	AZ	Reverse
Forward	Forward	Forward	Reverse
Reverse	Reverse	Reverse	Forward

Motor Gain

EL	CL	AZ
EL17	CL15	AZ16

Reference

EL	CL	AZ
On	On	On

Save

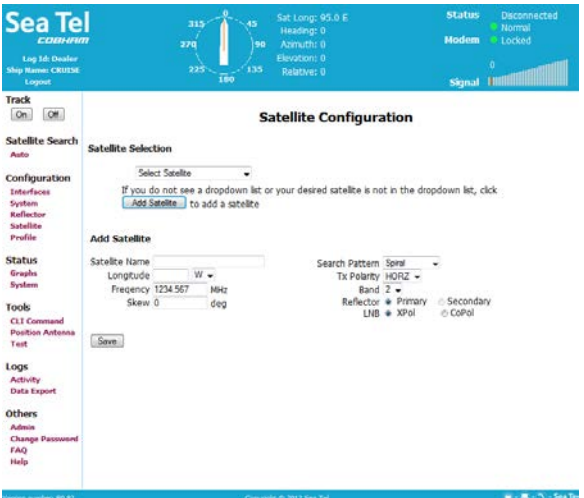
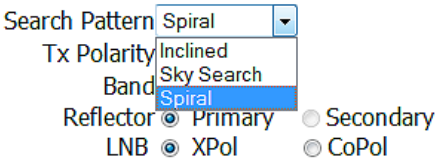
This combination of settings will cause “No Gyro” Search pattern to be used to find the desired satellite (refer to the setup – Searching chapter).

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6. Setup – Azimuth Trim

Beginning in IMA software version 1.05, calibrating the targeting of your antenna is much easier. This is accomplished improving Sky Search and changing the way that Azimuth Trim works so that the need for Home Flag Offset is eliminated. Azimuth Trim now corrects the relative position of the antenna in all configurations which have valid/accurate gyrocompass input.

If the antenna has been purposely mounted with the bow mark of the ADE not in alignment with the bow of the ship, such as for safe entry into the radome hatch, note and enter the approximate offset into the AZ TRIM parameter before searching for the satellite for the first time. **EXAMPLE:** The antenna is being mounted on the port side of the ship where it is unsafe for the hatch to be oriented directly in line with the stern. The installer rotates the ADE so that the bow mark is facing directly to the port and bolts that ADE into place. When first powering the system up, he will enter +90 in the AZ TRIM parameter to indicate that the ADE was rotated CW 90 degrees during the installation. This will make **initial** satellite acquisition faster (even though sky search would still find the satellite). This entry is only needed on a new installation that AUTO TRIM has not been run on yet. If the ADE had been similarly installed on the starboard side -90 degrees would have been entered to indicate that the ADE was rotated CCW 90 degrees during the installation.

<ol style="list-style-type: none"> 1. Access the Satellite Configuration screen. 	
<ol style="list-style-type: none"> 2. Select Sky Search as your desired type of search pattern to use for this initial satellite acquisition on a newly installed antenna system. 	
<ol style="list-style-type: none"> 3. Select the satellite that your airtime services will be provided on in the Satellite Selection dropdown. 4. Refer to the next chapter to enter blockage zones as desired. 5. After the desired satellite has been acquired, allow the antenna to track for about 2 minutes BEFORE clicking Auto Trim. 6. Refer to Setup – Targeting – and follow the instruction for AUTO TRIM to optimize the targeting of the antenna. 	

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7. Setup – Blockage & RF Radiation Hazard Zones

The Blockage Zones function inhibits the antenna from transmitting within certain pre-set zones. This is typically some structure of the ship that prevents satellite signal from getting to the Sea Tel antenna when the ship is at headings that put that structure in-between the satellite and the satellite antenna,

However, it can also be used as an RF Radiation Hazard zone. If there is an area where people may be near the antenna (within 2 meters), in the antennas transmitted beam for extended periods of time the zone can be set up so that transmit from the satellite antenna will be disabled whenever the antenna is pointed in that zone.

7.1. Radiation Hazard and Blockage Mapping

The MXP can be programmed with relative azimuth sectors (zones) where blockage exists or where transmit power would endanger personnel who are frequently in that area. Your MXP software allows you to set four zones.

When you create these ZONES (up to four), several things happen when the antenna is within any one of the zones:

1. Tracking continues as long as the AGC value is greater than the Threshold value. When the AGC value drops below Threshold, the antenna will wait “Search Delay” parameter amount of time and then re-target the satellite you targeted last. Timeout and re-target will continue until the satellite is re-acquired and tracking can resume.
2. The satellite modem transmission will be disabled until the antenna exits the zone.

The lower and upper azimuth limits are entered into the REL start, REL stop and EL fields within the MXP for each of the blockage zones you wish to create (up to four). Each zone can also be given a name (ie Mast, Deckhouse or Stack):

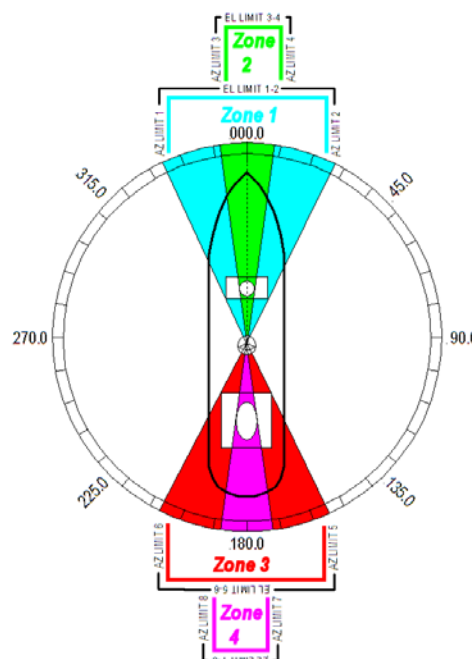
REL Start is the Lower Relative AZ limit (this is the more counter-clockwise of the two points, even if it is numerically larger). **REL Stop** is the Upper Relative AZ limit (the more clockwise of the two points) for pattern mapping of each. Enter the elevation value that represents the top of the blockage between the two azimuth limit points in the **EL** field.

Repeat for up to four zones, click SAVE when completed.

Programming instructions:

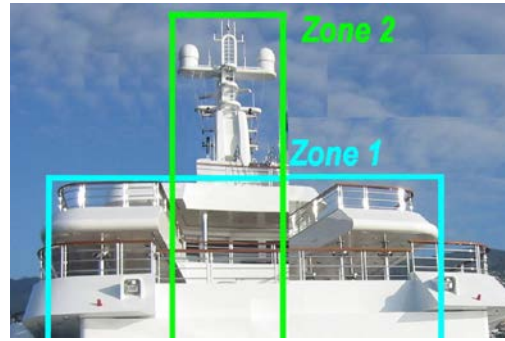
Determine the Relative AZ positions **where** blockage, or RF Radiation Hazard, exists. This may be done by monitoring the received signal level and the REL display readings while the ship turns or by graphing the expected blockage pattern. Elevation of the antenna in normal use also must be taken into consideration. A Mast or other structure may cause blockage at low elevation angles, but **may not** cause blockage when the antenna is at higher elevation angles where it is able to look over the structure. Up to four zones may be mapped. Only zones which are needed should be mapped.

EXAMPLE - Overlaid Blockage Zones: A ship has a Sea Tel antenna mounted on the center line of the ship. A mast mounted on top of a deckhouse (like the picture below) is forward and an engine exhaust stack, also on a deckhouse, is aft. These two blockage areas have wide azimuth blockage at lower elevations and then a narrower azimuth area of blockage extends up to a higher value of elevation.



be

ZONE 1 named “Fwd Deckhouse” begins (**REL Start**) at 334 degrees Relative and ends (**REL Stop**) at 026 degrees Relative. Enter **REL Start** value of 334.0 and **REL Stop** value of 26.0. In this case the mast height only causes blockage up to an elevation of 40 degrees, so we set **EL** to 40.0. If the antenna is between these two AZ Limit points but not in the “mast” zone AND the elevation is greater than 40 degrees, the antenna will no longer be blocked.



ZONE 2 named “Mast” begins (**REL Start**) at 352 degrees Relative and ends (**REL Stop**) at 008 degrees Relative. Enter **REL Start** value of 352.0 and **REL Stop** value of 8.0. In this case the mast height only causes blockage up to an elevation of 70 degrees, so we set **EL** to 70.0. If the antenna is between these two AZ Limit points but the elevation is greater than 70 degrees, the antenna will no longer be blocked.

ZONE 3 named “Aft Deckhouse” begins (**REL Start**) at 155 degrees Relative and ends (**REL Stop**) at 205 degrees Relative. Enter **REL Start** value of 155.0 and **REL Stop** value of 205.0. In this case the aft deckhouse height only causes blockage up to an elevation of 30 degrees, so we set **EL** to 30.0. If the antenna is between these two AZ Limit points but the elevation is greater than 30 degrees, the antenna will no longer be blocked.

ZONE 4 named “Stack” begins (**REL Start**) at 173 degrees Relative and ends (**REL Stop**) at 187 degrees Relative. Enter **REL Start** value of 173.0 and **REL Stop** value of 187.0. In this case the stack height only causes blockage up to an elevation of 55 degrees, so we set **EL** to 55.0. If the antenna is between these two AZ Limit points but the elevation is greater than 40 degrees, the antenna will no longer be blocked.

7.2. Programming Instructions:

1. To set up the blockage zones go to the System Configuration screen.

2. Enter a readily identifiable name for the zone (ie Mast, Deck House or Stack).
3. Moving to the right, enter the relative of the starting point of this blockage zone (the more counter-clockwise bearing).
4. Then enter the relative bearing of the stop point of this blockage zone (the more clockwise of the two bearings).

5. Likewise, for Elevation, you need only to enter the elevation angle, below which you want the transmitter inhibited (blocked).

System Configuration

Blockage Zones

Zone1 [Enter Description]	REL start 0.0 deg	REL end 0.0 deg	EL 90.0 deg
Zone2 [Enter Description]	REL start 0.0 deg	REL end 0.0 deg	EL 0.0 deg
Zone3 [Enter Description]	REL start 0.0 deg	REL end 0.0 deg	EL 0.0 deg
Zone4 [Enter Description]	REL start 0.0 deg	REL end 0.0 deg	EL 0.0 deg

Miscellaneous

Home Flag 0.0
Sat Ref Mode ☐ On ☒ Off

Profile Number 0
System SN 00000000000000000000
Ship Name [Enter Ship Name]
Antenna Name [Enter Description]

Auto Sat Load
Power Up ☒ On ☐ Off
Search Failure ☒ On ☐ Off

Advanced Settings

Vlim Ratio 2
Slow Scan Vlim 0.1 deg/sec
Step Resolution 0.1 deg
Antenna Model MODELID
Number of Reflectors 1

Drive Orientation
EL ☒ Forward ☐ Reverse
CL ☒ Forward ☐ Reverse
AZ ☒ Forward ☐ Reverse

Motor Gain
EL 17
CL 15
AZ 16

Reference limit
EL ☐ On ☒ Off
CL ☐ On ☒ Off
AZ ☐ On ☒ Off

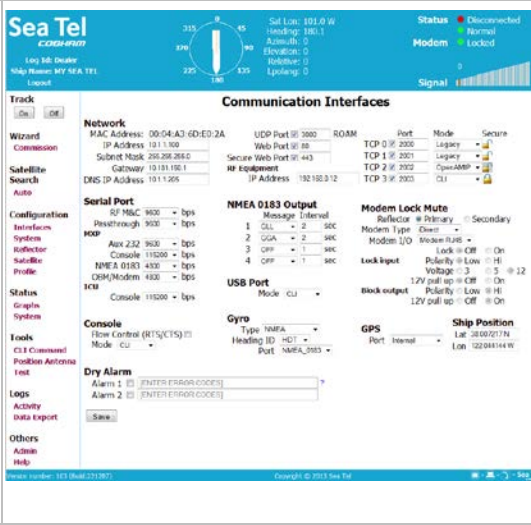
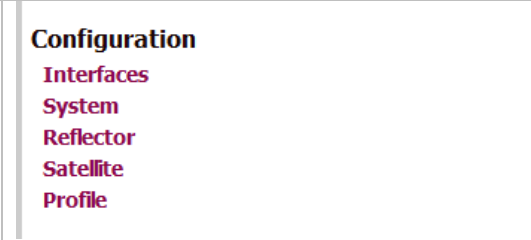
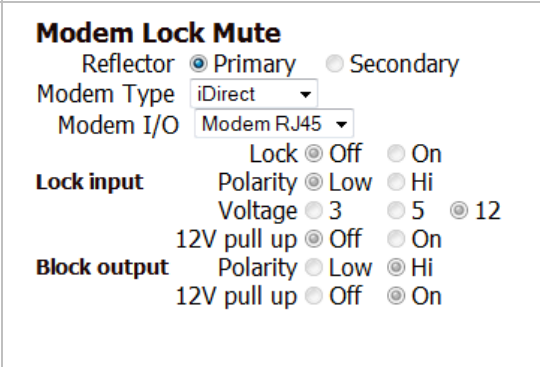
6. Repeat steps 2-5 to describe up to 4 blockage zones.

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8. Configuring The Satellite Modem Interface.

The configuration setup of an integrated satellite modem to the MXP is accomplished via the Communication Interface Page (Configuration>Interfaces link on the navigational panel on the left hand side of the screen). In order to access this page, the user must be logged in as either "Dealer" or "SysAdmin". The current software load, IMA Ver 105 at the time of this release) contains 6 commonly used satellite Modems (iDirect, Comtech, Gilat, Hughes, STM, and Viasat) as selectable presets and is typically a prompted selection when using the new Commissioning Wizard. However, the MXP allows configuration of a "Custom" modem type. The primary focus of this procedure is to define all of the parameter options made available to allow the commissioning technician to properly integrate any compatible L-Band Satellite modem.

8.1. Satellite Modem Interface

<ol style="list-style-type: none"> 1. If not already, log into the system using the "Dealer" or "SysAdmin" credentials. 	
<ol style="list-style-type: none"> 2. On the left hand side of the screen, under Configuration, select the "Interfaces" link. 	
<ol style="list-style-type: none"> 3. On the right side of the screen, approximately half way down is the "Modem Lock Mute" section. This section is where the user, via drop down menu selection and/or mutually exclusive radio buttons, defines: <ul style="list-style-type: none"> • Reflector • Modem Type • Modem I/O • Lock Input • Block Output 	

8.1.1. Reflector setting

Use: In a dual reflector based antenna system, the "Reflector" selection defines which reflector the modem configuration applies to.

Selection Type: Mutually Exclusive Radio Buttons

Options: Primary or Secondary

Modem Lock Mute

Reflector ☒ Primary ☐ Secondary

Modem Type

Modem I/O

Lock ☐ Off ☐ On

Lock input Polarity ☐ Low ☐ Hi

Voltage ☐ 3 ☐ 5 ☒ 12

12V pull up ☐ Off ☐ On

Block output Polarity ☐ Low ☐ Hi

12V pull up ☐ Off ☐ On

Notes: In the current Series 12 antennas this setting should always be set to PRIMARY. Failure to do so may result in abnormal system operation.

8.1.2. Modem Type setting

Use: This selection defines which manufacturer of satellite modem is to be interfaced with the system.

Selection Type: Drop down menu selection

Options: iDirect, ComTech, Gilat, Hughes, STM, Viasat, or Custom.

Notes: The selection of modem type (along with the modem I/O) allows the IMA software to configure the appropriate RX Network Lock, and TX Mute/Block output Lock interfaces per the modem manufacturers' specifications.

Once you select one of the manufacturers and I/O from the dropdown list the other settings that are appropriate for that modem will be set for you (and greyed out).

If your modem manufacturer is not listed, you will need to select "Custom" and manually configure the modem I/O properties. Refer to the custom settings information below.

Modem Type	iDirect
Modem I/O	iDirect
Lock input	Off
Block output	Low

8.1.3. Modem I/O setting

Use: This selection defines which type (and location) of communication interface between the MXP and the satellite modem.

Selection Type: Drop down menu selection

Options: OpenAMIP, ROAM, TS1, TS2, or CLI.

Notes: The Modem I/O selections of iDirect's **OpenAMIP** or ComTech's **ROAM**, both forms of ABS (Automatic Beam Switching), communicate via TCP/IP traffic between the MXP's J9 or J10 Ethernet port and the applicable modems Ethernet port. It should also be said that, to use these I/O types, there is a requirement that the integrated satellite modem and NOC (hardware and software) are properly configured and capable to support said feature.

Modem RJ45 is used for standard console port type connections where GPS forwarding is required (i.e. iDirect Console Port) in addition to Positive Satellite ID (RX Network Lock) and TX Mute/Blockage zone functionality

TS1 and **TS2** are hard wired interfaces used only for positive satellite ID (RX Lock) and TX mute functionality.

In some installations, **CLI** (Command Line Interface) may be desired. CLI is used when a third party ABS device (separate from satellite modem itself) is interfaced to provide antenna control, positive satellite ID (Rx Lock), and TX mute functionality via TCP/IP traffic between the MXP's J9 or J10 Ethernet port, or Serial Traffic (Console), and the applicable devices Ethernet port.

Modem I/O	Modem RJ45
Lock input	Off
Block output	Low

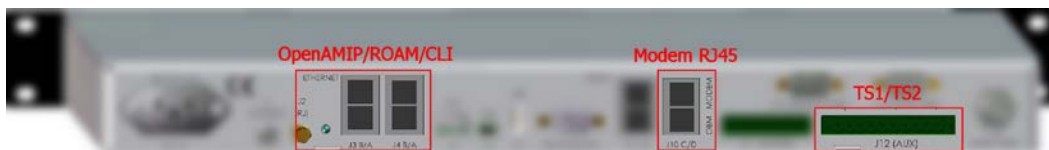


Figure 1 Available MXP Rear Panel Modem IO Ports

8.1.4. Modem I/O – Custom Settings

Use: The individual Modem I/O selections allow the user to manually define the expected driver (output) and detector (input) circuit(s) as well as positive satellite ID functionality between the MXP and the satellite modem.

Selection Type: Mutually Exclusive Radio Buttons

Options: Lock Input: On or Off, Polarity, 12V Pull up.

Block Output: Polarity and 12V Pull up

Notes: The lock input and Block output radio button selections may only be modified if the Modem Type "Custom" Modem Type has been selected.

Modem Lock Mute	
Reflector	<input checked="" type="radio"/> Primary <input type="radio"/> Secondary
Modem Type	iDirect
Modem I/O	Modem RJ45
Lock input	<input type="radio"/> Off <input checked="" type="radio"/> On <input type="radio"/> Low <input type="radio"/> Hi <input type="radio"/> 3 <input type="radio"/> 5 <input checked="" type="radio"/> 12
Block output	<input checked="" type="radio"/> Off <input type="radio"/> On <input type="radio"/> Low <input type="radio"/> Hi <input type="radio"/> 12V pull up <input type="radio"/> Off <input checked="" type="radio"/> On

If any of the other Modem Types are selected, the Lock Input and Block Output radio buttons are predefined for you by software and therefore become read only. This is evidenced to the user by disabling the selections, see image to right for an example of this.

8.1.4.1. Modem I/O – Lock ON/OFF

Use: The Modem I/O Lock Input “**Lock**” selection defines whether or not the MXP will use positive satellite ID functionality.

When OFF, the system will simply use the tracking receiver settings and the subsequent AGC from the receiver to track an acquired satellite. This may be the desired satellite or it may be an adjacent satellite that was acquired during a search for the desired satellite.

When ON, the system must get AGC and ALSO receive a network lock logic signal from the modem to continue tracking the acquired satellite. This prevents tracking the wrong satellite and verifies that the antenna is in fact on the desired satellite (to get network lock from the modem the antenna must be on the correct polarity of the correct satellite). If during a search an adjacent satellite is found, good AGC from the tracking receiver will cause the system to initially track/peak this satellite but be waiting for a network lock signal from the satellite. If the lock signal is not received within 30-40 seconds, that system will return to the search track line and resume searching for the satellite which provides AGC & Lock. Lock Input settings below MUST be set correctly for this functionality to work properly.

Selection Type: Mutually Exclusive Radio Buttons

Options: Lock ON or OFF.

Notes: Modem Type “Custom” must have been selected to allow changes to these settings. Setting Modem Lock to “ON” will enable the positive satellite ID feature whereas setting modem Lock to “OFF” disables the feature. With the exception of the some calibration procedures (ie during Cross-Pol isolation and 1dB compression tests) it highly recommended to leave this setting to ON. By doing so, you eliminate tracking on adjacent satellites for any extended amount of time (typically 30-40 seconds)

8.1.4.2. Modem I/O – Lock Input – Polarity

Use: The Modem I/O Lock Input Polarity selection defines whether the hard lined wire input provides a logic level high or logic level low as indication of Positive Satellite ID (RX Network Lock indication).

Selection Type: Mutually Exclusive Radio Button

Options: Polarity Low or Hi.

Notes: Modem Type “Custom” must have been selected to allow changes to this setting.

You must refer to your satellite modems manufacturers written specifications for its nominal receive lock indication output. Example if you have a satellite modem that provides a nominal 5VDC output when in a NON-Locked condition (off satellite) and 0Vdc when in a locked condition (on satellite), you would set Polarity to “Low”.

If your modem provides a continuity based output, short to ground is Low, and Open is High. If your modems output is continuity based logic the Voltage must be set to 12V and the 12V pull up must be set to “ON” (See Modem I/O Voltage & 12V Pull up sections below). Failure to do so may result in a false Rx Lock trigger when the applicable modem interface cable is removed for any reason.

8.1.4.3. Modem I/O – Lock Input - Voltage

Use: The Modem I/O Lock Input Voltage selection defines the nominal voltage range for the hard lined wire input for indication of Positive Satellite ID (RX Network Lock indication).

Selection Type: Mutually Exclusive Radio Buttons

Options: Voltage 3V, 5V or 12V.

Notes: Modem Type “Custom” must have been selected to allow changes to this setting.

You must refer to your satellite modems manufacturers written specifications for the receive lock indication voltage range that it provides as an output. The receive logic level itself is interpreted by the MXP based on the above mentioned Polarity selection (the actual Low versus Hi polarity trigger is 50% of selected voltage range). Example: You have a satellite modem that provides a 12VDC output range and Polarity has been set to Low. When the detected voltage is between 0 to 6Vdc, the MXP would interpret this as a Positive Satellite ID. Voltage between 6.1 and 12Vdc would be interpreted as a failed Positive Satellite ID (because it is High).

If your modem provides a continuity based output (short to ground is Low, and Open is high), you must set this selection to 12V.

8.1.4.4. Modem I/O – Lock Input - 12V Pull Up

Use: The Modem I/O Lock Input 12V Pull Up selection defines whether or not to use a built-in 12VDC Pull up resistor for the hard lined wire input for indication of Positive Satellite ID (RX Network Lock indication). The MXP requires a voltage input for this satellite ID functionality.

If your modem outputs continuity based logic, the pull up circuit (ON) converts the continuity to voltage. For all voltage based modem outputs, it MUST be set to OFF to prevent false Positive Sat ID indications (voltage high & higher, but never low).

Selection Type: Mutually Exclusive Radio Buttons

Options: 12V Pull Up Off or On.

Notes: Modem Type “Custom” must have been selected to allow changes to this setting.

If your modem provides a continuity based output (short to ground is Low, and Open is high) this selection must be set to “ON”. For all voltage based modem outputs, it MUST be set to OFF.

8.1.4.5. Modem I/O – Block Output – Polarity

Use: The Modem I/O - Block Output selection defines whether or not the MXP will provide a logic level Low or logic level Hi output when a condition exists that requires muting the IF transmission of the system. This is known as TX Mute functionality and is a signal from the MXP to the Satellite Modem (which in turn removes drive to the Block Up Converter mounted on the antenna assembly). The signal flow for this feature is from the MXP to the Satellite Modem.

Selection Type: Mutually Exclusive Radio Buttons

Options: Polarity Low or Hi.

Notes: Modem Type “Custom” must have been selected to allow changes to this setting.

You must refer to your satellite modems manufacturers written specifications for the input required to mute the modems output to the BUC. Ascertain whether the input signal must be Hi or Low logic to mute and whether it is continuity based logic or voltage based.

Example: If your satellite modem requires a Hi logic input (continuity or voltage) to cease transmissions you must select Hi.

There are numerous compliance laws (FCC and other worldwide entities) that mandate the ability and/or need to immediately mute transmit on a VSAT system when at least one of numerous predefined conditions are met. In most cases, these are conditions that ultimately determine that the system is not accurately pointed to the desired satellite. However there are some conditions where this may not be true, as is the case of the antenna being pointed at a pre-defined “Radiation Hazard Zone”, which discussed in detail within another chapter of this manual, is programmed in as a Blockage Zone, thus the name Block Output.

There may be an area on board the vessel in which crew and/or guests may be in the direct path of the terminals transmission to the satellite and might possibly be harmed by long term exposure to the microwave signal. This sector would be described as a blockage zone so that the transmissions from the antenna would cease when pointed in that area. Similarly a mast or other structure on the ship, directly in the beam path of the transmission, which would prevent transmitted signal from reaching the satellite and cause reflections which may degrade the signal or even be harmful to the antenna. These obstructions would also be described as a blockage zones. This similar in concept to “sector blanking” a radar array.

8.1.4.6. Modem I/O – Block Output – 12V Pull Up

Use: The Modem I/O Block Output 12V Pull Up selection defines whether or not use a built-in 12VDC Pull up resistor for the hard lined wire input for Blockage output (TX Mute).

If your modem requires a continuity based input (Short to ground is Low, and Open is High) this selection must be set to OFF. For all voltage based modem inputs, it MUST be set to ON.

Selection Type: Mutually Exclusive Radio Buttons

Options: 12V Pull Up OFF or ON.

Notes: Modem Type “Custom” must have been selected to allow changes to this setting.

Example: Your modem requires a high, voltage based, input to mute the modem. You would set Polarity to Hi and 12V Pull Up to ON.

If your modem required a low, continuity based, input to mute the modem. You would set Polarity to Low and 12V Pull Up to OFF.

8.2. Quick Reference: Common Modem Lock & Mute Settings

Modem Type	Compatible ABS Mode	Lock Input - Lock	Lock Input – Polarity	Lock Input – Voltage	Lock Input - 12V Pull Up	Block Output - Polarity	Block Output - 12V Pull Up
iDirect	OpenAMIP*	On	Low	12	Off	Hi	On
ComTech	ROAM*	On	Low	12	On	Low	On
Gilat	N/A	On	Low	12	Off	Low	Off
Hughes	N/A	On	Hi	12	Off	Hi	On
STM	N/A	On	Low	3	Off	Low	Off
Viasat	N/A	On	Low	12	Off	Low	Off
Custom	CLI*	On	As Required	As Required	As Required	As Required	As Required

***NOTE:** When interfacing ABS (via Ethernet connection) Lock input and Block Output selections have no operational impact.

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9. Setup – Targeting

Optimize the targeting of the antenna to track on or near a desired satellite (within +/- 1 degree).

9.1. AUTO TRIM

The Auto Trim function will automatically calculate and set the required Azimuth and Elevation trim offset parameters required to properly calibrate the antennas display to the mechanical angle of the antenna itself, while peaked ON satellite.

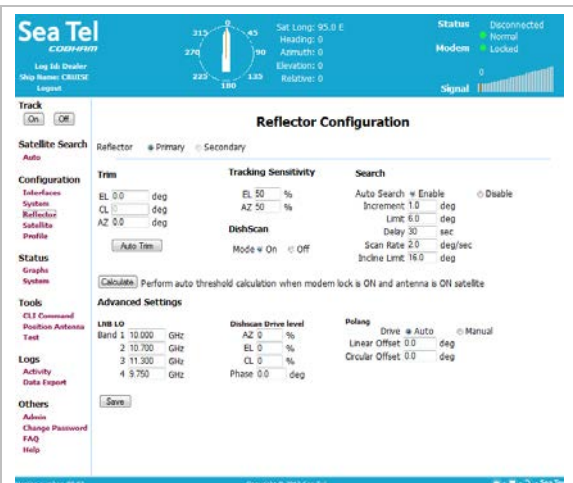
After locating the satellite, with Tracking ON, **wait at least 2 minutes** before performing the AUTO TRIM, this will allow sufficient time for the antenna to peak up on the satellite signal and for the targeting loops to completely stabilize. It is equally important that you verify that the system is tracking the CORRECT satellite (verify a RX lock indication on the satellite modem).



NOTE: The AUTO TRIM feature is NOT allowed unless all of these conditions are met:

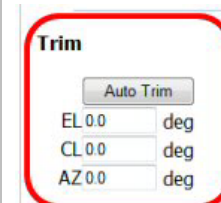
- The antenna must be actively tracking a satellite (AGC above threshold) **AND**
- The antenna must have positive SAT ID (RX lock input from the Satellite Modem) **AND**
- The elevation angle of the antenna must be LESS than 83 degrees **AND**
- The antenna must NOT be set for Inclined Orbit Search **AND**
- The system must NOT be set for “No Gyro” mode.

1. To activate the Auto Trim function go to the Reflector Configuration screen.



2. Click on the Auto Trim button.

This does not save these parameters to NVRAM, in order to save to memory, click the Save button.



3. Click SAVE

The screenshot shows the Sea Tel software interface with several configuration sections:

- Trim:** Includes fields for EL 0.0 deg, CL 0.0 deg, and AZ 0.0 deg, along with an 'Auto Trim' button.
- Search:** Includes 'Auto Search' (Enable/Disable), 'Increment' (1.0 deg), 'Limit' (6.0 deg), 'Delay' (30 sec), 'Scan Rate' (2.0 deg/sec), and 'Incline Limit' (16.0 deg).
- External Modem:** Includes 'Input polarity' (Low lock), 'Lock' (On), and 'Blockage output' (Low block).
- Tracking Sensitivity:** Includes 'EL 50 %' and 'AZ 50 %'.
- DishScan:** Includes 'Mode' (On/Off) and a 'Calculate' button for 'Perform auto threshold calculation'.
- Advanced Settings:** Includes 'LNBS LO' (Band 1, 10), 'Dishscan Drive level' (AZ 35 %, EL 20 %, CL 15 %, Phase 22.0 deg), and 'Polang' (Drive Auto, Mar).
- Save:** A button at the bottom left of the Advanced Settings section, highlighted by a large black arrow.

9.2. Manually Optimizing Targeting

1. First, assure that all of your Ship & Satellite settings in the MXP are correct.
2. Access the Satellite Search screen
3. Target the desired satellite by selecting it from the drop down list. You will see a message “Acquiring Satellite Signal...Please Wait” displayed.
4. Watch the Azimuth and Elevation values displayed in the center area of the banner and prepare to click the Track OFF button.

When targeting the antenna will initially drive to an elevation position that is 8 degrees above (or below if the elevation is greater than 83 degrees) the actual calculated position that the satellite should be at. After azimuth and polarization also finish driving, the elevation will drive to the actual elevation of the satellite

5. As soon as the elevation drives (up or down) 8 degrees click the Track OFF button and record the Azimuth and Elevation positions (these are the Calculated positions)..

6. Click Track ON button and allow the antenna to search, acquire and track the desired satellite.

As this happens you will see “Satellite Signal Found” and “Modem Lock: LOCKED” messages displayed. Select the Position Antenna screen., turn Tracking OFF and click Save.

7. After the antenna has been tracking for several minutes, record the Azimuth and Elevation positions of the antenna (these are the Peak positions).
8. Subtract the Peak Positions from the Calculated Positions to determine the amount of Trim which is required.

The screenshot shows the Sea Tel software interface with the following elements:

- Status Bar:** Displays 'Status' (Disconnected), 'Modem' (Normal), and 'Signal' (0).
- Central Display:** Features a compass rose showing azimuth and elevation values. Text on the right indicates 'Sat Long: 95.0 E', 'Heading: 0', 'Azimuth: 0', 'Elevation: 0', and 'Relative: 0'.
- Sidebar:** Includes sections for 'Track' (On/Off), 'Satellite Search' (Auto), 'Configuration' (Interfacing, System, Reflector, Satellite, Profile), 'Status' (Graphic, System), 'Tools' (CLI Command, Position Antenna, Test), 'Logs' (Activity, Data Export), and 'Others' (Admin, Change Password, FAQ, Help).
- Main Content Area:** Titled 'Satellite Signal Automatic Search', it shows 'Ship Position' (Latitude 0.000000 N, Longitude 0.000000 W, Heading 0.0) and a 'Satellite Selection' dropdown menu.

9. Access the Reflector Configuration page.

The screenshot shows the Sea Tel Reflector Configuration page. The top status bar indicates 'Disconnected', 'Normal', and 'Latched' status. The main configuration area includes sections for Trim, Tracking Sensitivity, Search, DishScan, Advanced Settings, and Tools. The Trim section is highlighted with a red box, showing fields for EL, CL, and AZ trim values.

10. Enter the Elevation Trim in the EL field.

11. Enter the Azimuth Trim in the AZ field.

This is a close-up of the Trim section from the previous screenshot. It shows the 'Auto Trim' button and three input fields: EL 0.0 deg, CL 0.0 deg, and AZ 0.0 deg. The entire section is enclosed in a red rectangular box.

12. Click Save.

13. Re-target the satellite several times to verify that targeting is now driving the antenna to a position that is within +/- 1.0 degrees of where the satellite signal is located.

This screenshot shows the same configuration page as before, but with a large black arrow pointing to the 'Save' button in the 'Advanced Settings' section. The 'Trim' and 'Search' sections are also visible, showing various settings for the reflector.

EXAMPLE: The antenna initially targets to an Elevation position of 38.0 degrees and an Azimuth position of 180.2. Shortly after that the Elevation drives to 30.0 degrees and Azimuth stays at 180.2 (Calculated), you find that Peak Elevation while ON your desired satellite is 31.5 degrees and Peak Azimuth is 178.0. You would enter an EL TRIM value of -1.5 degrees and an AZ TRIM of +2.2 degrees. After these trims values have been set, your peak "ON" satellite Azimuth and Elevation displays would be very near 180.2 and 30.0 respectively.

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10. Setup – Satellite Configuration

If you are using a remotely controlled ABS network control configuration (ie OpenAMIP, ROAM or legacy ABS direct connection to the MXP disregard this chapter as the network will make all changes in the MXP for the new beam or satellite to be used.

The values that these parameters are set to depends on the hardware configuration required for each satellite. Configure each of the satellites that airtime services will be provided on so that any one of them can be selected, remotely or by the user onboard. The satellite selection will in turn control the hardware on the antenna pedestal to select the correct TX & RX hardware and the correct tracking settings.

Sea Tel provides quad-band LNBs as standard on the Ku-Band feed assemblies.

10.1. Searching Patterns

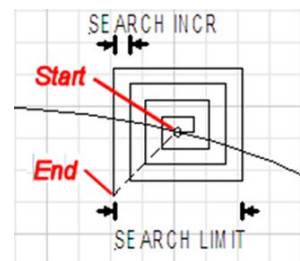
The MXP will initiate an automated search pattern after AGC falls below the current Threshold setting (indicates that satellite signal has been lost). The SEARCH DELAY parameter sets the amount of delay, in seconds that the MXP will wait after AGC has fallen below the threshold value before it starts a search. Below are the choices of patterns that each satellite can be set to.

10.1.1. Default “Spiral” (Box) Search Pattern

The factory default search pattern in the MXP is a “Spiral” pattern.

When a search begins;

The antenna will then search up in azimuth one Search Increment, search up one Search Increment in elevation, search down two Search Increments in azimuth, search down two Search Increments in elevation, etc until Search Limit is reached. When the end of the search pattern is reached, the MXP will retarget the antenna to the calculated Azimuth and Elevation position of the desired satellite (start point).



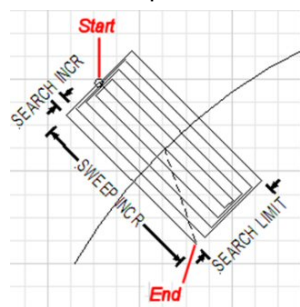
If the desired signal is found (AND network lock is achieved in the satellite modem) at this position, or anywhere within the search pattern, the MXP will terminate search and go into Tracking mode. If the desired signal is not found the MXP will wait SEARCH DELAY seconds and then begin the search pattern again. This cycle will repeat until the desired satellite signal is found or the operator intervenes.

10.1.2. Inclined Orbit Search Pattern

Some older satellites, in order to save fuel to keep them exactly positioned over the Equator, are in an inclined geosynchronous orbit. The satellite remains geosynchronous but is no longer geostationary. From a fixed observation point on Earth, it would appear to trace out a figure-eight with lobes oriented north-southward once every twenty-four hours. The north-south excursions of the satellite may be too far off the center point for a default box search pattern to find that satellite at all times during the 24 hour period.

When a search begins;

Initially the antenna will go to a calculated position that is half of SWEEP INCR degrees above, and perpendicular to, the satellite arc (along the same angle as polarization for the desired satellite). This position is the “Start” of the search pattern in the graphic above. Then the antenna will drive down along the polarization angle SWEEP INCR degrees, step one Search Increment to the right (parallel to the satellite arc), search up along the polarization angle SWEEP INCR degrees, step two Search Increments to the left, search down, etc expanding out in the search pattern until Search Limit is reached. When the end of the search pattern is reached, the MXP will retarget the antenna to the calculated Azimuth and Elevation point.



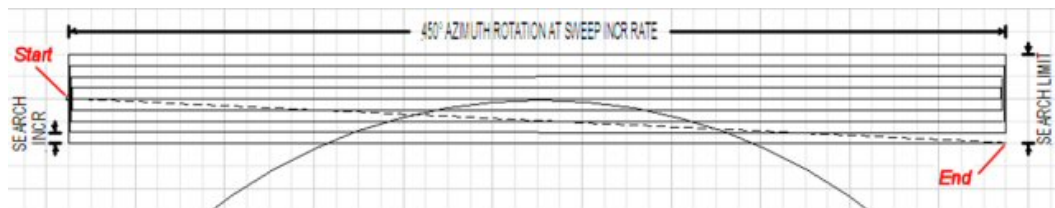
If the desired signal is found (AND network lock is achieved in the satellite modem) at this position, or anywhere within the search pattern, the MXP will terminate search and go into Tracking mode. If the desired signal is not found the MXP will wait SEARCH DELAY, then target the antenna to start point shown in the graphic above and begin the search pattern again. This cycle will repeat until the desired satellite signal is found or the operator intervenes.

10.1.3. Sky Search Pattern

A Sky Search pattern does a hemispheric pattern. Its behavior is different if you have a gyro compass input or not::

No Gyro - If you do not have gyro compass set the gyro type to “no gyro”. When in this mode, Sky Search drives the antenna to the calculated elevation angle and then drives azimuth CW 450 degrees, steps elevation up and then drives azimuth CCW 450 degrees and continues to alternately steps elevation up/down and drives azimuth alternately CW/CCW 450 degrees. Because of this large search area, acquiring the satellite will take longer than if you have valid heading input. If the end of the search pattern is reached, the MXP will retarget the antenna back to the start point shown in the graphic below.

With Gyro - If you have gyro compass set the gyro type to the appropriate selection. When in this mode, Sky Search drives the antenna to the calculated elevation angle and then drives azimuth CW **360** degrees, steps elevation up and then drives azimuth CCW **360** degrees and continues to alternately steps elevation up/down and drives azimuth alternately CW/CCW **360** degrees. Because of this large search area, acquiring the satellite will take less time because you have valid heading input. If the end of the search pattern is reached, the MXP will retarget the antenna back to the start point shown in the graphic below.



If the desired signal is found (AND network lock is achieved in the satellite modem) at any position within the search pattern, the MXP will terminate search and go into Tracking mode.

If the desired signal is not found within the search pattern the MXP will wait SEARCH DELAY seconds and then begin the search pattern again. This cycle will repeat until the desired satellite signal is found or the operator intervenes.

10.2. TX Pol select

Is used to select the transmit polarity of the C-Band Linear/Circular selectable feed, or the Ku-Band linear feed, whichever is currently installed.

10.3. Band select

Controls the band selection of the selected LNB (X-Pol or Co-Pol) on the Ku-Band linear feed ONLY. This setting works in conjunction with the X-Pol / Co-Pol selection setting.

10.4. X-Pol / Co-Pol select

Selects the desired (X-Pol or Co-Pol) on the Ku-Band linear feed ONLY. This setting works in conjunction with the band selection setting.

10.5. Selecting/Configuring Your Satellite Configuration

Choose a predefined satellite configuration or create a new one using the steps below.

The values that these parameters are set to depends on the hardware configuration required for each satellite. Configure each of the satellites that airtime services will be provided on so that any one of them can be selected, remotely or by the user onboard. The satellite selection will in turn control the hardware on the antenna pedestal to select the correct TX & RX hardware and the correct tracking settings.

Sea Tel provides quad-band LNBs as standard on the Series 12 Ku-Band antennas.

1. Access the Satellite Configuration screen.
2. If no satellites have been configured, or you need to add another, click Add Satellite.
3. Enter a name for this satellite you are creating.
4. Enter the Longitude position of this satellite.
5. Select the satellite that your airtime services will be provided on.

6. Determining the IF Tracking Frequency (MHz)

The IF Tracking frequency parameter is a value entered into the MXP MHz Sub-Menu. The value itself may be provided by your air-time provider and the MHz value will be entered directly in this sub-menu.

Or, the RF downlink frequency of a specific carrier on the desired satellite can be obtained from a satellite website and calculated by using the formula $RF - LO = IF$. When you take the Satellite Transponder Downlink RF value and subtract the LNB's Local Oscillator (LO) Value, the resultant value will equal the Intermediate Frequency (IF). It is this IF value that will be entered into the MXP for tracking purposes. The MHz and KHz are entered as a single value.

Example: Assuming an LNB LO value of 11.25GHz: We want to track a satellite downlink carrier at 12268.250 MHz.

$$12268.250 \text{ MHz} - 11250.000 \text{ MHz} = 1018.250 \text{ MHz IF}$$

7. Enter the entire six digits of the “megahertz and kilohertz” is simply entered as one value in the Frequency field.

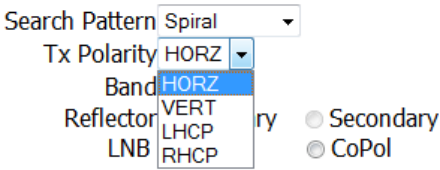
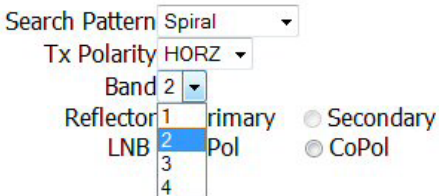
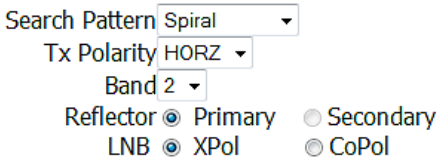
8. SAT SKEW

SKEW is used to optimize the polarization of the feed to the desired satellite signal. It is entered when a known satellite is skewed. Use Polang to peak the polarity.

9. Enter the known skew for this satellite in degrees, leave at zero if this satellite is not skewed.

Add Satellite


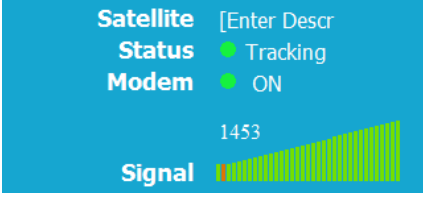
10. Select the desired type of search pattern to use for this satellite.

<p>11. Select desired TX Polarity from the drop down menu.</p>	
<p>12. Select desired Band from its drop down menu.</p>	
<p>13. Assure that reflector is set to “Primary”.</p> <p>14. Select Cross-Pol LNB (XPOL) or Co-Pol LNB (CoPol) as is appropriate for this satellite.</p>	
<p>15. Click the Save button to save this satellite.</p> <p>16. Repeat as necessary for all of the satellites that the system may need to use as the ship travels.</p>	

11. Quick Start Operation


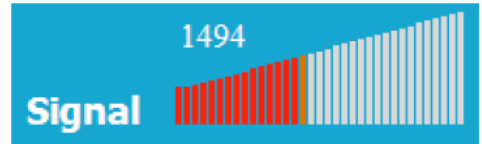
If your system has been set up correctly, and if the ship has not moved since the system was used last, the system should automatically acquire the satellite from a cold (power-up) start. Once the satellite has been acquired, the modem then should achieve lock and you should be able to use the system.

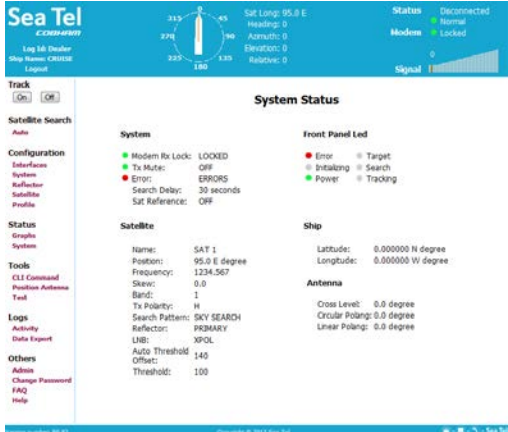
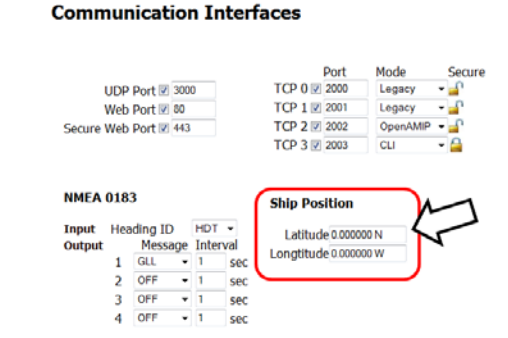
11.1. If satellite signal is found AND network lock is achieved:

<ol style="list-style-type: none"> Tracking will take over (front panel Tracking LED will be ON) and automatically peak the antenna position for highest receive signal level from the satellite. 	
<ol style="list-style-type: none"> When the ICU has signal above threshold AND modem has network lock the antenna will continue to track the satellite. Satellite Name (if entered), Tracking indicator, Modem Lock indicator and signal level (number value and bar graph) will be displayed in the header of the MXP GUI pages. 	
<p>Upon completion of the above, the system will continue to operate automatically, indefinitely until:</p> <ul style="list-style-type: none"> AC power to the system is interrupted OR The satellite signal is blocked OR The ship sails into an area of insufficient satellite signal strength/level. 	


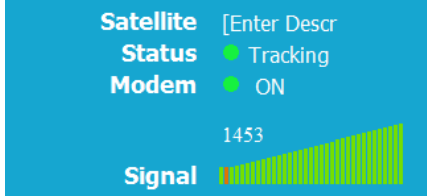
11.2. If no signal is found:

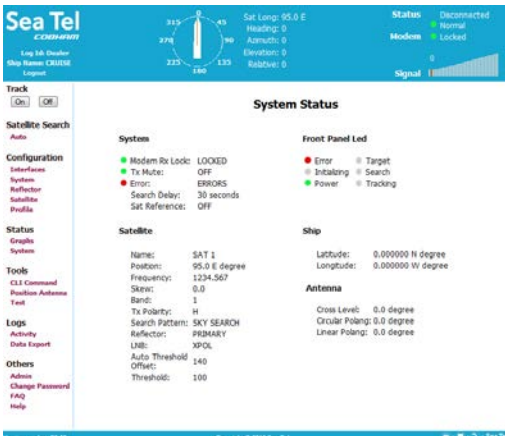
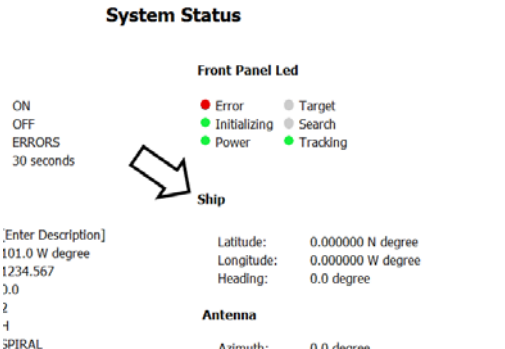
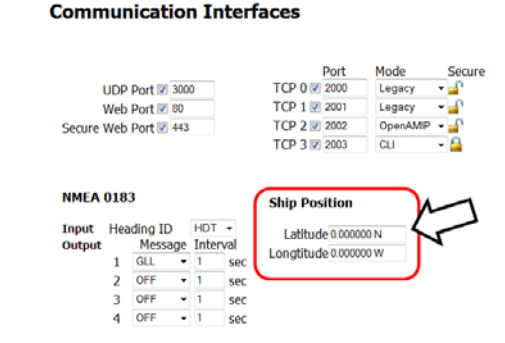
If the system does NOT automatically find the satellite from a cold start, follow the steps below:

<ol style="list-style-type: none"> The Tracking LED will flash for a short period of time (Search Delay) followed by the Search LED coming ON. The ICU will automatically move the antenna in the selected Search pattern until looking for a signal value that is greater than the threshold value (red bar in the bar graph). 	
<ol style="list-style-type: none"> Not finding a signal greater than Threshold, the bar graph will stay red and the antenna will reach the end of the prescribed search pattern. The antenna will retarget and the cycle will repeat (Search Delay timeout, conduct search pattern followed by retarget). 	

<ol style="list-style-type: none"> Check Latitude, Longitude and Heading. These should be correct, but may be updated if necessary. Access the System Status screen. Find the Latitude, Longitude (under Ship) and Heading (in the banner) displayed values. If they are correct skip to step 12. 	
<ol style="list-style-type: none"> If the Latitude & Longitude values are not correct, access the Communication Interfaces screen and enter the ships Latitude & Longitude position in the fields provided. If the Heading value is not correct, enter the correct value in the lower right field of the Communication Interfaces screen. If the system is set for NMEA or 1:1 type, you will not be able to enter a heading value. Click Save. 	
<ol style="list-style-type: none"> Check for blockage (this is the MOST common cause of not being able to acquire the desired satellite). Verify that the correct satellite is selected. Check cable connections to assure that a cable has not been disconnected. 	

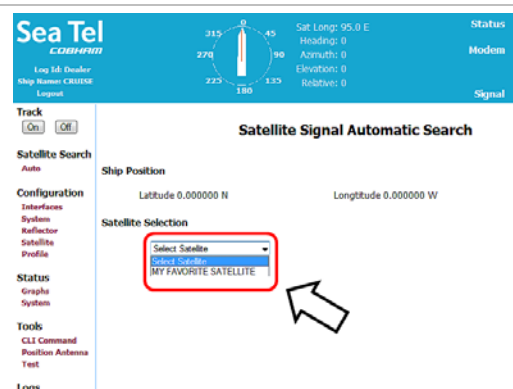
11.3. If satellite signal is found but network lock is NOT achieved:

<ol style="list-style-type: none"> The Tracking LED will flash for a short period of time (Search Delay) followed by the Search LED coming ON. 	
<ol style="list-style-type: none"> The ICU will automatically move the antenna in the selected Search pattern until it receives a signal value that is greater than the threshold value (red bar in the bar graph). If signal above Threshold is found, Tracking will take over (Tracking LED ON) and automatically peak the antenna position for highest receive signal level from the satellite which has been acquired. The system will wait for the modem to achieve lock. If the modem does not get lock, the antenna will resume its search pattern. 	

<ol style="list-style-type: none"> If the system does not acquire the correct satellite within the prescribed search pattern, the antenna will retarget and the cycle will repeat (Search Delay timeout, conduct search pattern followed by retarget). Check Latitude, Longitude and Heading. These should be correct, but may be updated if necessary. Access the System Status screen. 	
<ol style="list-style-type: none"> Find the Latitude, Longitude and Heading displayed values. If they are correct skip to step 11. 	
<ol style="list-style-type: none"> If the Latitude & Longitude values are not correct, access the Communication Interfaces screen and enter the ships Latitude & Longitude position in the fields provided. Click Save. 	
<ol style="list-style-type: none"> If the Heading value is not correct, enter the correct value in the lower left field of the Communication Interfaces screen. Click Save. 	
<ol style="list-style-type: none"> Check for blockage (this is the MOST common cause of not being able to acquire the desired satellite). Verify that the correct satellite is selected. Check for polarization drive failure. Check for improper polarization alignment/position. 	
<ol style="list-style-type: none"> Check cable connections to assure that a cable has not been disconnected. Verify that the modem option file is correct. Check the modem for failure. 	

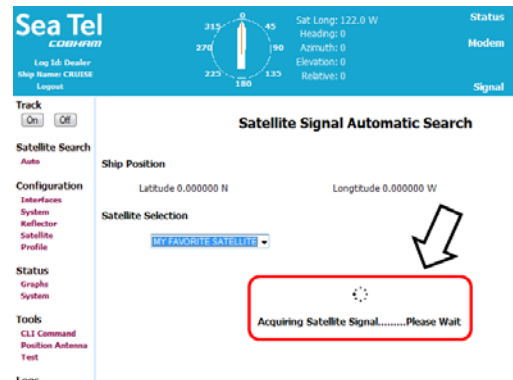
11.4. To Target a different satellite

1. To target a different satellite go to the Satellite Search Auto screen and select the desired satellite from the drop down list.



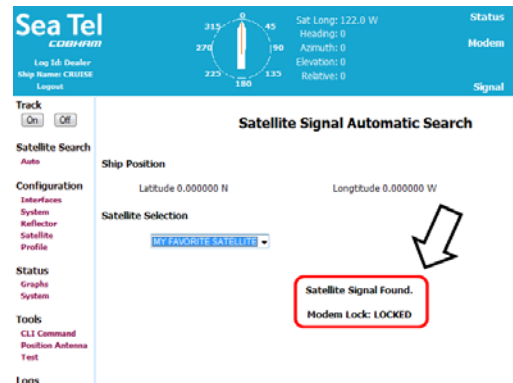
2. When you make that selection you will see the temporary message:

Acquiring Satellite Signal...Please Wait



3. Shortly after that you will see the temporary message:

Satellite Signal Found.
Modem Lock: LOCKED



12. Optimizing Cross-Pol Isolation

Now that all of the other setup items have been checked and changed as necessary, it is time to contact the NOC to arrange for cross-pol isolation testing and whatever other commissioning the NOC asks for. Read this procedure thoroughly before you are asked to begin. Assure that you are on the correct satellite and have RX network lock. (the NOC may have you adjust TX Frequency and/or modem TX level prior to beginning cross-pol isolation). At the appointed time follow the steps below for the cross-pol isolation testing.

12.1. Optimizing Cross-Pol Isolation

1. Access the Tools - Position Antenna screen.

NOTE: You will use Skew to optimize polarization because it drives the feed immediately (Linear Offset is slower, longer term drive).

2. Record the value in the Skew field in the upper section of the screen. If this satellite has a known Skew, it will be entered in the satellite configuration displayed here. If this satellite is not skewed this field will be 0.0.
3. While talking to the technician at the NOC make adjustments to the Skew value to adjust polarity of the feed under his/her direction (minus values are accepted – type a minus sign before the number value). It is best to adjust in one degree increments to get close to best isolation and then half degree steps and then tenths as needed. Click “Submit” after each numeric change is typed in.
4. Record the DIFFERENCE in Skew value which was required to achieve optimum cross-pol isolation.
5. Set Skew back to the value recorded in step 2.

6. Access the Reflector Configuration screen.
7. Change the “Linear Offset” value by the amount of difference recorded in step 4.

Examples:

Skew was 0.0, you increased it to 2.5 to optimize TX polarization. You set Skew back to zero and go to the Reflector Configuration screen where you find Linear Offset to be 0.0, so you increase Linear Offset to 2.5 degrees and click **Save**.

Skew was 3.0, you decrease it to 1.0 to optimize TX polarization. You set Skew back to 3.0 and go to the Reflector Configuration screen where you find Linear Offset to be 0.0, so you set Linear Offset to minus 2 (-2.0) degrees and click **Save**.

8. Double check with the NOC to assure that cross-pol is still optimized.
9. Conduct any other testing as directed by the NOC (ie P1dB compression).

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13. Stowing the Antenna

This antenna must be properly stowed if the ship will be underway while AC power to the Above Decks Equipment (ADE) is de-energized. Failure to do so may void your warranty.



CAUTION: There are three stow restraints that **MUST** be installed on this antenna pedestal if the ship will be underway while the Above Decks Equipment is de-energized.

It is strongly recommended that AC Power to the ADE and BDE be supplied from an adequately rated Un-interruptible Power Supply (UPS) to protect the antenna against short power outages while underway.

13.1. Installing the Stow Restraints

The order the restraints are installed is not critical.

13.1.1. Installing the AZ Shipping/Stow Restraint

<ol style="list-style-type: none"> 1. The AZ shipping/stow restraint is formed by a pin bolt that is lowered into a channel in a stowage block on the upper plate of the pedestal (as shown). 	
<ol style="list-style-type: none"> 2. Remove the pin bolt from the "STOW" hole (this only stows the pin bolt, not the antenna). 3. Rotate the antenna to center the LOCK hole directly over the stow block channel. <p>Pin bolt (this is the UN-Stowed position of the antenna)</p> <p>Stow Block Channel</p>	
<ol style="list-style-type: none"> 4. To restrain azimuth rotation of the antenna, install the pin bolt in the "Lock" hole and assure that the pin drops into the channel in the stow block below. 5. Verify that the stow pin is engaged in the channel of the stow block and that the antenna does NOT rotate in azimuth. 	

13.1.2. Installing the EL Shipping/Stow Restraint

1. The EL shipping/stow restraint is formed by a stow pin-bolt mounted through a bracket and is engaged into a hole/slot in the elevation driven sprocket when the dish is at zenith (90 degrees elevation).
2. In the un-stowed position the hardware from left to right is the stow pin-bolt head, hex nut, washer, bracket, washer, hex nut. So the pin section of the stow pin-bolt is **NOT** inserted into the hole in the elevation driven sprocket.

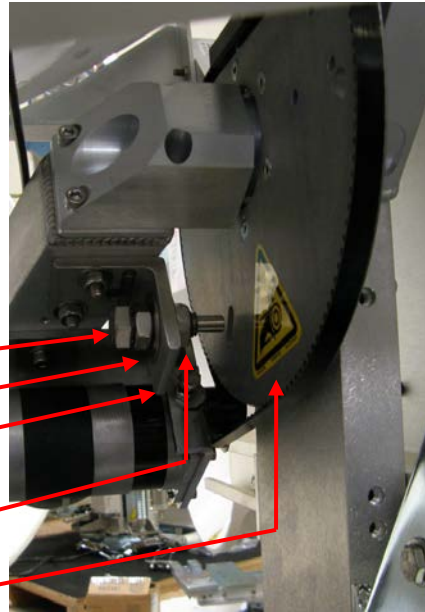
EL Stow Pin-Bolt head

Hex Nut & Washer

Bracket

Washer & Hex Nut

Elevation Driven Sprocket



3. To restrain the elevation axis of the antenna, unthread the hex nut nearest the elevation driven sprocket. Using a $\frac{3}{4}$ " open end wrench, remove the hex nut and washer from the stow pin-bolt.
4. Remove the stow pin-bolt from the bracket.



5. Remove the washer from the stow pin-bolt and unthread the hex nut from the bolt.
6. Put one of the washers onto the stow pin-bolt and insert it into the bracket toward the elevation driven sprocket.
7. Put the other washer, and then thread the two hex nuts onto the bolt.


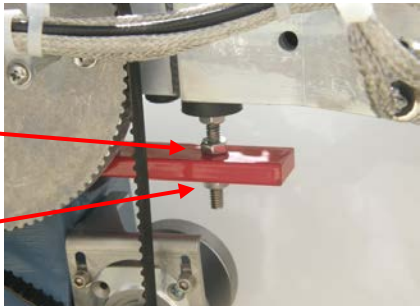


8. Tighten the hex nuts to prevent the hardware from loosening while in the stowed configuration.
9. Verify that the antenna does not rotate in elevation.




13.1.3. Installing the CL Shipping/Stow Restraint

1. The CL shipping/stow restraint is formed by a red locking bar with adjustable bumpers at each end of the bar. This mechanism is placed under the cross-level beam to lock it in place (at level).

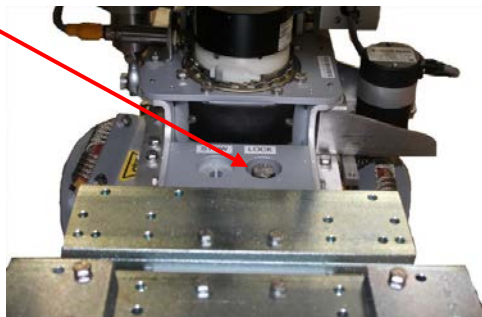
<ol style="list-style-type: none"> 2. If not already removed, remove an adjustable bumper by removing the bottom nut from one end of the locking bar. 3. If not already loosened, loosen the top nut up toward the rubber bumper. 4. Insert vacant end of the locking bar through the opening under the cross-level beam. 5. Insert the adjustable bumper into the vacant hole on the end of the locking bar. 	
<ol style="list-style-type: none"> 6. To restrain the cross-level axis of the antenna use a 7/16" open end wrench to tighten the nut on the top side of the locking bar until the rubber bumper is forced up against the bottom of the cross-level beam. 7. Verify that the antenna does NOT rotate (tilt left & right from level). 8. Re-install and tighten the bottom nut on the underside of the locking bar. 	

13.2. Removing the Shipping/Stow Restraints PRIOR to Power-Up

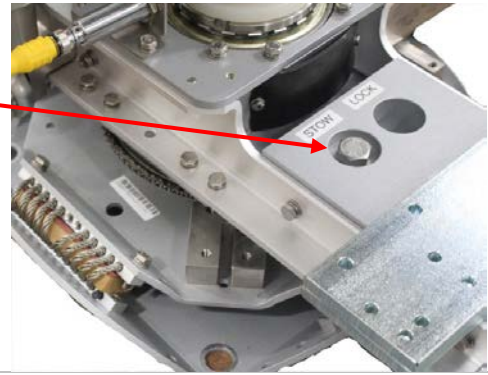
The order the restraints are removed is not critical.

	<p>CAUTION: There are three shipping/stow restraints on this antenna pedestal that MUST be removed, before energizing the antenna, for normal operation.</p>
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13.2.1. Removing the AZ Shipping/Stow Restraint

<ol style="list-style-type: none"> 1. The AZ shipping/stow restraint is formed by a pin bolt that is lowered into a channel in a stowage block on the upper plate of the pedestal (as shown). 	
<ol style="list-style-type: none"> 2. To un-stow the antenna, remove the pin bolt from the LOCK position. 	

3. Install the pin bolt into the STOW hole and tighten. This assures that it does not get lost and will be ready for re-use if the antenna needs to be stowed again at a later date.
4. Verify that the antenna is able to rotate freely in azimuth.



13.2.2. Removing the EL Shipping/Stow Restraint

1. The EL shipping/stow restraint is formed by a stow pin-bolt mounted through a bracket and is engaged into a hole/slot in the elevation driven sprocket when the dish is at zenith (90 degrees elevation).
2. In the stowed position, the hardware from left to right is stow pin-bolt head, washer, bracket, washer, hex nut, hex nut so that the pin section of the stow pin-bolt is inserted into the hole in the elevation driven sprocket.

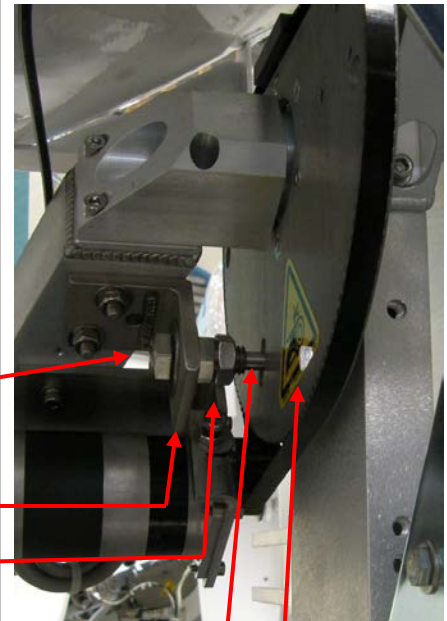
EL Stow Pin-Bolt head

Bracket

2 Hex Nuts

Pin inserted into Elevation Driven Sprocket

Elevation Driven Sprocket



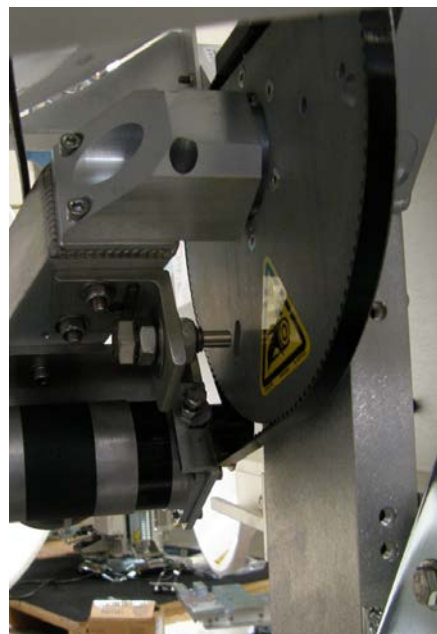
3. To un-restrain the elevation axis of the antenna, unthread the two hex nuts. Using a $\frac{3}{4}$ " open end wrench, remove the hex nuts and washer from the stow pin-bolt.
4. Remove the stow pin-bolt from the bracket.



5. Remove the washer from the stow pin-bolt and thread one of the two hex nuts onto the bolt and tighten.
6. Put one of the washers onto the stow pin-bolt and insert it into the bracket toward the elevation driven sprocket.
7. Put the other washer, and then the other hex nut onto the bolt.



8. Tighten the hex nut to prevent the hardware from loosening while in the un-stowed configuration.
9. Verify that the antenna rotates freely through its full elevation range of motion.



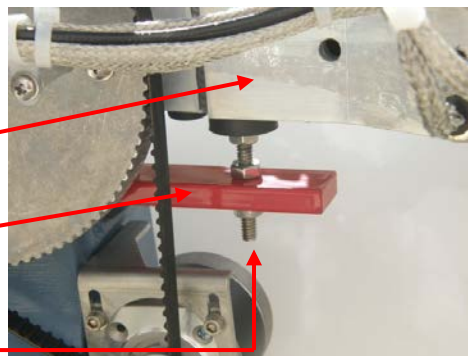
13.2.3. Removing the CL Shipping/Stow Restraint

1. The CL shipping/stow restraint is formed by a red locking bar with adjustable bumpers at each end of the bar. This mechanism is placed under the cross-level beam to lock it in place.

Cross-Level Beam

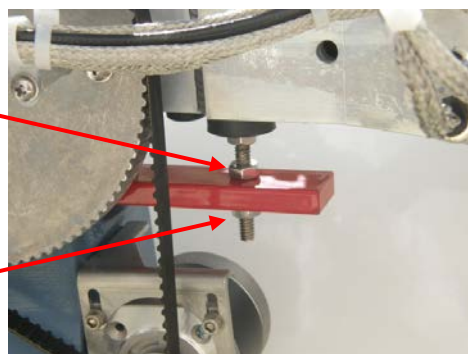
CL Shipping/Stow bar

Adjustable CL Locking Bumpers (only one end shown)



2. To un-restrain the cross-level axis of the antenna use a 7/16" open end wrench to loosen the nut on the top side of the locking bar (either end of the bar).

3. Remove the bottom nut off of that adjustable bumper.
4. Remove the adjustable bumper from the locking bar.



<ol style="list-style-type: none">5. Extract the locking bar from the underside of the cross-level beam and retain these parts for later re-use if it becomes necessary to stow the antenna.6. Verify that the antenna rotates (tilts left and right from level) freely through its full cross-level range of motion.	
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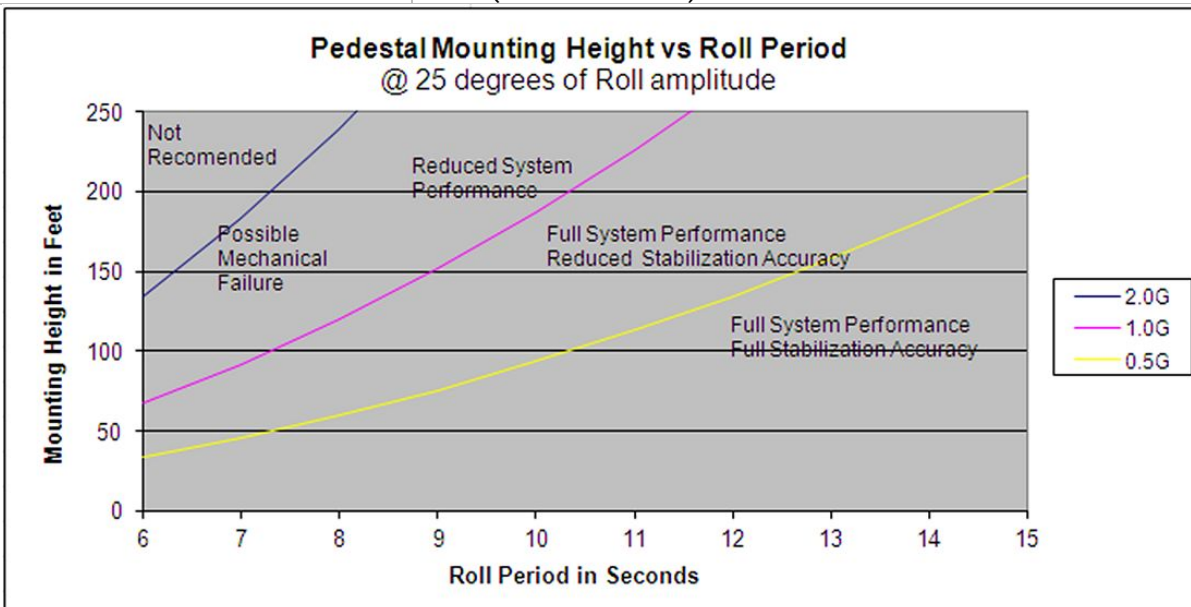
14. 6012-36 Technical Specifications

The specifications of your antenna system are below.

14.1. Above Decks Equipment

System Weight (ADE)	
Weight	216 kg / 276 lbs (76 in radome)
Stabilized Antenna Pedestal Assembly	
Type	Three-axis (Level, Cross Level and Azimuth)
Stabilization	Torque Mode Servo / Two Axis W/Pol
Stability Accuracy	0.1° RMS, 0.2° peak in presence of specified ship motions (see below).
Azimuth Motor	Size 23 Brushless DC Servo, Double Stacked W/Encoder
Level Motor	Size 23 Brushless DC Servo W/Brake
Cross Level Motor	Size 23 Brushless DC Servo W/Brake
Inertial Reference	3 Solid State Rate Sensors
Gravity Reference	2 MEMS Tilt Sensors
AZ transducer	256 line optical encoder / home switch
Pedestal Range of Motion:	
Elevation Joint Angle	-15° to +115°
Cross Level (Inclined 30°)	+/- 35°
Azimuth	Unlimited
Elevation Pointing	10 to 90 degrees at 25 degrees roll
	5 to 90 degrees at 20 degrees roll
	0 to 90 degrees at 15 degrees roll
Relative Azimuth Pointing	Unlimited
Maximum Ship Motions	
Roll	+/-25° at 8-12 sec periods
Pitch	+/-15° at 6-12 sec periods
Yaw	+/-8 degrees at 15-20 sec periods
Turning rate	Up to 12 deg/sec and 15 deg/sec/sec
Headway	Up to 50 knots
Heave	0.5G
Surge	0.2G
Sway	0.2G

Specified Ship Motion (for stability accuracy tests)	
Roll	+/- 20° at 8 second period
Pitch	10° Fixed
Relative Azimuth (Heading)	0, 45 and 90° with respect to roll input
Mounting Height	Sea Tel recommends you do not exceed tangential accelerations of 0.5G (See below chart)



Antenna Reflector Ku-Band	
Type	Spun Aluminum
Diameter	1.47 m / 58"
TX Gain	45.1 dBi @ 14.25 GHz
RX Gain	44 dBi @ 12.50 GHz
G/T (30° elevation, clear sky)	21.9 dB/k (In Radome, typical)
FCC Input Power Spectral Density Limitation	-14.0 dBW / 4 KHz
Minimum EIRP (TVRO)	NA

KU-band Feed	
Type	Center Focus Cassegrain feed with TX reject filter and Cross-Pol OMT
Port to Port Isolation (Xpol)	> 120 dB
Port to Port Isolation (copol)	> 90 dB
Cross Pol Isolation	> 35 dB typical (30dB within 1dB contour)
Polarization	Linear w/motorized skew adjustment
Polarization Control	24 volt DC motor with pot feedback
Polarization Range of Motion	270 degrees
Receive Frequency Range	10.70 - 12.75 GHz
Transmit Frequency Range	13.75 - 14.50 GHz

KU-band TX Radio Package	
SSPB	Codan 8 Watt LBUC 6908-W/E-48/EX-CE-NI
Output Flange	WR-75
Input Connector	Type N
RF Input Frequency Range	950 to 1700 MHz
RF Output Frequency Range	13.75-14.5 GHz
RF Output VSWR	1.5:1 max
RF Pout@ 1 dB GCP	39.0 dBm (8 Watt BUC)
Reference Frequency Level	-10 to +5 dBm
Reference Frequency	10 MHz ext
M&C Options	RS-232
Step attenuator	1db Increments
Alarms	Lock, Over Temp, Temperature
Co-Pol Diplexer	
Type:	DPX75K-002
Common Port (to feed)	WR-75 Flange, 10.70-14.5 GHz
Transmit Output (from SSPB)	WR-75 Flange, 13.75-14.5 GHz
Receive Output (to Co-Pol LNB)	WR-75 Flange, 10.70-12.75 GHz
Co-Pol LNB	Refer to LNB spec
LNB, KU-Band PLL	
NJR2535S - 122188-1	
Voltage Required	15VDC to 24VDC
Input RF Frequency	11.70 to 12.20 GHz
Local Oscillator Frequency	10.75 GHz
Output IF Frequency	950 - 1,450 MHz
Stacker	
Input: (2 ea)	
Frequency	950 to 1450 MHz
Level	-30 to -40 dBm per transponder
Input Return loss	950 MHz = -12dBm to 1450 MHz = -10dBm
Loss	
Even transponders	(Stacked) 3 dB
Odd transponders	(Non-Stacked) 6 dB
Voltage	
Odd input	13 +/- .5 Volts DC
Even input	Same as voltage applied to the output
Current	
Odd input	200 mA max from this output
Even input	500 mA max

Output	
Frequency	950 to 2050 MHz (Even transponders stacked 1550 to 2050)
Band flatness	950 to 2050 MHz (any 20 MHz) min +/-1 max +/-5 dB
	950 to 2050 MHz min +/-1 max +/-2 dB
Return loss	950 to 1450 and 1550 to 2050 MHz min -11 max -8 dB
2nd harmonic rejection	1150 MHz > 40 dBc
3rd Harmonic rejection	1725 MHz > 6 dBc
Voltage	20 VDC (Applied to the output)
LO Frequency	575 MHz +/- 30 KHz
Power Supply (ADE / PCU / ICU)	
A/C Input Voltage	85-264 VAC, 47-63Hz, single phase
Voltage	48VDC [24 VDC, 150W (QTY 2)]
Wattage	300W (total)
Current Capacity	13.0A (total)
Power Supply (BUC)	
A/C Input Voltage	85-264 VAC, 47-63Hz, single phase (see ADE power below).
GPS (On Board)	
Waterproof	IPX7
Operating Temperature	-30°C to +60°C
Storage Temperature	-40°C to +60°C
Humidity	Up to 95% non-condensing or a wet bulb temperature of +35°C
Altitude	-304m to 18,000m`
Vibration	IEC 68-2-64
Shock	50G Peak, 11ms
Connector	RJ11
Input Voltage	
Min	4.75VDC
Typ	5.0VDC
Max	5.25VDC
NMEA output messages	GGA, GLL
Refresh Rate	1s

Integrated Control Unit (ICU)	
Connectors	
J1	SMA (F) - RXIF Input from LNB 1 (Cross-Pol)
J2	SMA (F) - RXIF Input from LNB 2 (Co-Pol)
J3	SMA (F) - RXIF Output To Rotary Joint
J4 B/A	Ethernet - RJ45 Serial M&C - A=Radio M&C, B=Pass through
J5	Mini USB Antenna M&C
J6	DE-9 (F) - Serial Console - Antenna Serial M&C
J7	DE-9 (F) - Serial Radio M&C
J8	RJ-11 (F) - GPS Antenna Input
J9	DE-15 (F) - Motor Control to MDE
J10	DE-25 (F) - Feed Harness Connection
J14	DE-9 (F) - Serial Pass through M&C
J16	F (F) - TXIF Output to BUC
J19	M16 (F) - Power Supply DC Voltage Output to BUC
J20	Modular AC Power Input Receptacle
Status LEDs	Diagnostic Status of the EoC
	Diagnostic Status of the ICU
AC Input Power	85-264 VAC, 47-63Hz, single phase, 2A-1A
Coax Switch	
LNB-A (J1)	SMA (F)
LNB-B (J2)	SMA (F)
Rotary Joint (J3)	SMA (F)
Controls	Configurable from GUI
Integrated SCPC Receiver	
Tuning Range	950 to 1950 MHz in 1 KHz increments
Input RF Level	-85 to -25dBm typical
Output RF Level	Input level +/- 1dB typical
Sensitivity	30mV/dB typical (25 counts/dB typical)
Bandwidth (3dB)	150 KHz
Interfaces	
Modem/MXP M&C Interface	OpenAMIP & Legacy
Network Interface	4-port managed fast ethernet switch
User Interface	Web Browser/Console Port

Motor Driver Enclosure	
Connectors	
Drive	DA-15P
Home	DE-9S
AZ	DA-15S
EL	DA-15S
CL	DA-15S
Status LEDs	
CL Drive	Yes
EL Drive	Yes
Az Drive	Yes
MDE Status	Yes
Interface Connections	
Connection	Dual Channel Rotary Joint
Power Requirements	
ADE	85-264 VAC, 47-63Hz, single phase (MAX below = brake release, pedestal drive and BUC drive). 25W = 660 Watts MAX
Radome Assembly (76 Inch)	
Type	Frequency Tuned
Material	A sandwich
Size	
Diameter	1.93 m / 76" (2.01m max flange diameter)
Height	1.61 m / 63.44"
Hatch Size	11.5" x 22" curved (approx)
Weight	90.7 kg / 200 lbs
RF attenuation	Less than 0.2 dB @ 10.75-14.5 GHz dry
Wind:	Withstand relative average winds up to 56m/sec (125 MPH) from any direction.
Ingress Protection Rating	IP 56
ADE Environmental Conditions	
Temperature Range (Operating)	-25° to +55° Celsius (-13° to +131° F)
Humidity	100% Condensing
Wind Speed	56 m/sec (125 mph)
Solar Radiation	1,120 Watts per square meter, 55° Celsius
Spray	Resistant to water penetration sprayed from any direction.
Icing	Survive ice loads of 4.5 pounds per square foot. Degraded RF performance will occur under icing conditions.
Rain	Up to 101.6mm (4 inches) per hour. Degraded RF performance may occur when the radome surface is wet.
Corrosion	Parts are corrosion resistant or are treated to endure effects of salt air and salt spray. The equipment is specifically designed and manufactured for marine use.

Mechanical Conditions	
Systematic Vibration	
Amplitude (single peak)	5.0 millimeters
Acceleration	2.0 G (20m/s ²)
Frequency Range	1Hz - 150Hz
Shock (Transient Vibration)	
Response Spectrum	I - II - III
Peak Accel., m/s ²	100 - 300 - 500
Duration, ms	11 - 6 - 3
Number of Cycles	3 each direction
Directional Changes	6
Shock (Bump)	
Peak Accel., m/s ²	250
Duration, ms	6
Number of Cycles	100 ea. direction
Directional Changes	6
Transit Conditions	
Drop (Transit Shock)	Complies with ISTA Standard
Chemically Active Substances	
Environmental Condition	Test Level
Sea Salt	5 percent solution

14.2. Below Decks Equipment

Media Xchange Point (MXP)	
Standard 19 Inch Rack mount	One Unit High
Physical Dimensions	17 X 17 X 1.75 (Inches)/ 43.18 x 43.18 x 4.45 (cm)
Input Voltage	85-264 VAC, 47-63Hz, single phase, 110 Watts
Weight	6.6lbs/ 3.0 kgs
Front Panel	
	4 Modem LEDs (On the MXP Board)
	2 MXP status LEDs

Rear Panel Connections	
AC Input	Modular AC Power Input Receptacle
J1	SMA (F) - RXIF Output to Satellite Modem
J2	SMA (F) - RXIF Input from ADE
J3 B/A	Ethernet - 2 ports of the 4 Port 10/100 Ethernet Switch 10.1.1.100
J4 B/A	Ethernet - 2 ports of the 4 Port 10/100 Ethernet Switch 10.1.1.100
J5	SFP Gigabit Ethernet
J6	Mini USB Antenna M&C
J7	USB Host (Type A) - N/C - Future Development
J8	DE9 (F) - Serial Console - Antenna Serial M&C
J9 A/B	RJ45 Serial M&C - A=Radio M&C, B=Pass through
J10 C/D	RJ45 Serial M&C - C=Modem, D=OBM
J11	Terminal Strip - Gyro Compass (SBS-Synchro) Interface Terminals
J12	Terminal Strip - Auxiliary Interface Terminals
J13	DE-9 (M) - NMEA 0183 Interface Port
J14	DE-9 (M) - AUX (RS-232) Interface Port
J15	NMEA 2000 Interface Port - Future Development
Gyro Compass Interface	
Connections	Plug-in Terminal Strip
Pin 1	Synchro R1
Pin 2	Synchro R2
Pin 3	Synchro S1 / SBS A
Pin 4	Synchro S2 / SBS B
Pin 5	Synchro S3 / SBS C
Pin 6	SBS COM
Synchro Interface	
Connectors	5 screw terminal connections (Plug-In)
Input Voltage Level	36-110 VDC, 400 or 60 Hz
Synchro Ratios	1:1, 36:1, 90 or 180:1 and 360:1
Impedance	1M ohm
SBS Interface	
Connectors	4 screw terminal connections (Plug-In)
Input Voltage Level	20-90 VDC
Interface	Opto-isolated
Polarity	Auto switching
Ratio	6 steps per degree
Impedance	10K Ohm

Auxiliary Interface	
Connections	Plug-in Terminal Strip
Pin 1 - GND	Ground
Pin 2 - Aux IN1	Modem Lock Input 1
Pin 3 - Aux IN2	Modem Lock Input 2
Pin 4 - GND	Ground
Pin 5 - SW1	Modem Mute Output 1
Pin 6 - SW2	Modem Mute Output 2
Pin 7 - SW3A	Dry Contact set 1
Pin 8 - SW3B	Dry Contact set 1
Pin 9 - SW4A	Dry Contact set 2
Pin 10 - SW4B	Dry Contact set 2
External AGC (AUX Inputs)	
Connectors	2 screw terminal connections
Input Voltage Level	0-5 VDC
Impedance	30K Ohm
Control (Logic Sense can be reversed)	Low Level (<1.25VDC) = Modem Lock :: High Level (>1.25 VDC) = Modem Unlock
SW1 Blockage / TX Mute Output	
Connections	1 screw terminal connection (SW1)
Connections	1 screw terminal connection (SW2)
Control Level	Not Blocked or Not mispointed=OPEN circuit
	Blocked or mispointed=SHORT to ground
SW2 Blockage / TX Mute Output	
Connections	1 screw terminal connection (SW2)
Control Level	Not Blocked or Not mispointed=OPEN circuit
	Blocked or mispointed=SHORT to ground
Dry Contact Output Sets (SW3 A-B & SW4 A-B)	
Switched outputs	4.7K pull up or Pull Down
Current handling	Current sink of 0.5 amps max.
No Alarm State	Normally Open
Alarm State	Contact closure
NMEA 0183 Interface	
Connections	5 screw terminal connections (RXA+ /RXA- input, RXB+/ RXB- input, and TXA+ output)
Rx Sentence Format (GPS)	\$xxGLL,DDmm,mmmm,N,DDDmm.mmmm,W (UTC optional) (*CS optional)
Rx Sentence Format (Gyro)	Heading \$xxHDT,xxx.x
Tx Sentence Format (GPS)	\$GPGGA,0,DDmm,N,DDDmm,W (configurable)

NMEA string examples:	
RX:	
\$GPGLL,3800.4300,N,12202.6407,W,231110,A*32	
\$GPGGA,231110,3800.4300,N,12202.6407,W,2,08,1.2,40.0,M,-31.3,M,,*4A	
TX:	
\$GPRMC,231325,A,3800.4300,N,12202.6405,W,000.0,184.9,190412,014.1,E*67	
\$GPVTG,184.9,T,170.8,M,000.0,N,0000.0,K*74	
BDE Environmental Conditions	
Temperature	0 to 40 degrees C
Humidity	Up to 100% @ 40 degrees C, Non-Condensing

14.3. Regulatory Compliance

Survival Shock and Vibration	IEC-60721, MIL-STD-901D
Operational Shock and Vibration	Operational: IEC-60945, Survival: IEC-60721 and MIL-STD 901D
	MIL-STD-167-1
EMI/EMC Compliance Ku-Band	ETSI EN 301 843-1 V1.4.1 (2004-06)
	ETSI EN 301 489-1 V1.4.1 (2002-08)
	ETSI EN 300 339 (1998-03)
	IEC EN 60945:1997
Satellite Earth Stations and System (SES)	ETSI EN 301 428-1 V1.3.1 (2006-02)
	ETSI EN 302 340 V1.1.1 (2006-04)
Safety Compliance	IEC EN 60950-1:2001 (1st Edition)
Environmental Compliance	RoHS
	Green Passport
FCC ESV Compliance C-Band	NA
FCC ESV Compliance Ku-Band	47 C.F.R. § 25.222
FCC ESV Compliance Ka-Band	NA
Options	Bluetooth

14.4. Cables

14.4.1. Antenna L-Band IF Coax Cables (Customer Furnished)

Due to the loss across the length of the RF coaxes at L-Band, Sea Tel recommends the following 50 ohm coax cable types (and their equivalent conductor size) for our standard pedestal installations. Type N male connectors installed on the cables MUST be 50 Ohm connectors for the center pin to properly mate with the female adapters we provide on the cable interconnect brackets inside the radome and at the below decks equipment.

The coaxes must be continuous from the connection within the ADE radome, through the structure of the ship to the BDE. Splices, adapters or dummy connections will degrade the signal level and are discouraged.

Assure that the cable type that you choose has a loop resistance of less than 2.0 ohms across the entire cable run. Copper clad iron center conductor cables should never be used.

Run Length	Coax Type	Typical. Loss @ 1750Mhz	Shield isolation	Center Conductor Size	Installed Bend Radius	Tensile Strength
<100 ft	LMR-240	10.704 db per 100 ft(30.48 m)	>90db	0.056 In. (1.42 mm)	2.5 In. (63.5 mm)	80lb (36.3 kg)
up to 150 ft	LMR-400	5.571 db per 100 ft(30.48 m)	>90db	0.108 In. (2.74 mm)	4.0 in. (101.6 mm)	160lb (72.6 kg)
up to 200 ft	LMR-500	4.496 db per 100 ft(30.48 m)	>90db	0.142 In. (3.61 mm)	5.0 In. (127 mm)	260lb (118 kg)
Up to 300 ft	LMR-600	3.615 db per 100 ft(30.48 m)	>90db	0.176 In. (4.47 mm)	6.0 In. (152.4 mm)	350lb (158.9 kg)

14.4.2. Multi-conductor Cables (Customer Furnished)

Due to the voltage losses across the multi-conductor cables, Sea Tel recommends the following wire gauge for the AC & DC multi-conductor cables used in our standard pedestal installations:

Run Length	Conductor Size
up to 50 ft	20 AWG (0.8 mm)
up to 100 ft	18 AWG (1.0 mm)
up to 150 ft	16 AWG (1.3 mm)
up to 250 ft	14 AWG (1.6 mm)
Up to 350 ft	12 AWG (2.0 mm)

14.4.3. AC Power Cable Above Decks (Customer Furnished)

Voltage:	110 or 220 volts AC, 50/60 Hz., single phase
Type:	Multi-conductor, Shielded
Number of wires	3 Conductors
Wire Gauge:	Use proper wire gauge for the length of the power cable run.
Insulation:	600 VAC

14.4.4. Gyro Compass Interface Cable (Customer Furnished)

Type:	Multi-conductor, Shielded
Number of wires	4 Conductors for Step-By-Step Gyro, 5 Conductors for Synchro
Wire Gauge:	see Multi-conductor Cables spec above
Insulation:	600 VAC

15. DRAWINGS

15.1. Model Specific Drawings

Drawing	Title	
40-300135	System, 6012-36 in 76" Radome	15-3
DL-150520-A	System Block Diagram, 6012-36, Ku-Band	15-5
93-150519-A	Antenna Schematic, xx12-36	15-10
137389_A2	Pedestal Schematic, xx12	15-11
69-150515	General Assembly 6012-36	15-12
138658-1	Mounting Assembly, ICU	15-16
130387-1	Mounting Assembly, BUC	15-18
62-146667	Antenna Assembly	15-20
62-148767	Waveguide Assembly	15-22
133659-1	76" Radome Assembly, Tuned	15-24
125749_D	Installation Arrangement, 76" Radomes	15-28
131226_A	Procedure, Radome Strain Relief Installation	15-29
134563-1_D	Below Decks Kit, MXP	15-35

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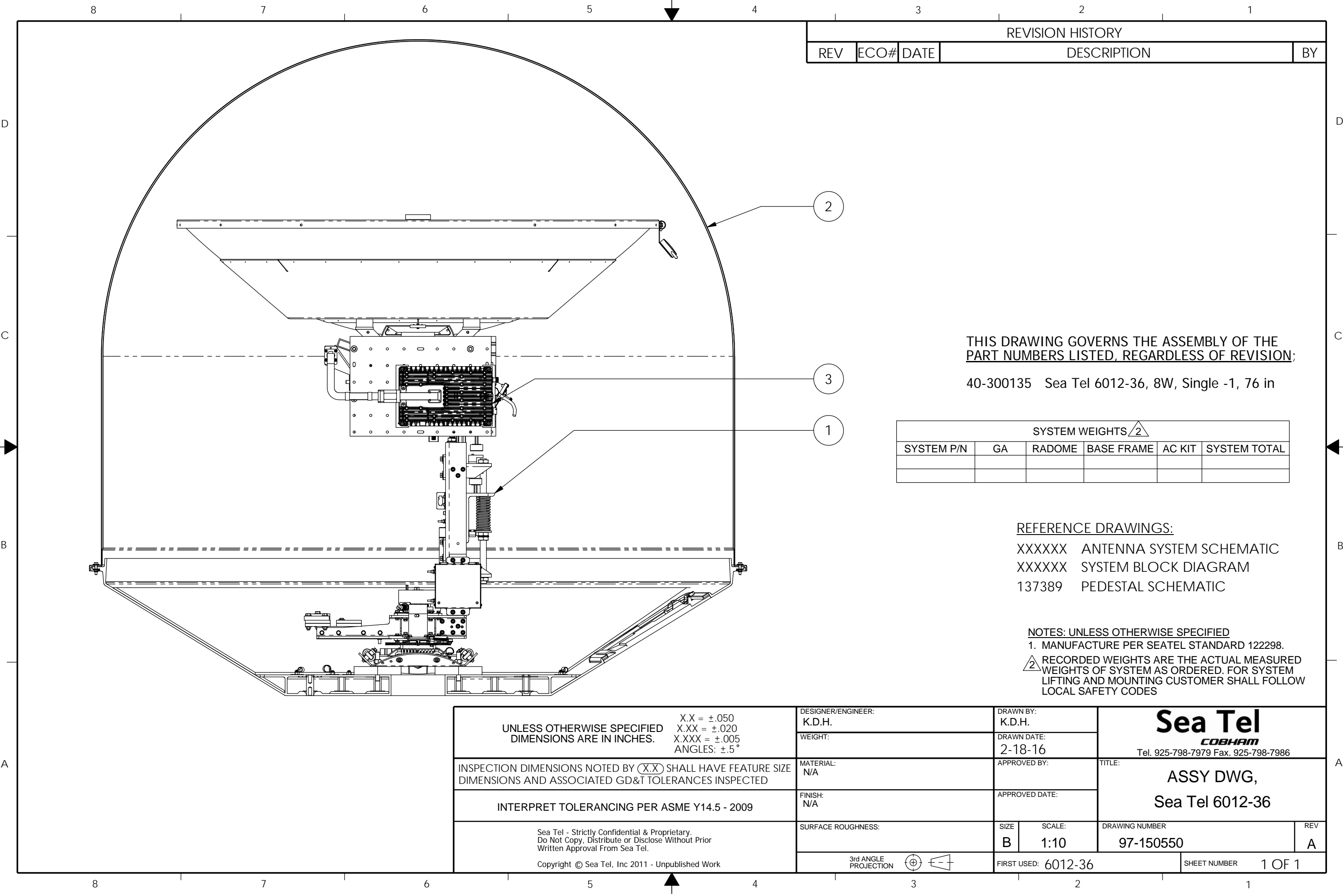


BOM Explosion Report

Item Number: 40-300135
Description: SEA TEL 6012-36, 8W, SINGLE -1, 76 IN.
Item Revision: A.06 ECO-00018800
Date as of: 08/10/2016 10:30:37 AM PDT

Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
0	1		93-150519-A	DRAFTA DCO-00015646	SCHEMATIC, 6012-36 ANTENNA SYSTEM	
0	1		97-150550-A	DRAFTA DCO-00015289	Sea Tel 6012-36	
0	1		DL-150520-A	DRAFTA DCO-00015841	SYSTEM BLOCK LIST, 6012-36	
1	1	pcs	62-150515	A.06 ECO-00017953	GENERAL ASSEMBLY, 6012-36	
2	1	ea	133659-1	D.03 ECO-00014527	RADOME ASSY, GA INSTALL, 76 IN, WHITE	
3	1	pcs	134442-4	A MCO-00020128	SSPB,KU,CODAN LBUC,8W NI,48VDC, 6908W/E-48/EX-CE-NI	
4	2	ea	122188-1	A.04 MCO-00020128	LNB, 11.70 TO 12.20 GHz, PLL, +/- 3 ppm, TYPE F	
5	1	pcs	134725-1	K.02 ECO-00014181	ENCLOSURE ASSY, MXP	(NOT SHOWN)
6	1	ea	134563-1	D ECO-00008546	BELOW DECK KIT, MXP	(NOT SHOWN)
7	1	ea	130929-1	B.01 ECO-00008545	BALANCE WEIGHT KIT, FEED	(NOT SHOWN)
8	1	ea	137387-1	A ECO-00008546	CUSTOMER DOC PACKET, SERIES 12 KU-BAND	(NOT SHOWN)
9	1	ea	124766-1	B ECO-00008543	DECAL KIT, 66-81 IN RADOME, SEA TEL	(NOT SHOWN)
10	1	ea	121711	B.01 ECO-00009762	BALANCE WEIGHT KIT, BASIC, MEDIUM SYSTEMS	(NOT SHOWN)
		pcs	40-300135	A.06 ECO-00018800	SEA TEL 6012-36, 8W, SINGLE -1, 76 IN.	

Created By: Mike Needham
Create Time: 08/11/2016 08:24:43 AM PDT



REVISION HISTORY				
REV	ECO#	DATE	DESCRIPTION	BY

THIS DRAWING GOVERNS THE ASSEMBLY OF THE
PART NUMBERS LISTED, REGARDLESS OF REVISION;

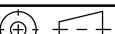
40-300135 Sea Tel 6012-36, 8W, Single -1, 76 in

SYSTEM WEIGHTS ²					
SYSTEM P/N	GA	RADOME	BASE FRAME	AC KIT	SYSTEM TOTAL

REFERENCE DRAWINGS:

- XXXXXX ANTENNA SYSTEM SCHEMATIC
- XXXXXX SYSTEM BLOCK DIAGRAM
- 137389 PEDESTAL SCHEMATIC

NOTES: UNLESS OTHERWISE SPECIFIED
1. MANUFACTURE PER SEATEL STANDARD 122298.
² RECORDED WEIGHTS ARE THE ACTUAL MEASURED WEIGHTS OF SYSTEM AS ORDERED. FOR SYSTEM LIFTING AND MOUNTING CUSTOMER SHALL FOLLOW LOCAL SAFETY CODES

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES.	X.X = ±.050 X.XX = ±.020 X.XXX = ±.005 ANGLES: ±.5°	DESIGNER/ENGINEER: K.D.H.	DRAWN BY: K.D.H.		<div>Sea Tel</div> <div>COBHAM</div> <div>Tel. 925-798-7979 Fax. 925-798-7986</div>		
	WEIGHT:	DRAWN DATE: 2-18-16					
INSPECTION DIMENSIONS NOTED BY (X.X) SHALL HAVE FEATURE SIZE DIMENSIONS AND ASSOCIATED GD&T TOLERANCES INSPECTED	MATERIAL: N/A	APPROVED BY:		TITLE: ASSY DWG, Sea Tel 6012-36			
	FINISH: N/A	APPROVED DATE:					
INTERPRET TOLERANCING PER ASME Y14.5 - 2009		SURFACE ROUGHNESS:		SIZE B	SCALE: 1:10	DRAWING NUMBER 97-150550	REV A
Sea Tel - Strictly Confidential & Proprietary. Do Not Copy, Distribute or Disclose Without Prior Written Approval From Sea Tel.		3rd ANGLE PROJECTION 		FIRST USED: 6012-36			SHEET NUMBER 1 OF 1
Copyright © Sea Tel, Inc 2011 - Unpublished Work							



BOM Explosion Report

Item Number: DL-150520-A
Description: SYSTEM BLOCK LIST, 6012-36
Item Revision: DRAFTA DCO-00015841
Date as of: 04/01/2016 11:15:04 AM PDT

Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
0	1		92-150520-A	Introductory	SYSTEM BLOCK DIAGRAM, 6012-36	
1	1	pcs	62-150515	A.01 ECO-00016289	GENERAL ASSEMBLY, 6012-36	
2	1	pcs	62-146667	A.02 ECO-00015403	ANTENNA INSTALL ASSY, 6012 KU-NET TX/RX CO/X-POL	
3	1	ea	69-143638	A.03 ECO-00015403	FEED ASSY, KU-NET, MEDIUM TX/RX CO/X-POL	
4	1	ea	122188-1	A.04 MCO-00020128	LNB, 11.70 TO 12.20 GHz, PLL, +/- 3 ppm, TYPE F	
5	1	pcs	134442-4	A MCO-00020128	SSPB,KU,CODAN LBUC,8W NI,48VDC, 6908W/E-48/EX-CE-NI	
21	1	ea	134735-1	G.03 ECO-00009135	ENCLOSURE ASSY, ICU, CABLE RETAINER	
22	1	ea	131227-1	H.02 ECO-00008545	ENCLOSURE ASSY, MOTOR DRIVER, 09G2	
23	1	ea	121951-3	G ECO-00008543	MOTOR,SZ 23,BLDC,2 STK W/ ENCODER,20 IN, 4.9MM MTG	
24	2	ea	125644-1	J.02 ECO-00008543	MOTOR, SIZE 23, BLDC W/ BRAKE, 15 PIN	
26	1	ea	131381-1	H ECO-00008545	GARMIN GPS MODULE, SERIAL, 118 INCH TERMINATED	
27	1	ea	129543-24	C ECO-00008544	KIT, CABLE ASSY AND PROXIMITY SENSOR, 24 IN	
28	1	ea	131355-3	C.05 ECO-00008545	POWER SUPPLY ASSY, 300W / 48V, CABLE RETAINER	
31	1	ea	129526-84	D ECO-00008544	HARNESS ASSY, PCU TO MOTOR DRIVER, XX09	
32	1	ea	129527-36	B ECO-00008544	HARNESS ASSY, MOTOR TO ELEVATION, 36 IN, XX09	

Created By: Mike Needham
Create Time: 08/11/2016 08:24:43 AM PDT



BOM Explosion Report

Item Number: DL-150520-A
Description: SYSTEM BLOCK LIST, 6012-36
Item Revision: DRAFTA DCO-00015841
Date as of: 04/01/2016 11:15:04 AM PDT

Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
33	1	ea	137914-72	B ECO-00008546	HARNESS ASSY, REFLECTOR W/ENCODER, 72 IN, 4012GX MK3	
34	1	ea	129741-84	D.01 ECO-00008544	HARNESS ASSY, 400MHZ MODEM TO CPI SSPB, 84 IN	
35	1	ea	128536-84	B ECO-00008544	CABLE ASSY, 48VDC TO CODAN SSPB, 84 IN	
40	1	ea	135696-1	C.03 MCO-00013952	CIRCUIT BREAKER BOX, KIT, 6A	
41	1	ea	129254-2	MCO-00012115	POWER RING, 20A, 3 CIRCUITS, XX09	
42	1	ea	135832-84C	B ECO-00008546	CABLE ASSY, AC POWER, SHIELDED, IEC C13 TO PIN TERM	
43	1	ea	138428-36	A MCO-00012115	POWER CORD, IEC-60320-C14 -DUAL IEC-60320-C13, 36IN	
50	1	ea	117164-60ORG	B ECO-00008542	CABLE ASSY, RG-179, F TO F, 60 IN, ORG	
51	1	ea	117164-60YEL	B ECO-00008542	CABLE ASSY, RG-179, F TO F, 60 IN, YEL	
52	1	ea	128001-24BLU	A.02 ECO-00008544	CABLE ASSY, RG-179, F(M) TO SMA(M)(RA), 24 IN, BLU	
53	1	ea	114972-2	N.01 ECO-00008542	CABLE ASSY, SMA(M) - SMA(M), 72 IN	
54	2	ea	114972-4	N.01 ECO-00008542	CABLE ASSY, SMA(M) - SMA(M), 30 IN	
55	1	ea	123758-7	B.02 ECO-00008543	CABLE ASSY, SMA(M)-N(M) 90 DEG, 7 FT	
60	1	ea	129826-1	B ECO-00008544	CONNECTOR BRACKET ASSY	
61	1	ea	116466	H MCO-00014264	ROTARY JOINT, 4.5 GHz, DUAL COAX.	

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Create Time: 08/11/2016 08:24:43 AM PDT



BOM Explosion Report

Item Number: DL-150520-A
Description: SYSTEM BLOCK LIST, 6012-36
Item Revision: DRAFTA DCO-00015841
Date as of: 04/01/2016 11:15:04 AM PDT

Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
62	1	ea	125171-1	A.01 ECO-00008543	RF STACKER, L-BAND, 500 MHZ	
70	1	ea	128059	MCO-00012114	FILTER, TX REJECT, WR-75, 13.75-14.5 GHZ	
71	1	ea	126144-1	D.01 ECO-00008544	WAVEGUIDE, WR-75, 180 DEG E-BEND	
72	1	ea	140078-1	MCO-00012114	FILTER, REJECT, METRIC, KU-BAND TRANSMIT	
73	1	ea	128290-1	A.01 ECO-00008544	WAVEGUIDE, WR-75, 180 DEG H-BEND W/BACE, 2.00L	
80	1	ea	41-150584-A	01 ECO-00016269	WAVEGUIDE, WR-75, 6012-36	
81	1	pcs	41-148743-A	04 ECO-00015403	WAVEGUIDE, WR-75, 6012-XX KU-NET	
82	1	ea	139034-1	A.01 ECO-00008547	ROTARY JOINT, WR-75, KU-NET	
83	1	ea	125157-1	B ECO-00008543	DIPLEXER, DPX75K-C02-A, WR-75	
84	1	pcs	41-143685-A	02 ECO-00015403	SPACER, WG, WR-75, .130 LONG, 2 GROOVES	
100	1	ea	134563-1	D ECO-00008546	BELOW DECK KIT, MXP	
101	1	pcs	134725-1	K.02 ECO-00014181	ENCLOSURE ASSY, MXP	
103	1	ea	111115-6	C ECO-00008542	CABLE ASSY, F(M)-F(M), 6 FT.	NOT SHOWN
104	1	ea	111079-6	H ECO-00008542	CABLE ASSY, SMA(M)-N(M), 6 FT.	
105	2	ea	119479-10	C ECO-00008542	CABLE ASSY, CAT5 JUMPER, 10 FT.	

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Create Time: 08/11/2016 08:24:43 AM PDT

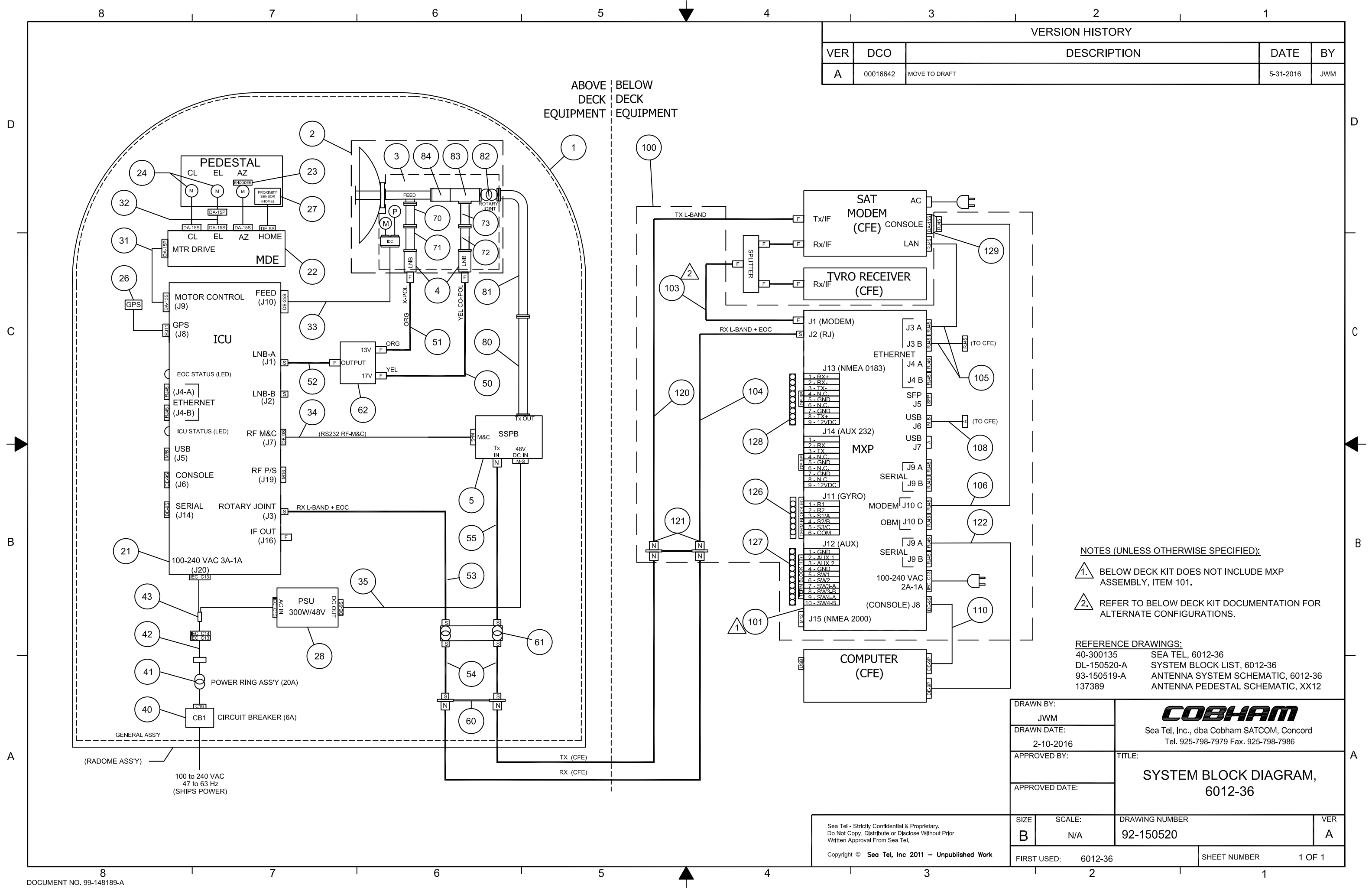


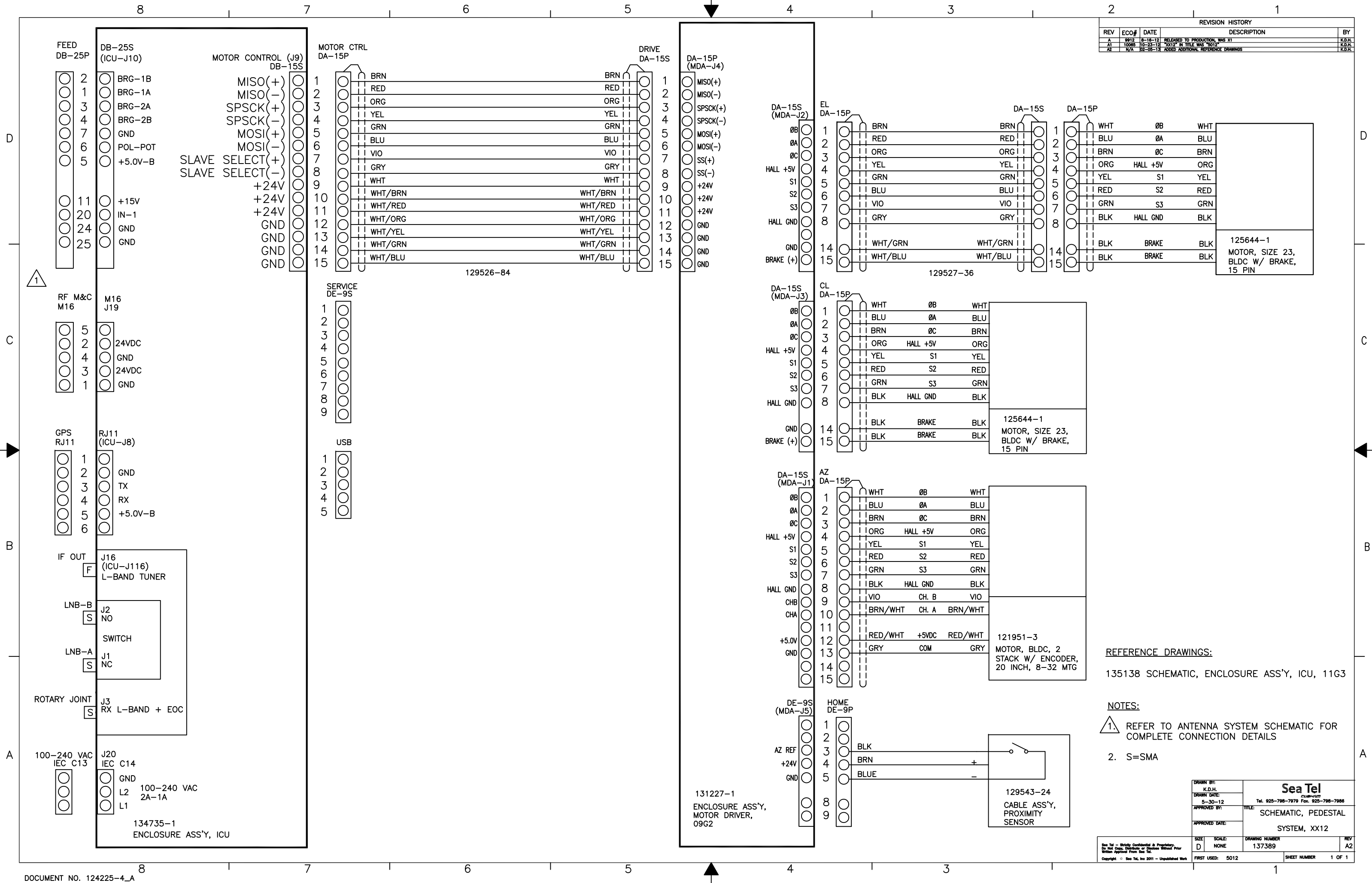
BOM Explosion Report

Item Number: DL-150520-A
Description: SYSTEM BLOCK LIST, 6012-36
Item Revision: DRAFTA DCO-00015841
Date as of: 04/01/2016 11:15:04 AM PDT

Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
106	1	ea	119478-5	E ECO-00008542	CABLE ASSY, RJ-45 SERIAL, 60 IN.	
108	1	ea	133287-2	B MCO-00012115	CABLE ASSY, USB 2.0, 6FT, A/M TO MINI B/M (5PIN)	
110	1	ea	120643-25	C ECO-00008543	CABLE ASSY, RS232, 9-WIRE, STRAIGHT, 25 FT.	
120	1	ea	116700-6	G ECO-00008542	CABLE ASSY, RG223, N(M)-F(M), 6 FT.	
121	2	ea	110567-19	MCO-00012115	ADAPTER, N(F)-N(F), STRAIGHT, FLANGE MNT.	
126	1	ea	135689-6	MCO-00012114	CONN,PHOENIX,PLUGGABLE,TERM BLOCK, 5.08MM P,6 POS	
127	1	ea	135689-10	MCO-00015608	CONN,PHOENIX,PLUGBLE,TERM BLCK,5.08MM PITCH,10 POS	
128	1	ea	136897	C MCO-00012115	CONNECTOR, DE9 (F) - TERM. BLOCK	
			DL-150520-A	DRAFTA DCO-00015841	SYSTEM BLOCK LIST, 6012-36	

Created By: Mike Needham
Create Time: 08/11/2016 08:24:43 AM PDT





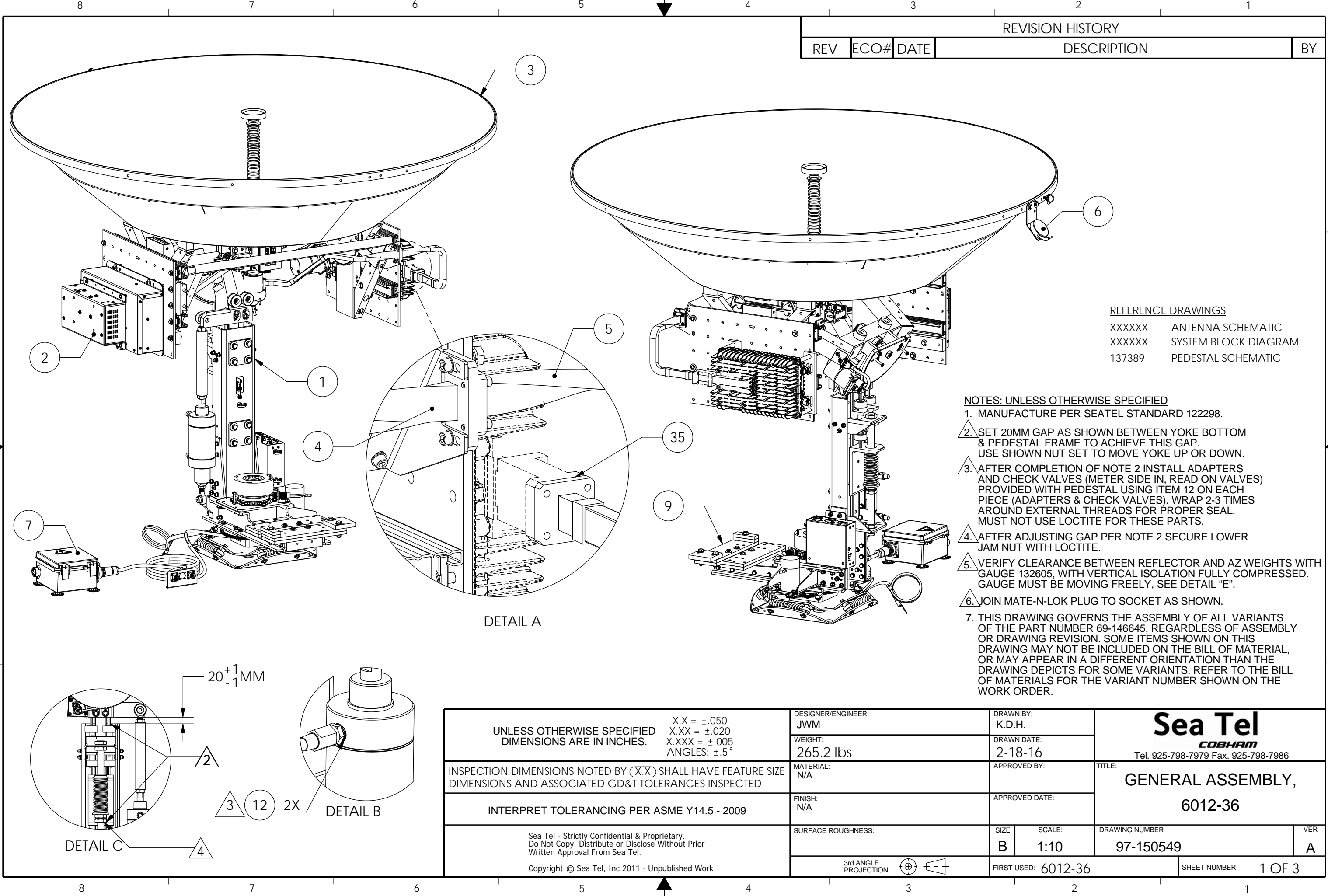


BOM Explosion Report

Item Number: 62-150515
Description: GENERAL ASSEMBLY, 6012-36
Item Revision: A.06 ECO-00017953
Date as of: 08/03/2016 07:13:27 PM PDT

Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
0	1		97-150549-B	DRAFTB DCO-00015466	GENERAL ASSEMBLY, 6012-36	
0	1		DL-000604-C	A DCO-00015899	Software Assembly, General Release IMA	
1	1	ea	138344-3	D.05 ECO-00017508	PEDESTAL ASSY, HD, SINGLE BRIDGE, 6012	
2	1	pcs	62-150516	A.01 MCO-00024016	ELECT. EQU. FRAME ASSY, 6012-36, MK3	
3	1	pcs	62-146667	A.02 MCO-00024016	ANTENNA INSTALL ASSY, 6012 KU-NET TX/RX CO/X-POL	
4	1	pcs	62-148767	A.01 MCO-00024016	KIT, WAVEGUIDE, 6012-XX	
5	1	ea	41-150584-A	01 ECO-00016269	WAVEGUIDE, WR-75, 6012-36	
6	1	ea	131645-1	B.01 ECO-00008545	INSTALL ASSY, GPS, XX09/XX10, MK2 SYSTEMS	
7	1	ea	135696-1	C.03 MCO-00013952	CIRCUIT BREAKER BOX, KIT, 6A	
8	1	pcs	62-150907	A.01 MCO-00024015	BALANCE WEIGHT KIT, 6012-36	
9	1	ea	130294-1	B ECO-00008545	BALANCE WEIGHT KIT, AZ, 6009	
11	1	ea	121655-4	N ECO-00017953	LABELS INSTALLATION, XX09	
12	12	in	130043-12	A ECO-00008544	TAPE, PIPE THREAD SEALANT, 1/2 IN WIDE	
35	1	ea	118294-5	A.03 ECO-00008542	HARDWARE KIT, WR-75, UG FLANGE, METRIC, 1/2 GASKET	
		pcs	62-150515	A.06 ECO-00017953	GENERAL ASSEMBLY, 6012-36	

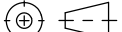
Created By: Mike Needham
Create Time: 08/11/2016 08:24:43 AM PDT



REVISION HISTORY				
REV	ECO#	DATE	DESCRIPTION	BY

REFERENCE DRAWINGS	
XXXXXX	ANTENNA SCHEMATIC
XXXXXX	SYSTEM BLOCK DIAGRAM
137389	PEDESTAL SCHEMATIC

- NOTES: UNLESS OTHERWISE SPECIFIED
- 1. MANUFACTURE PER SEATEL STANDARD 122298.
 - 2. SET 20MM GAP AS SHOWN BETWEEN YOKE BOTTOM & PEDESTAL FRAME TO ACHIEVE THIS GAP. USE SHOWN NUT SET TO MOVE YOKE UP OR DOWN.
 - 3. AFTER COMPLETION OF NOTE 2 INSTALL ADAPTERS AND CHECK VALVES (METER SIDE IN, READ ON VALVES) PROVIDED WITH PEDESTAL USING ITEM 12 ON EACH PIECE (ADAPTERS & CHECK VALVES). WRAP 2-3 TIMES AROUND EXTERNAL THREADS FOR PROPER SEAL. MUST NOT USE LOCTITE FOR THESE PARTS.
 - 4. AFTER ADJUSTING GAP PER NOTE 2 SECURE LOWER JAM NUT WITH LOCTITE.
 - 5. VERIFY CLEARANCE BETWEEN REFLECTOR AND AZ WEIGHTS WITH GAUGE 132605, WITH VERTICAL ISOLATION FULLY COMPRESSED. GAUGE MUST BE MOVING FREELY, SEE DETAIL "E".
 - 6. JOIN MATE-N-LOK PLUG TO SOCKET AS SHOWN.
 - 7. THIS DRAWING GOVERNS THE ASSEMBLY OF ALL VARIANTS OF THE PART NUMBER 69-146645, REGARDLESS OF ASSEMBLY OR DRAWING REVISION. SOME ITEMS SHOWN ON THIS DRAWING MAY NOT BE INCLUDED ON THE BILL OF MATERIAL, OR MAY APPEAR IN A DIFFERENT ORIENTATION THAN THE DRAWING DEPICTS FOR SOME VARIANTS. REFER TO THE BILL OF MATERIALS FOR THE VARIANT NUMBER SHOWN ON THE WORK ORDER.

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES.	X.X = ±.050 X.XX = ±.020 X.XXX = ±.005 ANGLES: ±.5°	DESIGNER/ENGINEER: JWM		DRAWN BY: K.D.H.		<div>Sea Tel</div> <div>COBHAM</div> <div>Tel. 925-798-7979 Fax. 925-798-7986</div>	
	WEIGHT: 265.2 lbs		DRAWN DATE: 2-18-16				
INSPECTION DIMENSIONS NOTED BY (X.X) SHALL HAVE FEATURE SIZE DIMENSIONS AND ASSOCIATED GD&T TOLERANCES INSPECTED		MATERIAL: N/A		APPROVED BY:		TITLE: GENERAL ASSEMBLY, 6012-36	
		FINISH: N/A		APPROVED DATE:			
INTERPRET TOLERANCING PER ASME Y14.5 - 2009		SURFACE ROUGHNESS:		SIZE B	SCALE: 1:10	DRAWING NUMBER 97-150549	VER A
Sea Tel - Strictly Confidential & Proprietary. Do Not Copy, Distribute or Disclose Without Prior Written Approval From Sea Tel.		3rd ANGLE PROJECTION 		FIRST USED: 6012-36		SHEET NUMBER 1 OF 3	
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3rd ANGLE
PROJECTION

D



6

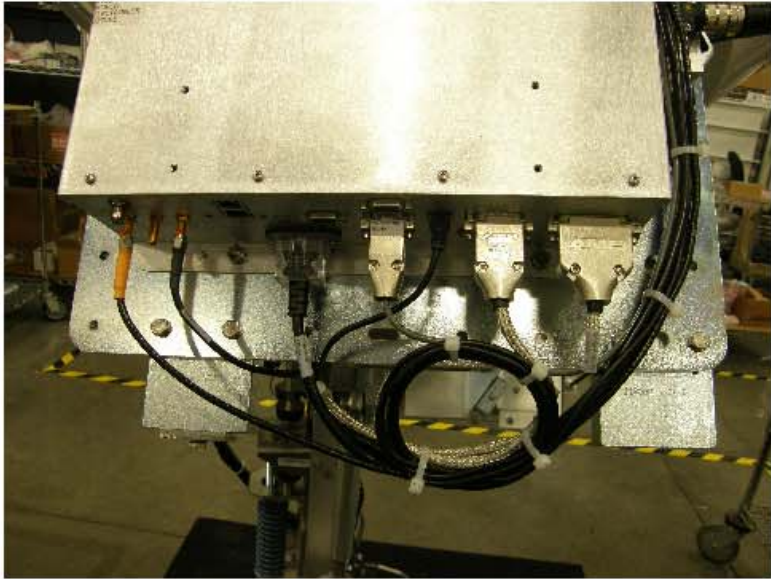


D

C

C

B



Update views

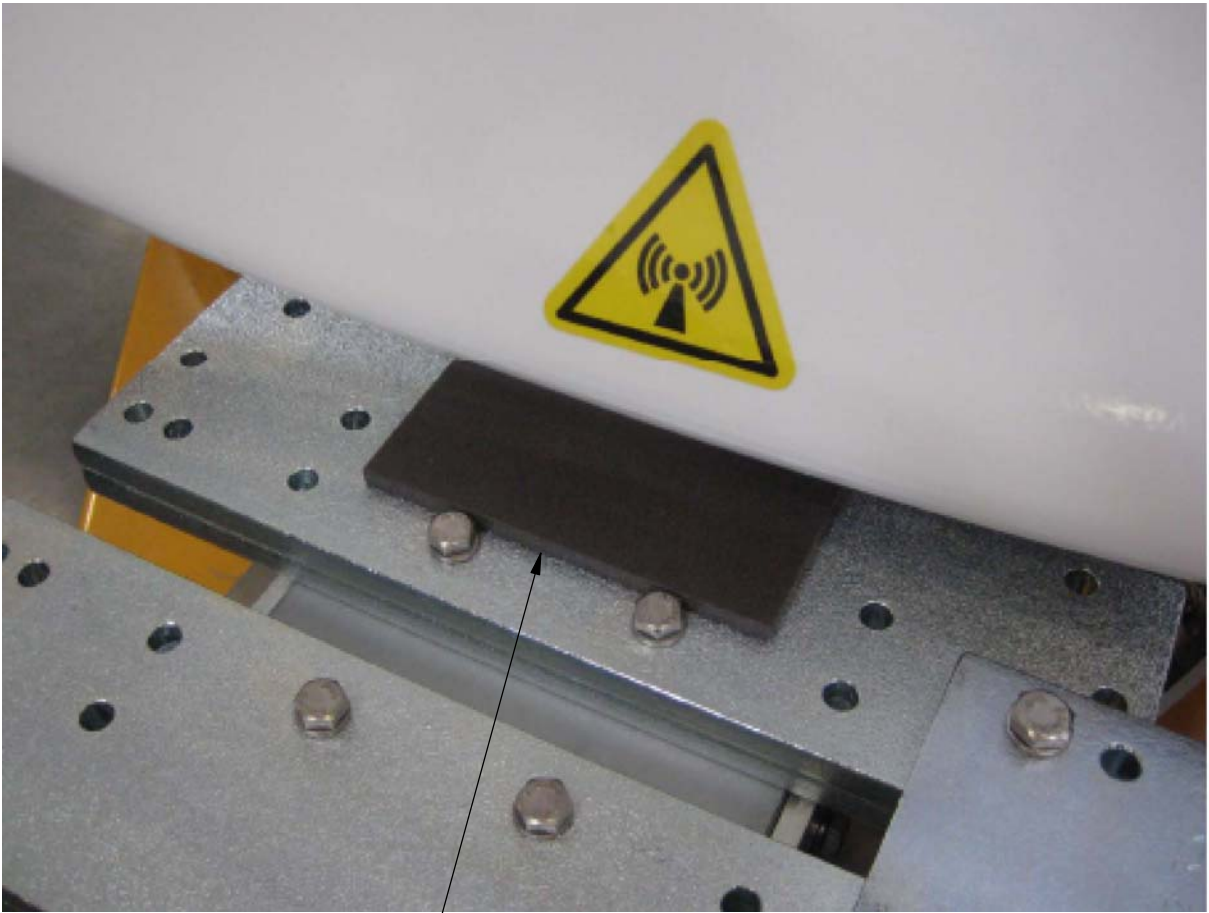


B

A

A

SIZE	SCALE:	DRAWING NUMBER	VER
B	1:10	97-150549	A
		SHEET NUMBER	2 OF 3



5 DETAIL "E"

SIZE	SCALE:	DRAWING NUMBER	VER
B	1:10	97-150549	A
		SHEET NUMBER	3 OF 3



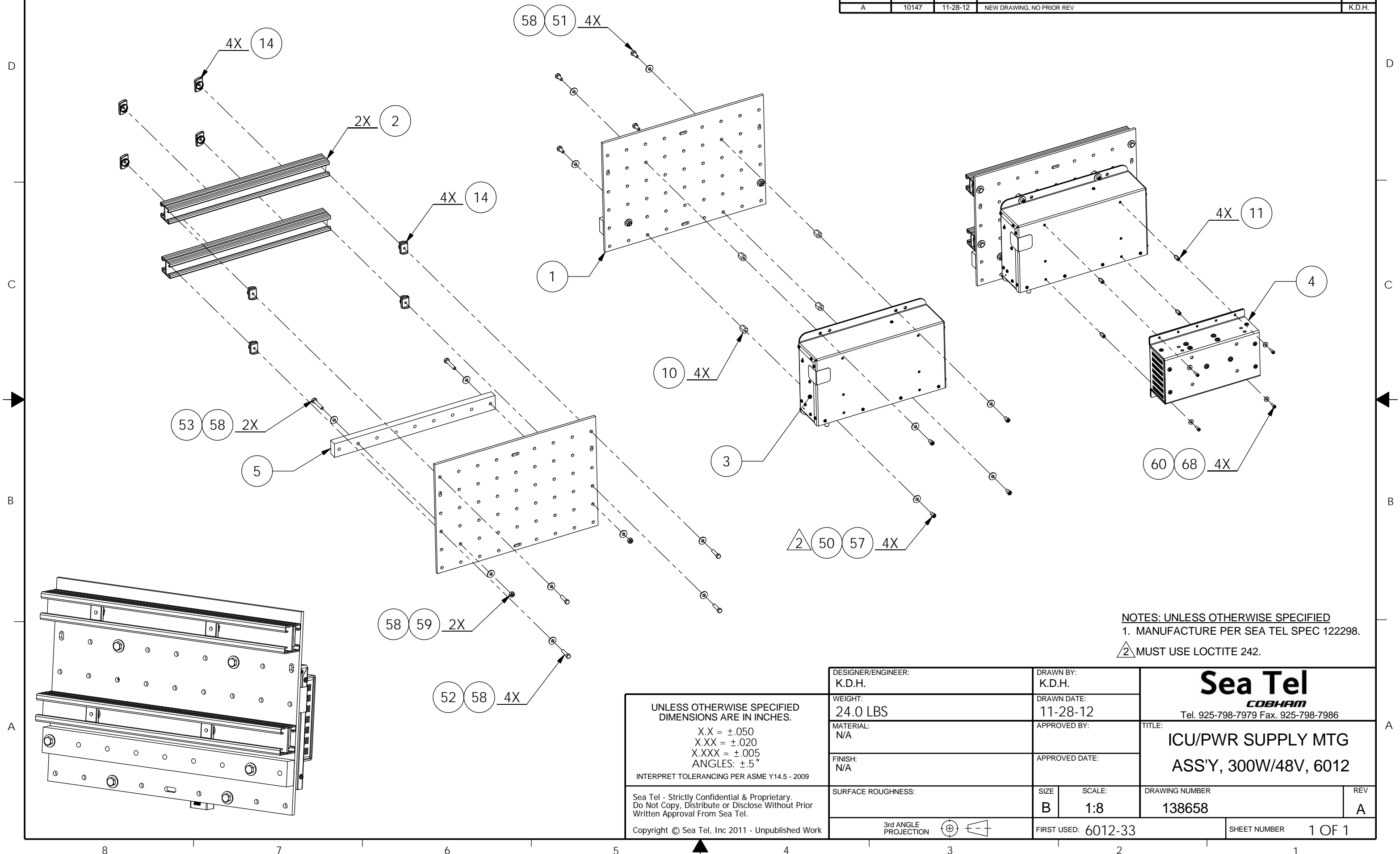
BOM Explosion Report

Item Number: 138658-1
Description: ICU/PSU MOUNTING ASSY, 300W/48V, 6012
Item Revision: A ECO-00008547
Date as of: 09/20/2014 04:34:33 PM PDT

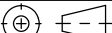
Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
1	1	ea	123861	B ECO-00008543	MOUNTING PLATE	
2	2	ea	126288-17	B ECO-00008544	UNISTRUT, 1-5/8 H-CHANNEL, 17 IN, AL	
3	1	ea	134735-1	G.02 ECO-00008546	ENCLOSURE ASSY, ICU, CABLE RETAINER	
4	1	ea	131355-3	C.05 ECO-00008545	POWER SUPPLY ASSY, 300W / 48V, CABLE RETAINER	
5	1	ea	131374-1	A ECO-00008545	WEIGHT, COUNTER, 1-1/2 X 3/4 X 17	
10	4	ea	124588-1021	MCO-00012114	STANDOFF, HEX, F/F, 1/4-20 X .50 OD X 0.625, ALUM	
11	4	ea	131572-5321	MCO-00012114	STANDOFF, HEX, M/F, M4 X 14, BRASS W/ZINC PLATING	
14	8	ea	126279-3	MCO-00012114	NUT, 1 5/8 UNISTRUT, 1/4-20, W/SPRING, STEEL	
50	4	ea	114593-202	MCO-00012113	SCREW, SOCKET HD, 1/4-20 x 3/8, SS.	
51	4	ea	114586-536	MCO-00012113	SCREW, HEX HD, 1/4-20 x 5/8, SS.	
52	4	ea	114586-538	MCO-00012113	SCREW, HEX HD, 1/4-20 x 1, SS.	
53	2	ea	114586-541	MCO-00012113	SCREW, HEX HD, 1/4-20 x 1-1/2, SS.	
57	4	ea	114580-027	MCO-00012113	WASHER, FLAT, 1/4, SMALL PATTERN, SS.	
58	12	ea	114580-029	MCO-00012113	WASHER, FLAT, 1/4, SS.	
59	2	ea	114583-029	MCO-00012113	NUT, HEX, 1/4-20, SS.	
60	4	ea	119973-117	MCO-00012113	SCREW, SOCKET HD, M4 X 12, SS.	
68	4	ea	114580-230	MCO-00012113	WASHER, FLAT, M4, SS.	
		ea	138658-1	A ECO-00008547	ICU/PSU MOUNTING ASSY, 300W/48V, 6012	

Created By: Mike Needham
Create Time: 08/11/2016 08:24:43 AM PDT

REVISION HISTORY				
REV	ECO#	DATE	DESCRIPTION	BY
A	10147	11-28-12	NEW DRAWING, NO PRIOR REV	K.D.H.



NOTES: UNLESS OTHERWISE SPECIFIED
1. MANUFACTURE PER SEA TEL SPEC 122298.
2 MUST USE LOCTITE 242.

<p>UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES.</p> <p>X.X = ±.050 X.XX = ±.020 X.XXX = ±.005 ANGLES: ±.5°</p> <p>INTERPRET TOLERANCING PER ASME Y14.5 - 2009</p>	<p>DESIGNER/ENGINEER: K.D.H.</p>	<p>DRAWN BY: K.D.H.</p>		<p>Sea Tel <i>COBHAM</i> Tel. 925-798-7979 Fax. 925-798-7986</p>	
	<p>WEIGHT: 24.0 LBS</p>	<p>DRAWN DATE: 11-28-12</p>			
	<p>MATERIAL: N/A</p>	<p>APPROVED BY:</p>		<p>TITLE: ICU/PWR SUPPLY MTG ASS'Y, 300W/48V, 6012</p>	
	<p>FINISH: N/A</p>	<p>APPROVED DATE:</p>			
<p>Sea Tel - Strictly Confidential & Proprietary. Do Not Copy, Distribute or Disclose Without Prior Written Approval From Sea Tel.</p> <p>Copyright © Sea Tel, Inc 2011 - Unpublished Work</p>	<p>SURFACE ROUGHNESS:</p>	<p>SIZE B</p>	<p>SCALE: 1:8</p>	<p>DRAWING NUMBER 138658</p>	<p>REV A</p>
	<p>3rd ANGLE PROJECTION</p> 	<p>FIRST USED: 6012-33</p>			<p>SHEET NUMBER 1 OF 1</p>

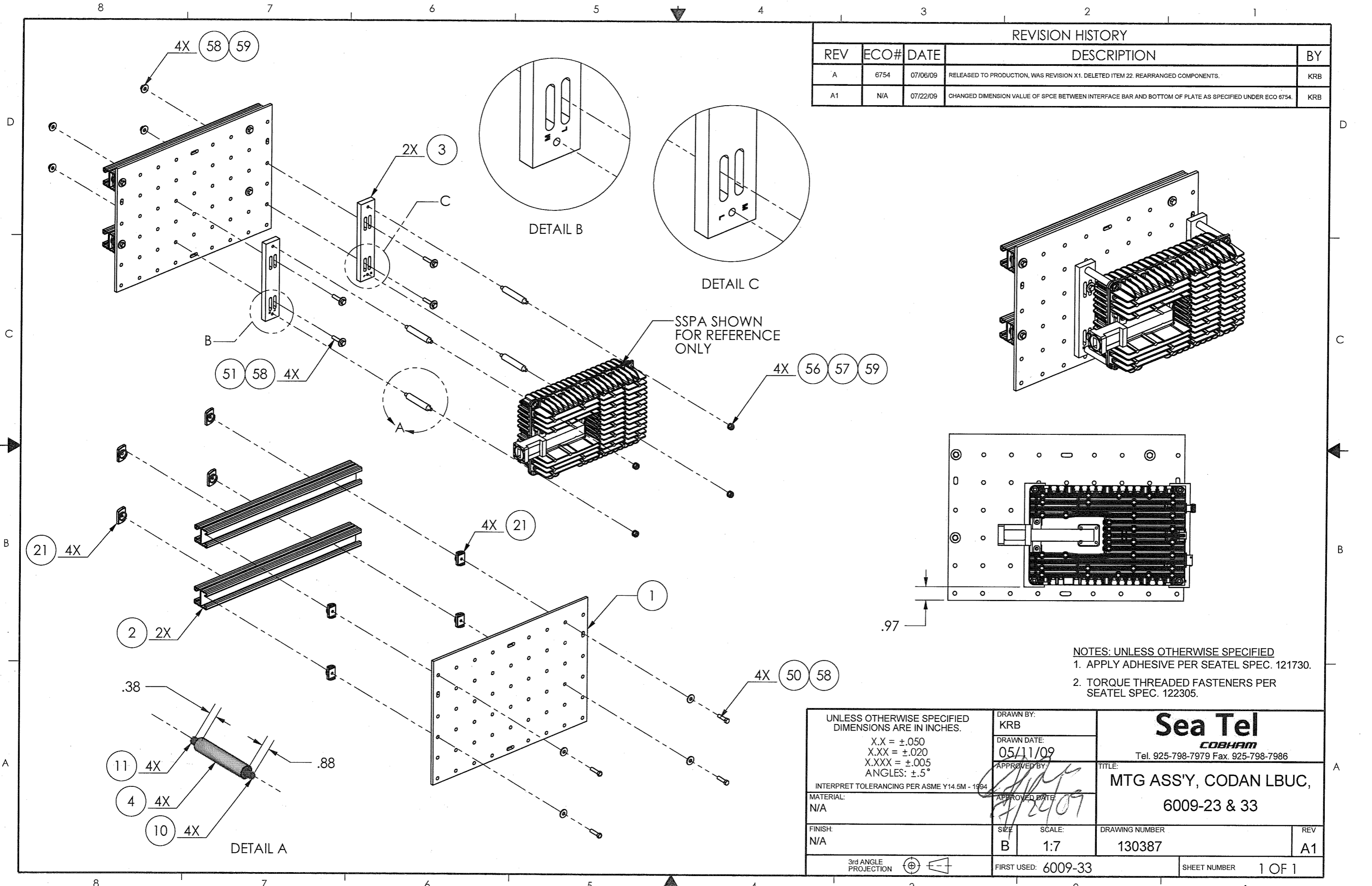


BOM Explosion Report

Item Number: 130387-1
Description: MOUNTING ASSY, CODAN LBUC, 6009-23/33
Item Revision: A.01 ECO-00008545
Date as of: 09/20/2014 04:24:59 PM PDT


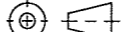
Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
1	1	ea	123861	B ECO-00008543	MOUNTING PLATE	
2	2	ea	126288-17	B ECO-00008544	UNISTRUT, 1-5/8 H-CHANNEL, 17 IN, AL	
3	2	ea	124716	B ECO-00008543	RF INTERFACE, BAR, CODAN, BUC	
4	4	ea	118328-4	D ECO-00008542	STANDOFF, RND, F/F, 1/4-20 X .5 OD X 2.62, SS	
10	4	ea	114592-544	MCO-00012113	STUD, FULLY THREADED, 1/4-20 x 1-1/4, SS.	
11	4	ea	114592-540	MCO-00012113	STUD, FULLY THREADED, 1/4-20 x 3/4, SS.	
21	8	ea	126279-3	MCO-00012114	NUT, 1 5/8 UNISTRUT, 1/4-20, W/SPRING, STEEL	
50	4	ea	114586-538	MCO-00012113	SCREW, HEX HD, 1/4-20 x 1, SS.	
51	4	ea	114586-540	MCO-00012113	SCREW, HEX HD, 1/4-20 x 1-1/4, SS.	
56	4	ea	114580-027	MCO-00012113	WASHER, FLAT, 1/4, SMALL PATTERN, SS.	
57	4	ea	114581-029	MCO-00012113	WASHER, LOCK, 1/4, SS	
58	12	ea	114580-029	MCO-00012113	WASHER, FLAT, 1/4, SS.	
59	8	ea	114583-029	MCO-00012113	NUT, HEX, 1/4-20, SS.	
		ea	130387-1	A.01 ECO-00008545	MOUNTING ASSY, CODAN LBUC, 6009-23/33	

Created By: Mike Needham
Create Time: 08/11/2016 08:24:43 AM PDT



REVISION HISTORY				
REV	ECO#	DATE	DESCRIPTION	BY
A	6754	07/06/09	RELEASED TO PRODUCTION, WAS REVISION X1. DELETED ITEM 22. REARRANGED COMPONENTS.	KRB
A1	N/A	07/22/09	CHANGED DIMENSION VALUE OF SPCE BETWEEN INTERFACE BAR AND BOTTOM OF PLATE AS SPECIFIED UNDER ECO 6754.	KRB

NOTES: UNLESS OTHERWISE SPECIFIED
1. APPLY ADHESIVE PER SEATEL SPEC. 121730.
2. TORQUE THREADED FASTENERS PER SEATEL SPEC. 122305.

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES. X.X = ±.050 X.XX = ±.020 X.XXX = ±.005 ANGLES: ±.5° INTERPRET TOLERANCING PER ASME Y14.5M - 1994		DRAWN BY: KRB		<div>Sea Tel</div> <div>COBHAM</div> <div>Tel. 925-798-7979 Fax. 925-798-7986</div>	
		DRAWN DATE: 05/11/09			
MATERIAL: N/A		APPROVED BY: 		TITLE: MTG ASS'Y, CODAN LBUC, 6009-23 & 33	
		APPROVED DATE: 5/24/09			
FINISH: N/A		SIZE: B	SCALE: 1:7	DRAWING NUMBER: 130387	REV: A1
3rd ANGLE PROJECTION 		FIRST USED: 6009-33			SHEET NUMBER 1 OF 1

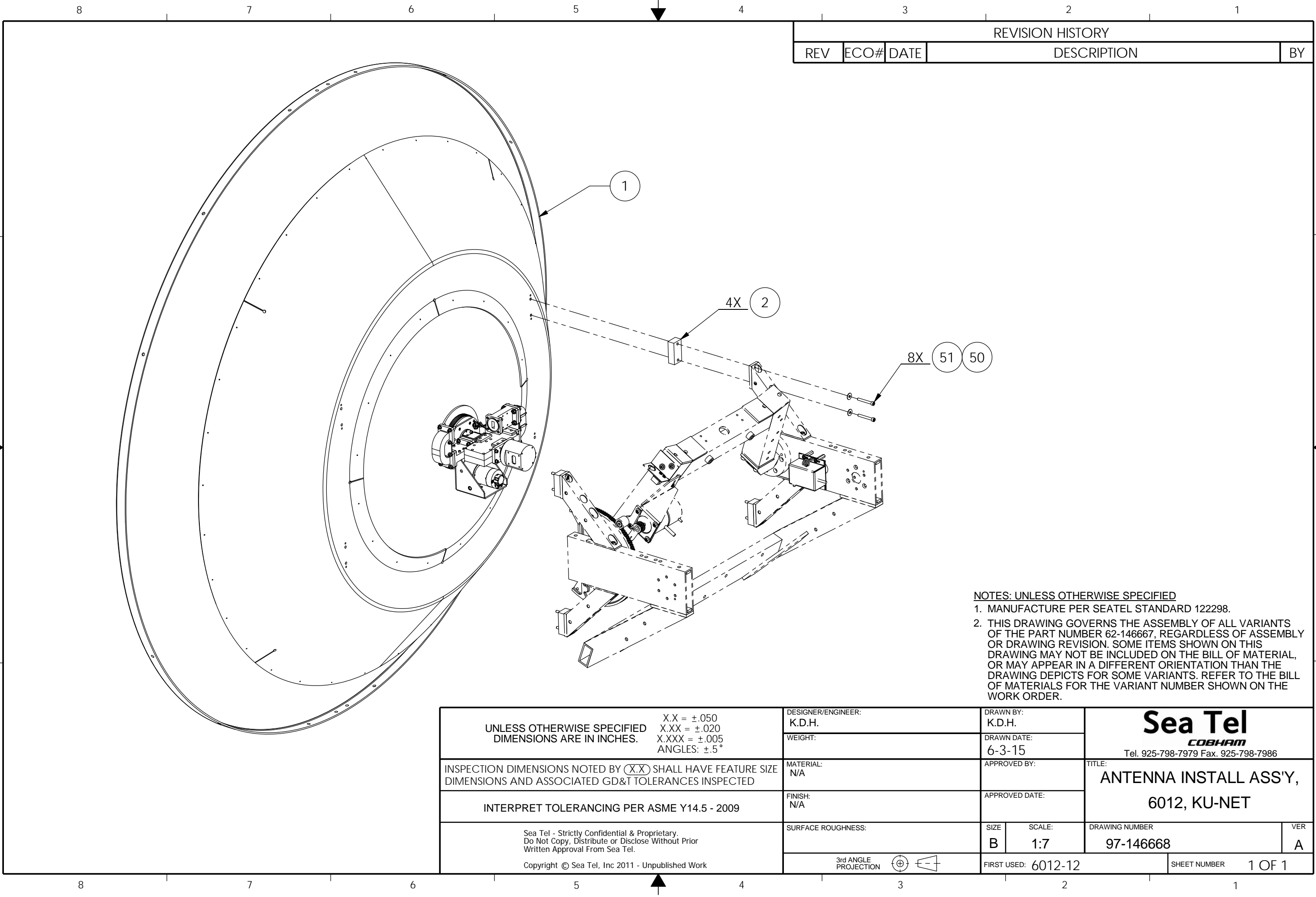


BOM Explosion Report

Item Number: 62-146667
Description: ANTENNA INSTALL ASSY, 6012 KU-NET TX/RX CO/X-POL
Item Revision: A.02 MCO-00024016
Date as of: 04/22/2016 01:11:35 PM PDT

Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
0	1		97-146668-A	DRAFTA DCO-00011560	ASSEMBLY DRAWING, ANTENNA INSTALL ASSY, 6012, KU-NET	
1	1	pcs	62-146669	B MCO-00024015	ANTENNA ASSEMBLY, 6012, KU-NET, TX/RX CO/X-POL	
2	4	ea	125488-7	B.02 ECO-00008543	SPACER, REFLECTOR BRACE, 1.000 IN	
50	8	ea	114593-173	MCO-00012113	SCREW, SOCKET HD, 10-32 x 2, SS.	
51	8	ea	114580-011	MCO-00012113	WASHER, FLAT, #10, SS.	
		pcs	62-146667	A.02 MCO-00024016	ANTENNA INSTALL ASSY, 6012 KU-NET TX/RX CO/X-POL	

Created By: Mike Needham
Create Time: 08/11/2016 08:24:43 AM PDT



REVISION HISTORY				
REV	ECO#	DATE	DESCRIPTION	BY

- NOTES: UNLESS OTHERWISE SPECIFIED**
- 1. MANUFACTURE PER SEATEL STANDARD 122298.
 - 2. THIS DRAWING GOVERNS THE ASSEMBLY OF ALL VARIANTS OF THE PART NUMBER 62-146667, REGARDLESS OF ASSEMBLY OR DRAWING REVISION. SOME ITEMS SHOWN ON THIS DRAWING MAY NOT BE INCLUDED ON THE BILL OF MATERIAL, OR MAY APPEAR IN A DIFFERENT ORIENTATION THAN THE DRAWING DEPICTS FOR SOME VARIANTS. REFER TO THE BILL OF MATERIALS FOR THE VARIANT NUMBER SHOWN ON THE WORK ORDER.

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES.	X.X = ±.050 X.XX = ±.020 X.XXX = ±.005 ANGLES: ±.5°	DESIGNER/ENGINEER: K.D.H.		DRAWN BY: K.D.H.		<div>Sea Tel</div> <div>COBHAM</div> <div>Tel. 925-798-7979 Fax. 925-798-7986</div>			
		WEIGHT:		DRAWN DATE: 6-3-15					
INSPECTION DIMENSIONS NOTED BY (X.X) SHALL HAVE FEATURE SIZE DIMENSIONS AND ASSOCIATED GD&T TOLERANCES INSPECTED		MATERIAL: N/A		APPROVED BY:		TITLE: ANTENNA INSTALL ASS'Y, 6012, KU-NET			
		FINISH: N/A		APPROVED DATE:					
INTERPRET TOLERANCING PER ASME Y14.5 - 2009		SURFACE ROUGHNESS:		SIZE B	SCALE: 1:7	DRAWING NUMBER 97-146668			VER A
Sea Tel - Strictly Confidential & Proprietary. Do Not Copy, Distribute or Disclose Without Prior Written Approval From Sea Tel.		3rd ANGLE PROJECTION		FIRST USED: 6012-12			SHEET NUMBER 1 OF 1		
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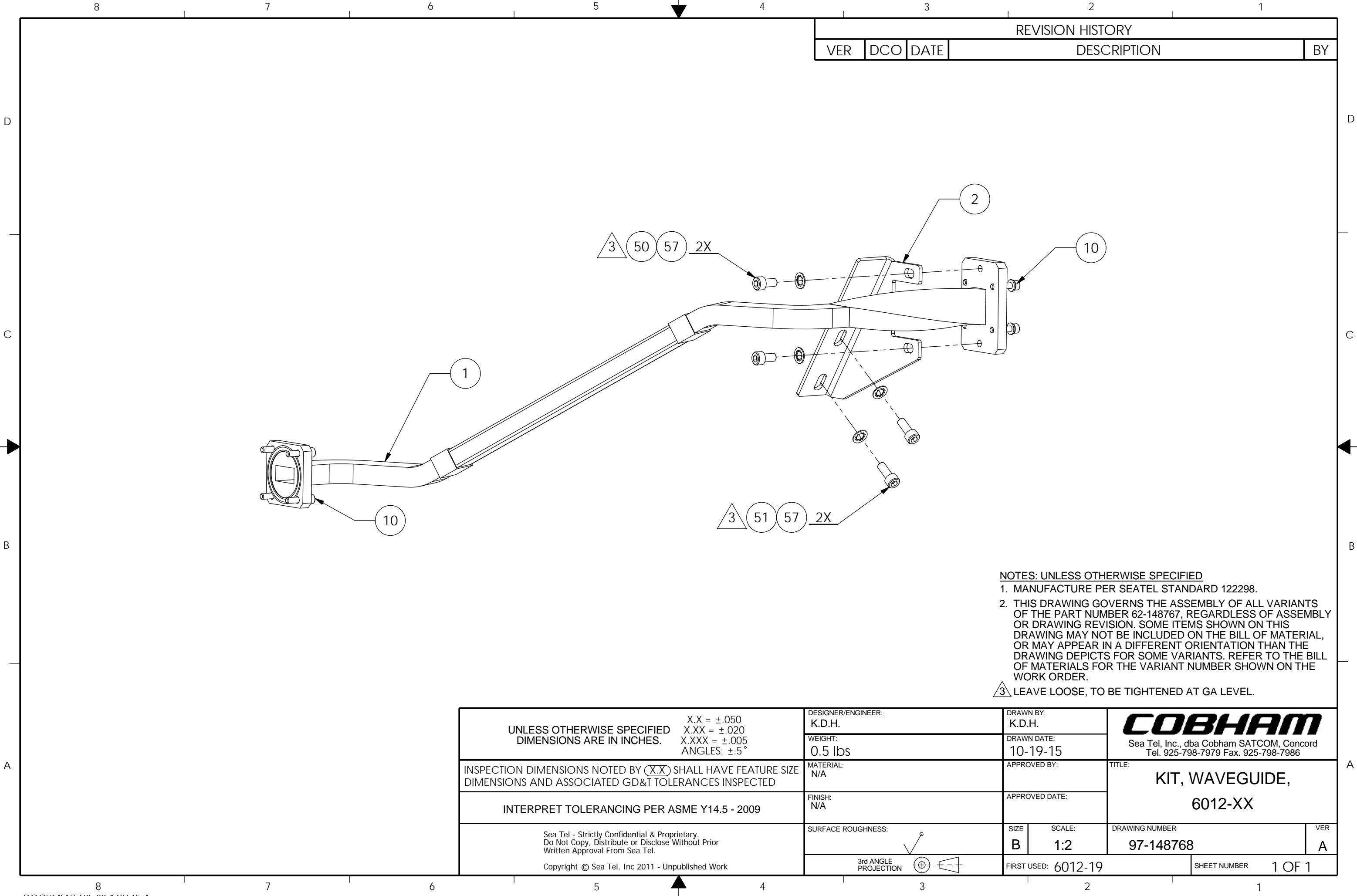


BOM Explosion Report

Item Number: 62-148767
Description: KIT, WAVEGUIDE, 6012-XX
Item Revision: A.01 MCO-00024016
Date as of: 04/22/2016 01:11:35 PM PDT


Find Num	Qty	Inventory Unit (LN6)	Number	Rev	Description / Title	BOM Notes
0	1		97-148768-A	DRAFTA DCO-00013703	KIT, WAVEGUIDE, 6012-XX	
1	1	pcs	41-148743-A	04 ECO-00015403	WAVEGUIDE, WR-75, 6012-XX KU-NET	
2	1	pcs	41-148762-A	04 ECO-00015403	BRACKET, WAVEGUIDE SUPPORT, 6012-XX KU-NET	
10	2	ea	118294-12	B.01 ECO-00008542	HARDWARE KIT, WR-75, UG FLANGE, BLIND	
50	2	ea	114593-162	MCO-00012113	SCREW, SOCKET HD, 10-32 x 3/8, SS.	
51	2	ea	114593-164	MCO-00012113	SCREW, SOCKET HD, 10-32 x 1/2, SS.	
57	4	ea	119952-011	MCO-00012114	WASHER, STAR, INTERNAL TOOTH, #10, SS.	
		pcs	62-148767	A.01 MCO-00024016	KIT, WAVEGUIDE, 6012-XX	

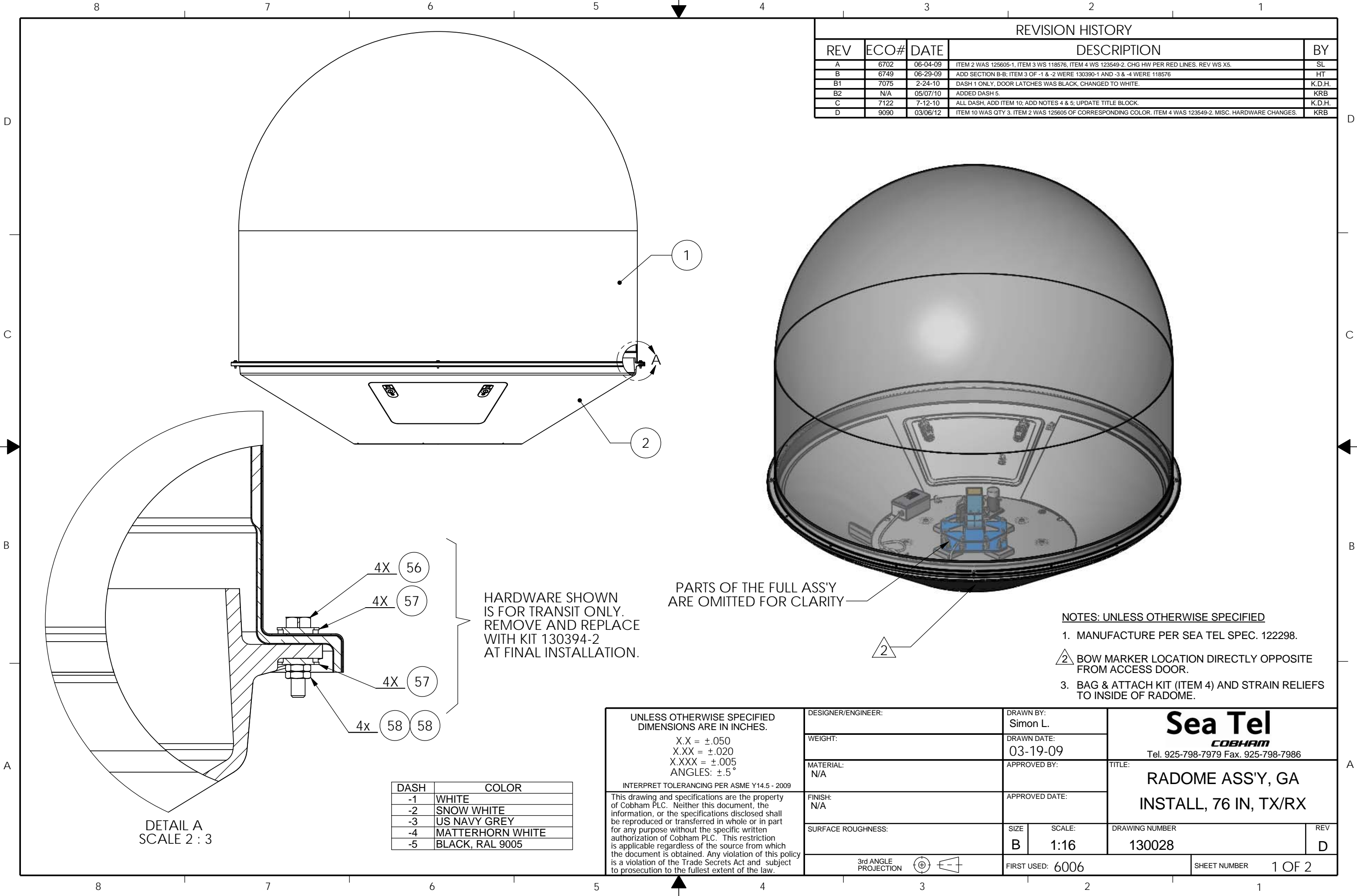
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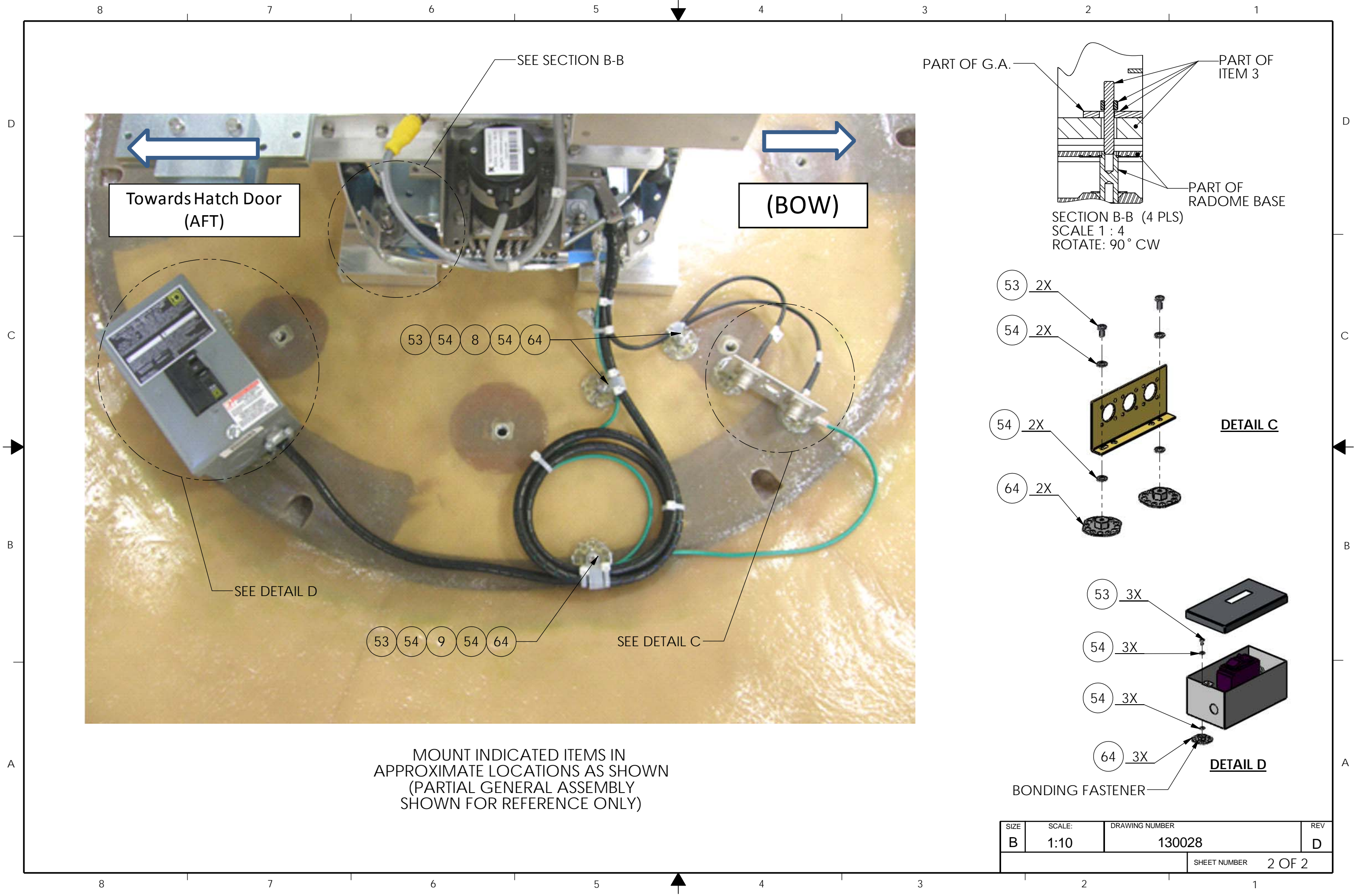


SINGLE LEVEL MFG BILL OF MATERIAL

FIND	QTY	PART NO	REV	DESCRIPTION	REFERENCE DESIGNATOR
1	1 EA	128652-1	A2	RADOME TOP FAB, 76 IN, WHITE	
2	1 EA	130395-1	A3	RADOME BASE ASS'Y, 76 IN, WHITE	
3	1 EA	130390-2	B	KIT, HARDWARE, GA TO RADOME, RAISED	
4	1 EA	130394-2	D	KIT, HARDWARE, RADOME TO MAST, 12-HOL	
5	4 EA	119801-012	B	CABLE TIE, NYLON, 4 IN, NATURAL	(NOT SHOWN) ,
6	7 EA	119801-019	B	CABLE TIE, NYLON, 7.5 IN, NATURAL	(NOT SHOWN) ,
7	1 OZ	125948-1	A	ADHESIVE, HOT MELT, 3M SCOTCH-WELD 37	(NOT SHOWN) ,
8	2 EA	111679-7	B	CABLE CLAMP, NYLON, .50 DIA, #8 MTG H	
9	1 EA	111679-25	B	CABLE CLAMP, NYLON, 3/4 DIA, #10 MTG	
10	5 EA	124903-1	B3	STRAIN RELIEF ASS'Y (CABLE GLAND)	(NOT SHOWN) ,
53	8 EA	119745-218		SCREW, PAN HD, PHIL, M4 x 8	
54	16 EA	114580-230		WASHER, FLAT, M4, S.S.	
56	4 EA	114589-141		SCREW, HEX HD M6X35	
57	8 EA	130371-170	A	WASHER, NYLON, 6.4 ID, 12 OD	
58	8 EA	120089-251		NUT, HEX, M6, S.S.	
64	8 EA	125806-7	A	ROTALOC HEX NUT, SS-1-B38-M4 X 07-6H	
101	1 EA	131412	A	CRATE, 76 IN RADOME, OD: 88 X 88 X 87	
102	1 EA	131469-1	A1	SHIPPING KIT, ASS'Y	

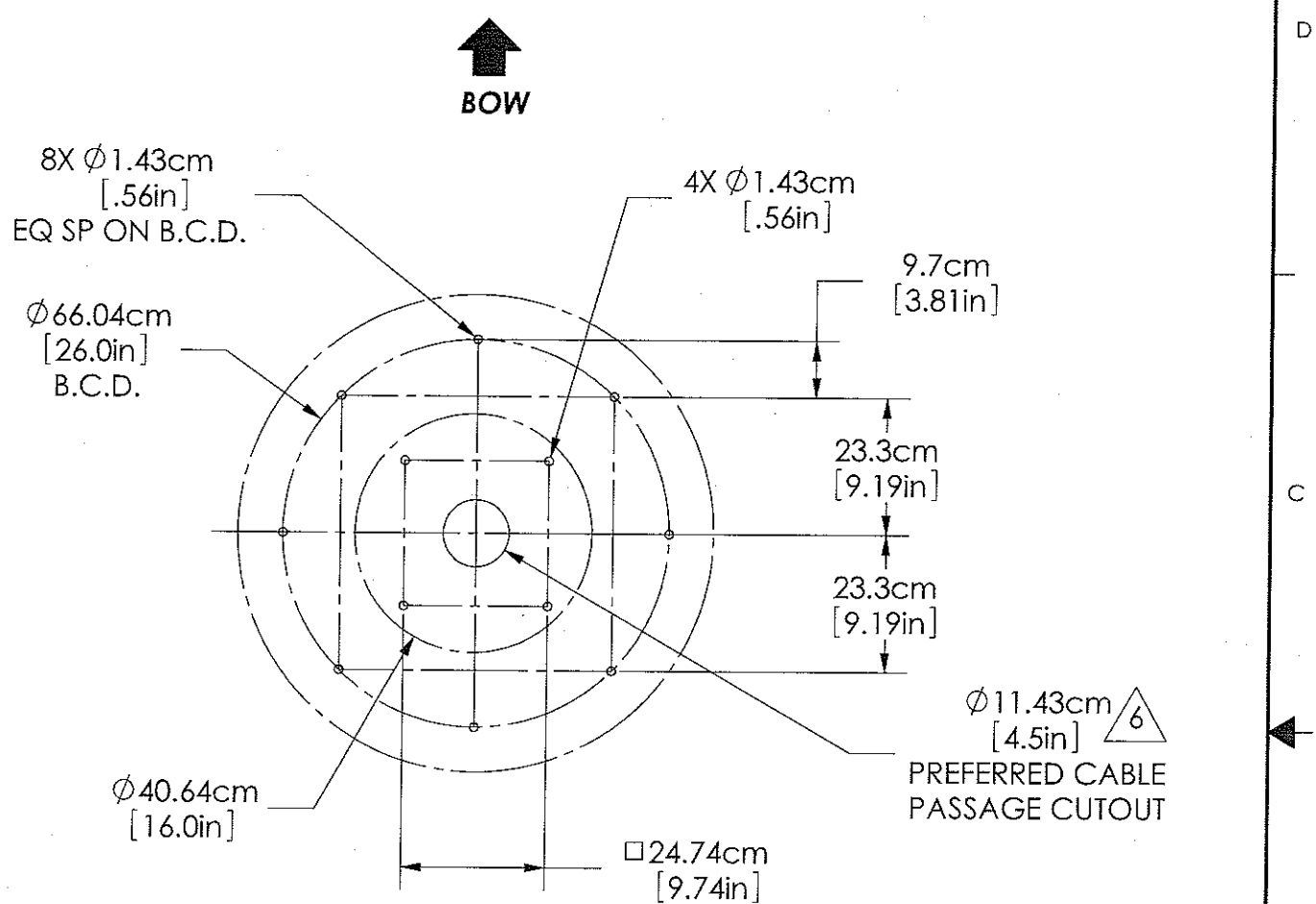
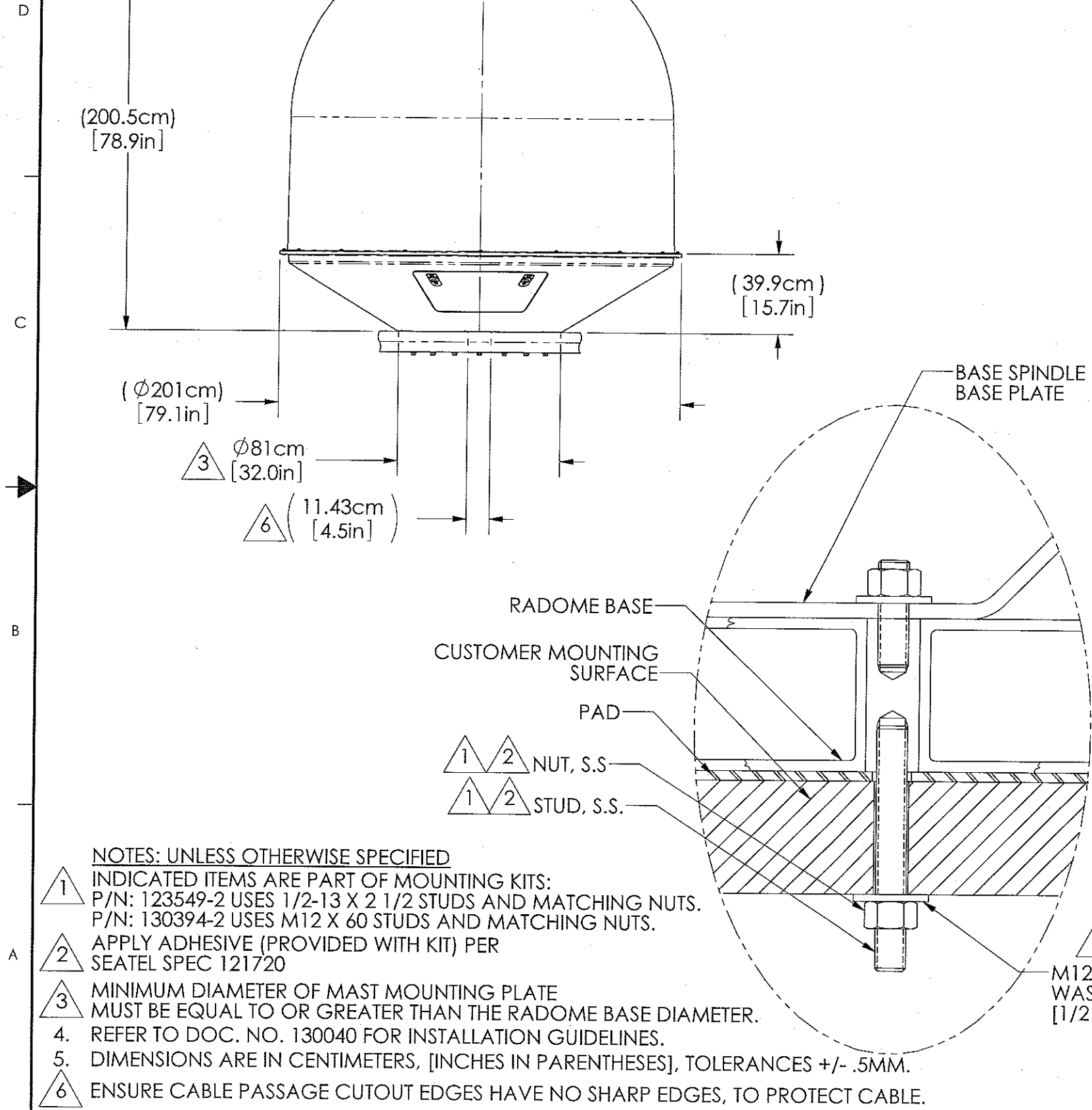
				
RADOME ASS'Y, GA INSTALL, 76 IN, TX/RX, WHITE				
PROD FAMILY COMMON	EFF. DATE 2/20/2013	SHT 1 OF 1	DRAWING NUMBER 130028-1	REV E





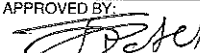
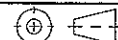
SIZE	SCALE:	DRAWING NUMBER	REV
B	1:10	130028	D
		SHEET NUMBER	2 OF 2

REVISION HISTORY				
REV	ECO#	DATE	DESCRIPTION	BY
A	N/A	01-05-06	PRODUCTION RELEASE, WS X1.	LAE
B	6762	07-10-09	ADD METRIC VALUES TO ALL DIMENSIONS.	SL
C	N/A	09-17-09	ADDED NOTES 3-5; NOTE 1: ADDED 130394-2; REF DWGS: ADDED 126153, 130028, 130029; SECTION VIEW: ADDED PAD.	AMN
D	N/A	01-29-10	ADDED 4.5 IN DIA PREFERRED CABLE PASSAGE CUTOUT (ZONE C3); ADDED NOTE 6.	AMN



ALL HOLES MUST BE USED TO MOUNT THE ABOVE DECKS EQUIPMENT TO THE SHIP.

- REFERENCE DRAWINGS
 125849 RADOME ASS'Y, GA INSTALL, 76-IN, TX/RX
 126153 RADOME ASS'Y, GA INSTALL, 76-IN, TVRO
 130028 RADOME ASS'Y, GA INSTALL, 76-IN, TX/RX
 130029 RADOME ASS'Y, GA INSTALL, 76-IN, TVRO

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES. X.X = $\pm .050$ X.XX = $\pm .020$ X.XXX = $\pm .005$ ANGLES: $\pm .5^{\circ}$		DRAWN BY: T PATEL		<h1>Sea Tel</h1> COBHAM Tel. 925-798-7979 Fax. 925-798-7986			
INTERPRET TOLERANCING PER ASME Y14.5M - 1994		DRAWN DATE: 12/19/06					
MATERIAL: N/A		APPROVED BY: 		TITLE: INSTALLATION ARRANGEMENT 76-IN RADOME			
FINISH: N/A		APPROVED DATE: 1/29/2010					
<div>3rd ANGLE PROJECTION</div> 		SIZE B	SCALE: 1:4	DRAWING NUMBER 125749		REV D	
		FIRST USED: 6006			SHEET NUMBER		1 OF 1

Procedure, Radome Strain Relief Installation

- 1.0 Purpose.** To define the installation procedure for installing strain reliefs in "smooth base" radomes.
- 2.0 Scope.** This installation procedure applies to fiberglass radomes having Sea Tel's standard four-hole mounting pattern, and M12 mounting hardware, in the 80-180 cm (34-66 in) nominal size range, typically referred to as "smooth" base radomes. It also applies to our larger 193 cm (76-inch) radome having a twelve-hole mounting pattern. It is to be used where the preferred center cable exit may not be desired.
- 3.0 Tools/materials.**
1. Electric drill.
 2. Small drill bit 1/8" dia. (3-4mm dia.).
 3. Hole saw, 1 3/8" dia. (35 mm), with mandrel and 1/4" dia. pilot drill.
 4. Medium file.
 5. Two 1-1/2" (38 mm) adjustable pliers.
 6. #2 Phillips screwdriver.
 7. Fiberglass resin & catalyst, (marine grade) - at least 2 oz (50 cc).
Such as Tap Plastics Marine Vinyl Ester Resin with MEKP Catalyst.
Note: Use liquid resin, instead of paste type, due to better penetration.
 8. Mixing cup – 4 oz (100 cc).
 9. Disposable brush.
 10. Strain Relief Assembly 124903-1, (one per cable).
- 4.0 Responsibilities.** It is the responsibility of the installer to observe all standard safety precautions, including eye, slip, and chemical protection when performing this procedure.

4.1 Procedure.

Remove the standard cable pass through assembly 130818-1*

* N/A for 193 cm (76-inch) nominal size radomes. Refer to Fig 1, then use #2 Phillips screwdriver to remove 4 ea. attachment screws.

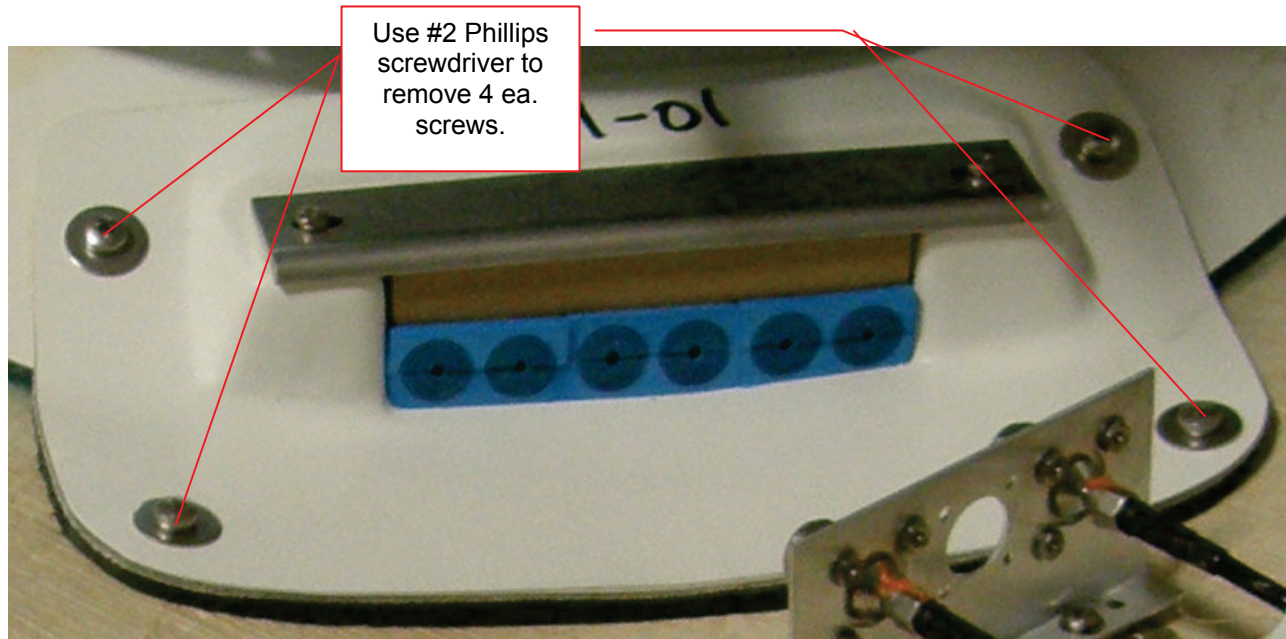


Fig. 1 – Cable pass-thru assembly

Procedure, Radome Strain Relief Installation

4.2 Making the holes

PLANNING: Space has been allowed for up to 5 ea. strain reliefs, but, install only as many as needed. (Typically only 2-3 for TX/RX systems). Refer to Fig 2 then plan which hole positions to use.

For 76-inch radomes lowest holes may be approx 1.5 inches from inside wall corner with floor (ref drawing 129416).

Note: The hole center-to-center distance given is the MINIMUM.

Follow good engineering practice and provide the largest spacing possible between holes as follows:

- 1 Hole pattern - "A".
- 2 Hole pattern - "B", "C".
- 3 Hole pattern - "A", "B", "C", ("A", "D", "E" PERMITTED).
- 4 Hole pattern - "B", "C", "D", "E".
- 5 Hole pattern - "A", "B", "C", "D", "E".

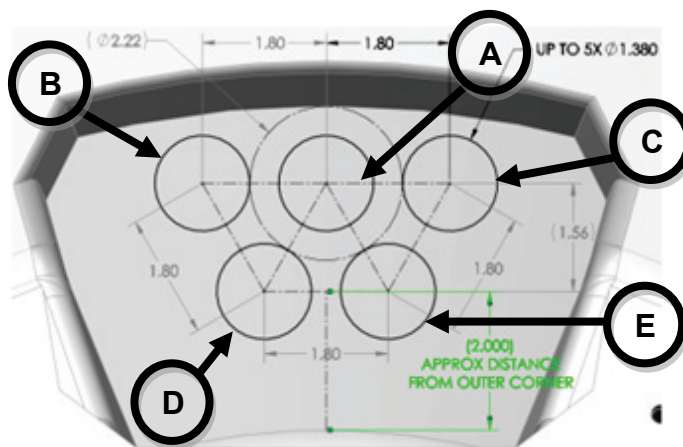


Fig. 2 – Planning
Measure in place or use
template drawing 132234



Fig. 3 – (Up to) 5-Hole Pattern

Procedure, Radome Strain Relief Installation

4.3 Measure, mark and drill pilot holes

CAUTION: The hole locations cannot be determined accurately from outside of the radome.

Using full scale drawing 132234, provided in the strain relief kit, measure mark and drill pilot holes from the inside out, and using only light pressure, use the small drill bit, (~1/8" dia) to make a pilot hole through each planned location.

4.4 Use the hole saw from the outside with light pressure.

CAUTION: Using the hole saw from the inside is likely to damage the Gel Coat.

CAUTION: Heavy pressure on the hole saw from the inside is likely to damage the Gel Coat and splinter the fiberglass.

Working from the outside, use a 1-3/8" hole saw to make the holes for the planned strain reliefs.

4.5 After holes are drilled CAREFULLY use a file to clean the hole edges.

4.6 Test fit the strain reliefs in each location, then, make adjustments as necessary.

4.7 Sealing the hole edges.

CAUTION: Cut edges can allow water and/or ice ingress and weaken the fiberglass laminate or structural foam. It is essential to seal all cut edges thoroughly with fiberglass resin to preserve the radome's structural strength.

CAUTION: Fiberglass paste or RTV silicone sealant will not wick into and seal the fiberglass strands as well as fiberglass resin, ONLY use fiberglass resin (such as TAP PLASTICS MARINE VINYL ESTER, or equivalent) for sealing the cut edges.

Follow the manufacturer's instructions to mix a small amount of fiberglass resin and catalyst, then working quickly, use a disposable brush to apply mixed fiberglass resin to the hole edges, both inside and out.

Allow the fiberglass resin to set per resin manufacturer's instructions.

Note: Like all chemical reactions, set time will be temperature/humidity dependent.

4.8 Refer to strain relief assembly drawing 124903

Being careful not to damage either the radome or the strain relief threads, use adjustable pliers to install strain reliefs.



Fig. 4 – Outside view.

Procedure, Radome Strain Relief Installation



Fig. 5 – Outside view.

4.9 Rotate General Assembly (G.A.)

Once cables have been installed, rotate General Assembly (G.A.), to ensure cables are routed properly and do not interfere with azimuth rotation.



Fig. 6 – Inside view.

5.0 Records. N/A.

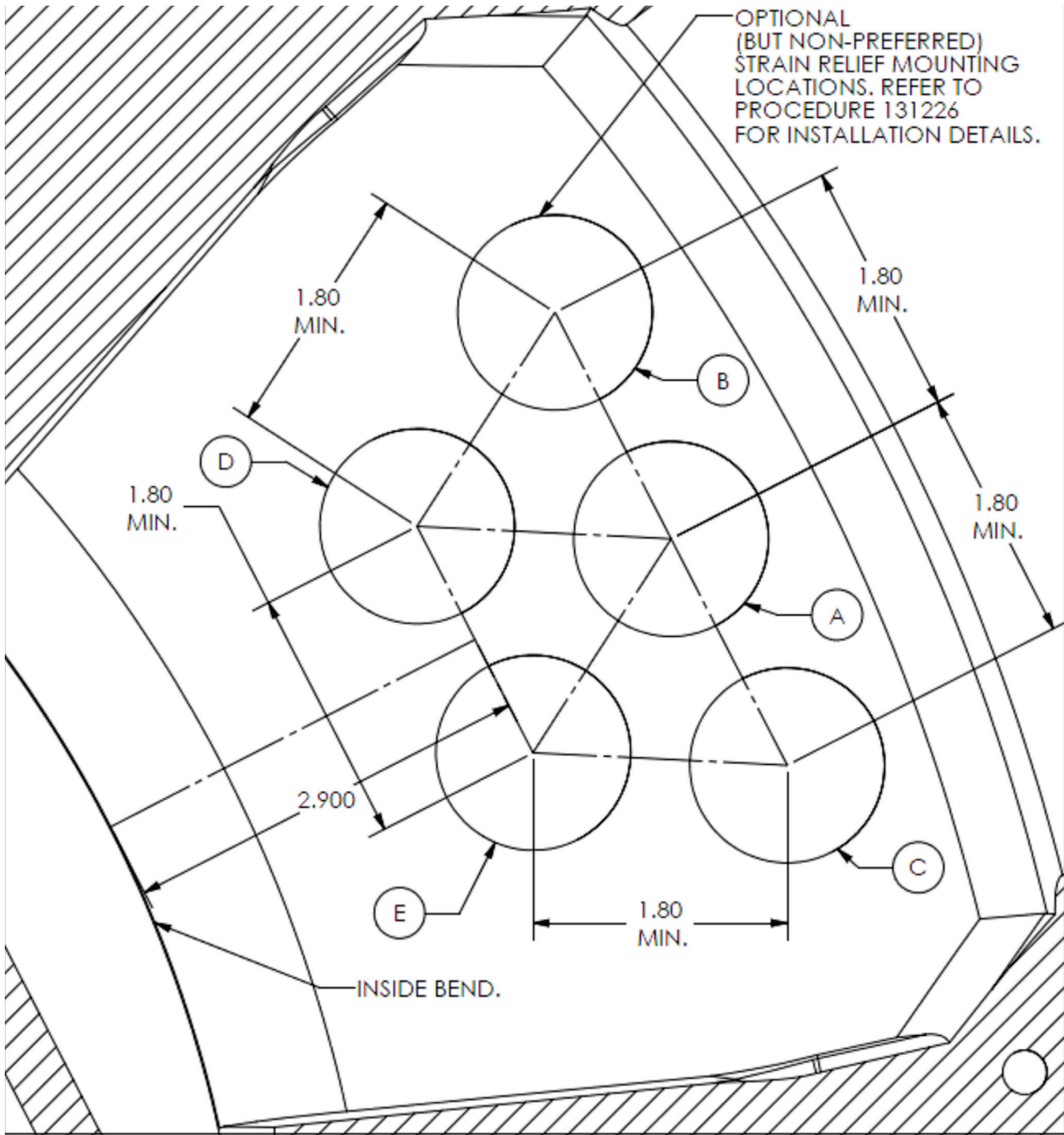
6.0 Training. N/A

7.0 References.

Strain relief assembly drawing (P/N: 124903)
Template drawing (P/N 132234)

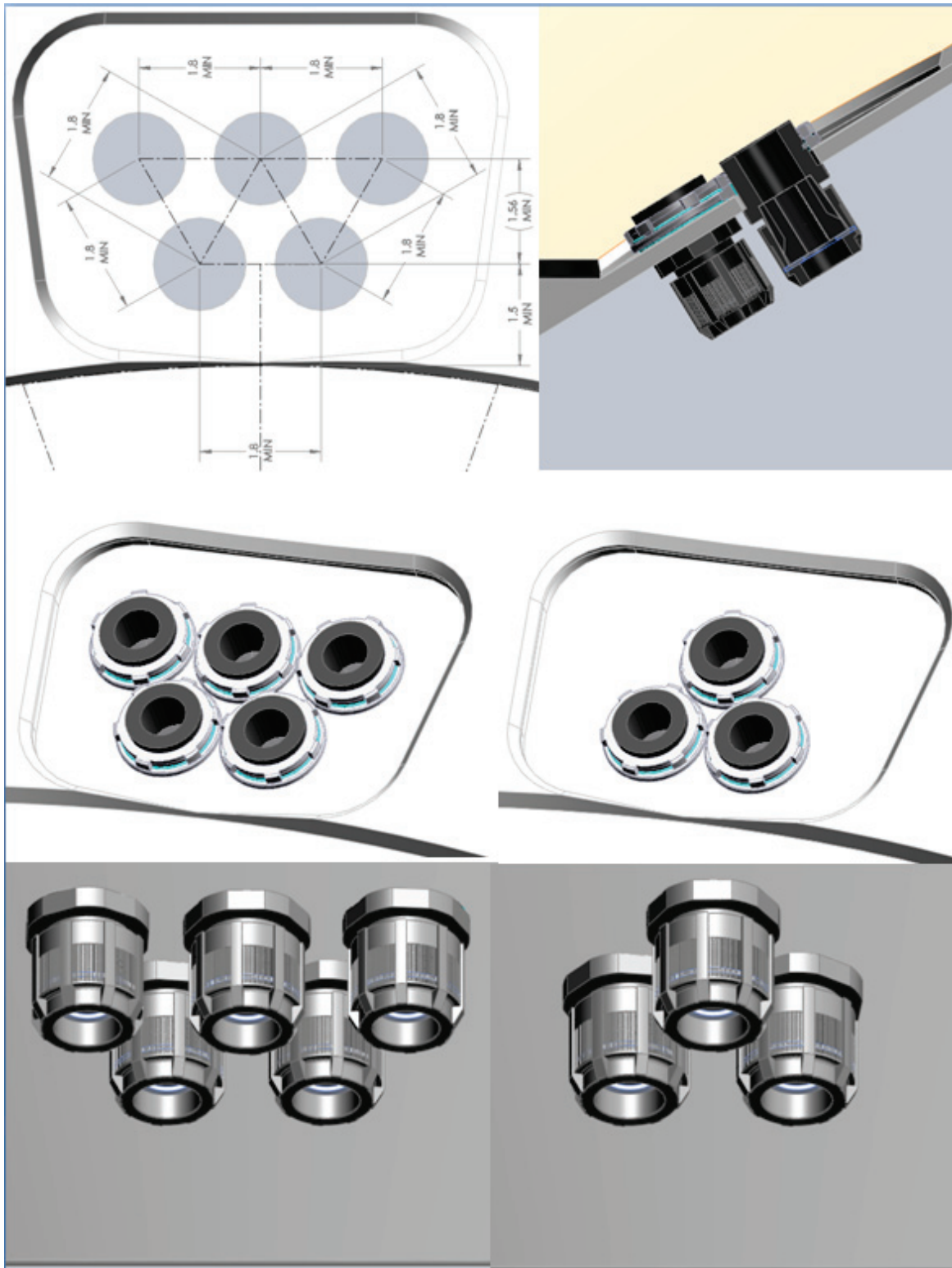
Procedure, Radome Strain Relief Installation

8.0 Strain relief positioning for 80-180 cm (34-66 in) smooth based radomes, (May use Sea Tel drawing 132234 as template.)



Procedure, Radome Strain Relief Installation

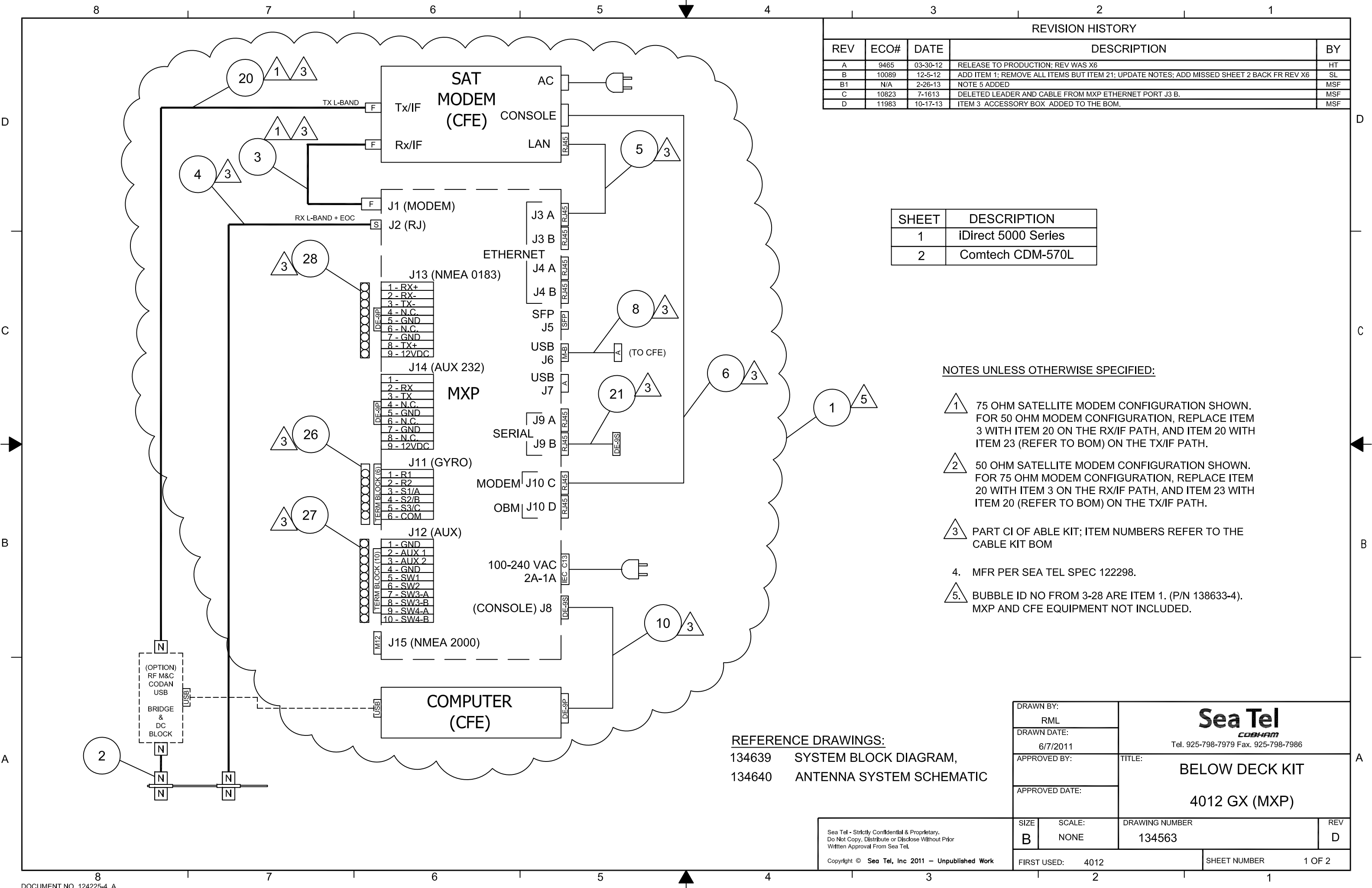
9.0 Strain relief positioning for 193 cm (76-inch) radomes. (May use Sea Tel drawing 132234 as template.)



SINGLE LEVEL MFG BILL OF MATERIAL

FIND	QTY	PART NO	REV	DESCRIPTION	REFERENCE DESIGNATOR
1	1 EA	138633-4	B	BDE CABLE KIT, 4012GX (MXP)	
2	1 EA	136872	A1	BRACKET ASS'Y, CONNECTOR, RACK MOUNT	
3	1 EA	139410	B	BOX, ACCESSORY	

<div> <div>Sea Tel</div> <div>COBHAM</div> </div>				
BELOW DECK KIT, MXP				
PROD FAMILY COMMON	EFF. DATE 11/8/2013	SHT 1 OF 1	DRAWING NUMBER 134563-1	REV D



REVISION HISTORY				
REV	ECO#	DATE	DESCRIPTION	BY
A	9465	03-30-12	RELEASE TO PRODUCTION; REV WAS X6	HT
B	10089	12-5-12	ADD ITEM 1; REMOVE ALL ITEMS BUT ITEM 21; UPDATE NOTES; ADD MISSED SHEET 2 BACK FR REV X6	SL
B1	N/A	2-26-13	NOTE 5 ADDED	MSF
C	10823	7-1613	DELETED LEADER AND CABLE FROM MXP ETHERNET PORT J3 B.	MSF
D	11983	10-17-13	ITEM 3 ACCESSORY BOX ADDED TO THE BOM.	MSF

SHEET	DESCRIPTION
1	iDirect 5000 Series
2	Comtech CDM-570L

NOTES UNLESS OTHERWISE SPECIFIED:

- 1

75 OHM SATELLITE MODEM CONFIGURATION SHOWN. FOR 50 OHM MODEM CONFIGURATION, REPLACE ITEM 3 WITH ITEM 20 ON THE RX/IF PATH, AND ITEM 20 WITH ITEM 23 (REFER TO BOM) ON THE TX/IF PATH.
- 2

50 OHM SATELLITE MODEM CONFIGURATION SHOWN. FOR 75 OHM MODEM CONFIGURATION, REPLACE ITEM 20 WITH ITEM 3 ON THE RX/IF PATH, AND ITEM 23 WITH ITEM 20 (REFER TO BOM) ON THE TX/IF PATH.
- 3

PART CI OF ABLE KIT; ITEM NUMBERS REFER TO THE CABLE KIT BOM
- 4

MFR PER SEA TEL SPEC 122298.
- 5

BUBBLE ID NO FROM 3-28 ARE ITEM 1. (P/N 138633-4). MXP AND CFE EQUIPMENT NOT INCLUDED.

REFERENCE DRAWINGS:

- 134639
- SYSTEM BLOCK DIAGRAM,
- 134640
- ANTENNA SYSTEM SCHEMATIC

DRAWN BY: RML		<div>Sea Tel</div> <div>COBHAM</div> <div>Tel. 925-798-7979 Fax. 925-798-7986</div> <div>BELOW DECK KIT</div> <div>4012 GX (MXP)</div>	
DRAWN DATE: 6/7/2011			
APPROVED BY:			
APPROVED DATE:			
SIZE B	SCALE: NONE	DRAWING NUMBER 134563	REV D
FIRST USED: 4012			SHEET NUMBER 1 OF 2

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