

Part 1 General

1.1 SUMMARY

- .1 Section Includes.
 - .1 Methods and procedures for start-up, verification and commissioning, for building Energy Monitoring and Control System (EMCS) and includes:
 - .1 Start-up testing and verification of systems.
 - .2 Check out demonstration or proper operation of components.
 - .3 On-site operational tests.
 - .2 Related Sections.
 - .1 Section 01 33 00 - Submittal Procedures.
 - .2 Section 01 35 29 - Health and Safety Requirements.
 - .3 Section 01 45 00 - Quality Control.
 - .4 Section 01 78 00 - Closeout Submittals.
 - .5 Section 25 05 01 - EMCS: General Requirements.

1.2 DEFINITIONS

- .1 For additional acronyms and definitions refer to Section 25 05 01 - EMCS: General Requirements.
- .2 AEL: ratio between total test periods less any system downtime accumulated within that period and test period.
- .3 Downtime: results whenever EMCS is unable to fulfill required functions due to malfunction of equipment defined under responsibility of EMCS contractor. Downtime is measured by duration, in time, between time that Contractor is notified of failure and time system is restored to proper operating condition. Downtime not to include following:
 - .1 Outage of main power supply in excess of back-up power sources, provided that:
 - .1 Automatic initiation of back-up was accomplished.
 - .2 Automatic shut-down and re-start of components was as specified.
 - .2 Failure of communications link, provided that:
 - .1 Controller automatically and correctly operated in stand-alone mode.
 - .2 Failure was not due to failure of any specified EMCS equipment.
 - .3 Functional failure resulting from individual sensor inputs or output devices, provided that:
 - .1 System recorded said fault.
 - .2 Equipment defaulted to fail-safe mode.
 - .3 AEL of total of all input sensors and output devices is at least 99 % during test period.

1.3 DESIGN REQUIREMENTS

- .1 Commissioning personnel to be fully aware of and qualified to interpret Design Criteria and Design Intents.

1.4 SUBMITTALS

- .1 Submittals in accordance with Section 01 33 00 - Submittal Procedures.
- .2 Final Report: submit report to Departmental Representative.
 - .1 Include measurements, final settings and certified test results.
 - .2 Bear signature of commissioning technician and supervisor
 - .3 Report format to be approved by Departmental Representative before commissioning is started.
 - .4 Revise "as-built" documentation, commissioning reports to reflect changes, adjustments and modifications to EMCS as set during commissioning and submit to Departmental Representative in accordance with Section 01 78 00 - Closeout Submittals.
 - .5 Recommend additional changes and/or modifications deemed advisable in order to improve performance, environmental conditions or energy consumption.

1.5 CLOSEOUT SUBMITTALS

- .1 Provide documentation, O&M Manuals, and training of O&M personnel for review of Departmental Representative before interim acceptance in accordance with Section 01 78 00 - Closeout Submittals.

1.6 COMMISSIONING

- .1 Carry out commissioning under direction of Departmental Representative.
- .2 Inform, and obtain approval from, Departmental Representative in writing at least 14 days prior to commissioning or each test. Indicate:
 - .1 Location and part of system to be tested or commissioned.
 - .2 Testing/commissioning procedures, anticipated results.
 - .3 Names of testing/commissioning personnel.
- .3 Correct deficiencies, re-test in presence of Departmental Representative until satisfactory performance is obtained.
- .4 Acceptance of tests will not relieve Contractor from responsibility for ensuring that complete systems meet every requirement of Contract.
- .5 Perform tests as required.

1.7 COMPLETION OF COMMISSIONING

- .1 Commissioning to be considered as satisfactorily completed when objectives of commissioning have been achieved and reviewed by Departmental Representative.

1.8 ISSUANCE OF FINAL CERTIFICATE OF COMPLETION

- .1 Final Certificate of Completion will not be issued until receipt of written approval indicating successful completion of specified commissioning activities including receipt of commissioning documentation.

Part 2 Products

2.1 EQUIPMENT

- .1 Provide sufficient instrumentation to verify and commission the installed system. Provide two-way radios.
- .2 Instrumentation accuracy tolerances: higher order of magnitude than equipment or system being tested.
- .3 Independent testing laboratory to certify test equipment as accurate to within approved tolerances no more than 2 months prior to tests.
- .4 Locations to be approved, readily accessible and readable.
- .5 Application: to conform to normal industry standards.

Part 3 Execution

3.1 PROCEDURES

- .1 Test each system independently and then in unison with other related systems.
- .2 Commission each system using procedures prescribed by the Commissioning Manager.
- .3 Commission integrated systems using procedures prescribed by Commissioning Manager.
- .4 Debug system software.
- .5 Optimize operation and performance of systems by fine-tuning PID values and modifying CDLs as required.

3.2 FIELD QUALITY CONTROL

- .1 Pre-Installation Testing.
 - .1 General: consists of field tests of equipment just prior to installation.
 - .2 Testing may be on site or at Contractor's premises as approved by Departmental Representative.
 - .3 Equip each Building Controller with sensor and controlled device of each type (AI, AO, DI, DO or B1, BO).
 - .4 Additional instruments to include:
 - .1 DP transmitters.

- .5 In addition to test equipment, provide inclined manometer, digital micro-manometer, milli-amp meter, source of air pressure infinitely adjustable between 0 and 500 Pa, to hold steady at any setting and with direct output to milli-amp meter at source.
- .6 After setting, test zero and span in 10 % increments through entire range while both increasing and decreasing pressure.
- .7 Transmitters above 0.5 % error will be rejected.
- .2 Completion Testing.
 - .1 General: test after installation of each part of system and after completion of mechanical and electrical hook-ups, to verify correct installation and functioning.
 - .2 Include following activities:
 - .1 Test and calibrate field hardware including stand-alone capability of each controller.
 - .2 Verify each A-to-D convertor.
 - .3 Test and calibrate each AI using calibrated digital instruments.
 - .4 Test each DI or BI to ensure proper settings and switching contacts.
 - .5 Test each DO or BO to ensure proper operation and lag time.
 - .6 Test each AO to ensure proper operation of controlled devices. Verify tight closure and signals.
 - .7 Test operating software.
 - .8 Test application software and provide samples of logs and commands.
 - .9 Debug software.
 - .10 Blow out flow measuring and static pressure stations with high pressure air at 700 kPa.
 - .11 Provide point verification list in table format including point identifier, point identifier expansion, point type and address, low and high limits and engineering units. Include space on commissioning technician and Departmental Representative. This document will be used in final start-up testing.
 - .3 Final Start-up Testing: Upon satisfactory completion of tests, perform point-by-point test of entire system under direction of Departmental Representative and provide:
 - .1 Technical personnel capable of re-calibrating field hardware and modifying software.
 - .2 Detailed daily schedule showing items to be tested and personnel available.
 - .3 Commissioning to commence during final start-up testing.
 - .4 O&M personnel to assist in commissioning procedures as part of training.
 - .5 Commissioning to be supervised by qualified supervisory personnel and Departmental Representative.
 - .6 Commission systems considered as life safety systems before affected parts of the facility are occupied.
 - .7 Operate systems as long as necessary to commission entire project.
 - .8 Monitor progress and keep detailed records of activities and results.

- .4 Final Operational Testing: to demonstrate that EMCS functions in accordance with contract requirements.
 - .1 Prior to beginning of 30 day test demonstrate that operating parameters (setpoints, alarm limits, operating control software, sequences of operation, trends, graphics and CDL's) have been implemented to ensure proper operation and operator notification in event of off-normal operation.
 - .1 Repetitive alarm conditions to be resolved to minimize reporting of nuisance conditions.
 - .2 Test to last at least 30 consecutive 24 hour days.
 - .3 Tests to include:
 - .1 Demonstration of correct operation of monitored and controlled points.
 - .2 Operation and capabilities of sequences, reports, special control algorithms, diagnostics, software.
 - .4 System will be accepted when:
 - .1 EMCS equipment operates to meet overall performance requirements. Downtime as defined in this Section must not exceed allowable time calculated for this site.
 - .2 Requirements of Contract have been met.
 - .5 In event of failure to attain specified AEL during test period, extend test period on day-to-day basis until specified AEL is attained for test period.
 - .6 Correct defects when they occur and before resuming tests.
- .5 Departmental Representative to verify reported results.

3.3 ADJUSTING

- .1 Final adjusting: upon completion of commissioning as reviewed by Departmental Representative, set and lock devices in final position and permanently mark settings.

3.4 DEMONSTRATION

- .1 Demonstrate Departmental Representative operation of systems including sequence of operations in regular and emergency modes, under normal and emergency conditions, start-up, shut-down interlocks and lock-outs in accordance with Section 01 79 00 - Demonstration and Training.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes.
 - .1 Requirements and procedures for training program, instructors and training materials, for building Energy Monitoring and Control System (EMCS) Work.
- .2 Related Sections.
 - .1 Section 01 33 00 - Submittal Procedures.
 - .2 Section 25 05 01 - EMCS: General Requirements.

1.2 DEFINITIONS

- .1 CDL - Control Description Logic.
- .2 For additional acronyms and definitions refer to Section 25 05 01 - EMCS: General Requirements.

1.3 SUBMITTALS

- .1 Submittals in accordance with Section 01 33 00 - Submittal Procedures, supplemented and modified by requirements of this Section.
- .2 Submit training proposal complete with hour-by-hour schedule including brief overview of content of each segment to Departmental Representative 30 days prior to anticipated date of beginning of training.
 - .1 List name of trainer, and type of visual and audio aids to be used.
 - .2 Show co-ordinated interface with other EMCS mechanical and electrical training programs.
- .3 Submit reports within one week after completion of Phase 1 and Phase 2 training program that training has been satisfactorily completed.

1.4 QUALITY ASSURANCE

- .1 Provide competent instructors thoroughly familiar with aspects of EMCS installed in facility.
- .2 Departmental Representative reserves right to approve instructors.

1.5 INSTRUCTIONS

- .1 Provide instruction to designated personnel in adjustment, operation, maintenance and pertinent safety requirements of EMCS installed.
- .2 Training to be project-specific.

1.6 TIME FOR INSTRUCTION

- .1 Number of days of instruction to be as specified in this section (1 day = 8 hours including two 15 minute breaks and excluding lunch time).

1.7 TRAINING MATERIALS

- .1 Provide equipment, visual and audio aids, and materials for classroom training.
- .2 Supply manual for each trainee, describing in detail data included in each training program.
 - .1 Review contents of manual in detail to explain aspects of operation and maintenance (O&M).

1.8 TRAINING PROGRAM

- .1 To be in 2 phases over 6 month period.
- .2 Phase 1: 1 day program to begin before 30 day test period at time mutually agreeable to Contractor, Departmental Representative.
 - .1 Train O&M personnel in functional operations and procedures to be employed for system operation.
 - .2 Supplement with on-the-job training during 30 day test period.
 - .3 Include overview of system architecture, communications, operation of computer and peripherals, report generation.
 - .4 Include detailed training on operator interface functions for control of mechanical systems, CDL's for each system, and elementary preventive maintenance.
- .3 Phase 2: 2 day program to begin 8 weeks after acceptance for operators, equipment maintenance personnel and programmers.
 - .1 Provide multiple instructors on pre-arranged schedule. Include at least following:
 - .1 Operator training: provide operating personnel, maintenance personnel and programmers with condensed version of Phase 1 training.
 - .2 Equipment maintenance training: provide personnel with 1 day training in maintenance of EMCS equipment, including general equipment layout, trouble shooting and preventive maintenance of EMCS components, maintenance and calibration of sensors and controls.
 - .3 Programmers: provide personnel with 1 day training in following subjects in approximate percentages of total course shown:
 - Software and architecture: 10%
 - Application programs: 15%
 - Controller programming: 50%
 - Trouble shooting and debugging: 10%
 - Colour graphic generation: 15%

1.9 ADDITIONAL TRAINING

- .1 List courses offered by name, duration and approximate cost per person per week. Note courses recommended for training supervisory personnel.

1.10 MONITORING OF TRAINING

- .1 Departmental Representative may monitor training program and may modify schedule and content.

Part 2 Products

2.1 NOT USED

- .1 Not Used.

Part 3 Execution

3.1 NOT USED

- .1 Not Used.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes:
 - .1 General requirements for building Energy Monitoring and Control System (EMCS) that are common to NMS EMCS Sections.
- .2 Related Sections:
 - .1 Section 01 33 00 - Submittal Procedures.
 - .2 Section 01 35 29.06 - Health and Safety Requirements.
 - .3 Section 01 45 00 - Quality Control.
 - .4 Section 01 78 00 - Closeout Submittals.
 - .5 Section 09 91 23 - Interior Painting.
 - .6 Section 25 05 02 - EMCS: Shop Drawings, Product Data and Review Process.
 - .7 Section 25 05 54 - EMCS: Identification.
 - .8 Section 25 90 01 - EMCS: Site Requirements Applications and Systems Sequences of Operation.

1.2 REFERENCES

- .1 American National Standards Institute (ANSI)/The Instrumentation, Systems and Automation Society (ISA).
 - .1 ANSI/ISA 5.5, Graphic Symbols for Process Displays.
- .2 American National Standards Institute (ANSI)/ Institute of Electrical and Electronics Engineers (IEEE).
 - .1 ANSI/IEEE 260.1-2005, American National Standard Letter Symbols Units of Measurement (SI Units, Customary Inch-Pound Units, and Certain Other Units).
- .3 American Society of Heating, Refrigerating and Air-Conditioning Engineers, Inc. (ASHRAE).
 - .1 ASHRAE STD 135-2016, BACNET - Data Communication Protocol for Building Automation and Control Network.
- .4 Canadian Standards Association (CSA International).
 - .1 CAN/CSA-Z234.1-00 (R2011), Canadian Metric Practice Guide.
- .5 Consumer Electronics Association (CEA).
 - .1 CEA-709.1-B-2014, Control Network Protocol Specification.
- .6 Health Canada/Workplace Hazardous Materials Information System (WHMIS).
 - .1 Material Safety Data Sheets (MSDS).

1.3 ACRONYMS AND ABBREVIATIONS

.1 Acronyms used in EMCS:

- .1 AEL - Average Effectiveness Level.
- .2 AI - Analog Input.
- .3 AIT - Agreement on International Trade.
- .4 AO - Analog Output.
- .5 BACnet - Building Automation and Control Network.
- .6 BC(s) - Building Controller(s).
- .7 BECC - Building Environmental Control Center.
- .8 CAD - Computer Aided Design.
- .9 CDL - Control Description Logic.
- .10 CDS - Control Design Schematic.
- .11 COSV - Change of State or Value.
- .12 CPU - Central Processing Unit.
- .13 DI or BI - Digital Input.
- .14 DO or BO - Digital Output.
- .15 DP - Differential Pressure.
- .16 ECU - Equipment Control Unit.
- .17 EMCS - Energy Monitoring and Control System.
- .18 HVAC - Heating, Ventilation, Air Conditioning.
- .19 IDE - Interface Device Equipment.
- .20 I/O - Input/Output.
- .21 ISA - Industry Standard Architecture.
- .22 LAN - Local Area Network.
- .23 LCU - Local Control Unit.
- .24 MCU - Master Control Unit.
- .25 NAFTA - North American Free Trade Agreement.
- .26 NC - Normally Closed.
- .27 NO - Normally Open.
- .28 OS - Operating System.
- .29 O&M - Operation and Maintenance.
- .30 OWS - Operator Work Station.
- .31 PC - Personal Computer.
- .32 PCI - Peripheral Control Interface.
- .33 PCMCIA - Personal Computer Micro-Card Interface Adapter.
- .34 PID - Proportional, Integral and Derivative.
- .35 RAM - Random Access Memory.
- .36 SP - Static Pressure.
- .37 ROM - Read Only Memory.
- .38 TCU - Terminal Control Unit.

- .39 USB - Universal Serial Bus.
- .40 UPS - Uninterruptible Power Supply.
- .41 VAV - Variable Air Volume.

1.4 DEFINITIONS

- .1 Point: may be logical or physical.
 - .1 Logical points: values calculated by system such as set points, totals, counts, derived corrections and may include, but not limited to result of and statements in CDL's.
 - .2 Physical points: inputs or outputs which have hardware wired to controllers which are measuring physical properties, or providing status conditions of contacts or relays which provide interaction with related equipment (stop, start) and valve or damper actuators.
- .2 Point Name: composed of two parts, point identifier and point expansion.
 - .1 Point identifier: comprised of three descriptors, "area" descriptor, "system" descriptor and "point" descriptor, for which database to provide 25-character field for each point identifier. "System" is system that point is located on.
 - .1 Area descriptor: building or part of building where point is located.
 - .2 System descriptor: system that point is located on.
 - .3 Point descriptor: physical or logical point description. For point identifier "area", "system" and "point" will be short forms or acronyms. Database must provide 25-character field for each point identifier.
 - .2 Point expansion: comprised of three fields, one for each descriptor. Expanded form of short form or acronym used in "area", "system" and "point" descriptors is placed into appropriate point expansion field. Database must provide 32-character field for each point expansion.
 - .3 Bilingual systems to include additional point identifier expansion fields of equal capacity for each point name for second language.
 - .1 System to support use of numbers and readable characters including blanks, periods or underscores to enhance user readability for each of the above strings.
- .3 Point Object Type: points fall into following object types:
 - .1 AI (analog input).
 - .2 AO (analog output).
 - .3 DI or BI (digital input).
 - .4 DO or BO (digital output).
 - .5 Pulse inputs.
- .4 Symbols and engineering unit abbreviations utilized in displays: to ANSI/ISA S5.5.
 - .1 Printouts: to ANSI/IEEE 260.1.
 - .2 Refer also to Section 25 05 54- EMCS: Identification.

1.5 SYSTEM DESCRIPTION

- .1 Refer to control schematics and for system architecture.
- .2 Work covered by sections referred to above consists of fully operational EMCS, including, but not limited to, following:
 - .1 Building Controllers.
 - .2 Control devices as listed in I/O point summary tables.
 - .3 OWS(s).
 - .4 Data communications equipment necessary to effect EMCS data transmission system.
 - .5 Field control devices.
 - .6 Software/Hardware complete with full documentation.
 - .7 Complete operating and maintenance manuals.
 - .8 Training of personnel.
 - .9 Acceptance tests, technical support during commissioning, full documentation.
 - .10 Wiring interface co-ordination of equipment supplied by others.
 - .11 Miscellaneous work as specified in these sections and as indicated.
- .3 Design Requirements:
 - .1 Design and provide conduit and wiring linking elements of system.
 - .2 Supply sufficient programmable controllers of types to meet project requirements. Quantity and points contents as reviewed by Departmental Representative prior to installation.
 - .3 Location of controllers as reviewed by Departmental Representative prior to installation.
 - .4 Provide utility power to EMCS and emergency power to EMCS as indicated.
 - .5 Metric references: in accordance with CAN/CSA Z234.1.
- .4 Language Operating Requirements:
 - .1 Provide English operator selectable access codes.
 - .2 Use non-linguistic symbols for displays on graphic terminals wherever possible. Other information to be in English.
 - .3 Operating system executive: provide primary hardware-to-software interface specified as part of hardware purchase with associated documentation to be in English.
 - .4 System manager software: include in English system definition point database, additions, deletions or modifications, control loop statements, use of high level programming languages, report generator utility and other OS utilities used for maintaining optimal operating efficiency.
 - .5 Include, in English:
 - .1 Input and output commands and messages from operator-initiated functions and field related changes and alarms as defined in CDL's or assigned limits (i.e. commands relating to day-to-day operating functions and not related to system modifications, additions, or logic re-definitions).

- .2 Graphic "display" functions, point commands to turn systems on or off, manually override automatic control of specified hardware points. To be in English at specified OWS and to be able to operate one terminal in English. Point name expansions in both languages.
- .3 Reporting function such as trend log, trend graphics, alarm report logs, energy report logs, maintenance generated logs.

1.6 SUBMITTALS

- .1 Make submittals in accordance with Section 01 33 00 - Submittal Procedures and 25 05 02 - EMCS: Shop Drawings, Product Data and Review Process.
- .2 Submit for review:
 - .1 Equipment list and systems manufacturers at time of bid tender within 48h within 10 days after award of contract.
- .3 Quality Control:
 - .1 Provide equipment and material from manufacturer's regular production, CSA certified, manufactured to standard quoted plus additional specified requirements.
 - .2 Where CSA certified equipment is not available submit such equipment to inspection authorities for special inspection and approval before delivery to site.
 - .3 Submit proof of compliance to specified standards with shop drawings and product data in accordance with Section 25 05 02 - EMCS: Shop Drawings, Product Data and Review Process. Label or listing of specified organization is acceptable evidence.
 - .4 In lieu of such evidence, submit certificate from testing organization, approved by Departmental Representative, certifying that item was tested in accordance with their test methods and that item conforms to their standard/code.
 - .5 For materials, whose compliance with organizational standards/codes/specifications is not regulated by organization using its own listing or label as proof of compliance, furnish certificate stating that material complies with applicable referenced standard or specification.
 - .6 Permits and fees: in accordance with general conditions of contract.
 - .7 Submit certificate of acceptance from authority having jurisdiction to Departmental Representative.
 - .8 Existing devices intended for re-use: submit test report.

1.7 QUALITY ASSURANCE

- .1 Have local office within 50 km of project staffed by trained personnel capable of providing instruction, routine maintenance and emergency service on systems,
- .2 Provide record of successful previous installations submitting tender showing experience with similar installations utilizing computer-based systems.
- .3 Have access to local supplies of essential parts and provide 7-year guarantee of availability of spare parts after obsolescence.

.4 Ensure qualified supervisory personnel continuously direct and monitor Work and attend site meetings.

.5 Health and Safety:

.1 Do construction occupational health and safety in accordance with Section 01 35 29.06 - Health and Safety Requirements.

1.8 DELIVERY, STORAGE AND HANDLING

.1 Waste Management and Disposal:

.1 Construction/Demolition Waste Management and Disposal: separate waste materials.

.2 Remove from site and dispose of packaging materials at appropriate recycling facilities.

.3 Collect and separate for disposal paper, plastic, polystyrene, corrugated cardboard packaging material in appropriate on-site bins for recycling in accordance with Waste Management Plan.

.4 Divert unused metal materials from landfill to metal recycling facility.

Part 2 Products

2.1 EQUIPMENT

.1 Control Network Protocol and Data Communication Protocol: to CEA 709.1 ASHRAE STD 135.

.2 Complete list of equipment and materials to be used on project and forming part of bid tender documents by adding manufacturer's name, model number and details of materials, and submit for approval.

2.2 ADAPTORS

.1 Provide adaptors between metric and imperial components.

Part 3 Execution

3.1 MANUFACTURER'S RECOMMENDATIONS

.1 Installation: to manufacturer's recommendations.

3.2 PAINTING

.1 Painting: in accordance with Section 09 91 23 - Interior Painting, supplemented as follows:

.1 Clean and touch up marred or scratched surfaces of factory finished equipment to match original finish.

- .2 Restore to new condition, finished surfaces too extensively damaged to be primed and touched up to make good.
- .3 Clean and prime exposed hangers, racks, fastenings, and other support components.
- .4 Paint unfinished equipment installed indoors to EEMAC 2Y-1.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes.
 - .1 Methods and procedures for shop drawings submittals, preliminary and detailed review process including review meetings, for building Energy Monitoring and Control System (EMCS).
- .2 Related Sections.
 - .1 Section 01 33 00 - Submittal Procedures.
 - .2 Section 25 05 01 - EMCS: General Requirements.
 - .3 Section 25 01 11 - EMCS: Start-up, Verification and Commissioning.

1.2 DEFINITIONS

- .1 Acronyms and definitions: refer to Section 25 05 01 - EMCS: General Requirements.

1.3 DESIGN REQUIREMENTS

- .1 Preliminary Design Review: to contain following contractor and systems information.
 - .1 Location of office.
 - .2 Description and location of installing and servicing technical staff.
 - .3 Location and qualifications of programming design and programming support staff.
 - .4 List of spare parts.
 - .5 Location of spare parts stock.
 - .6 Names of sub-contractors and site-specific key personnel.
 - .7 Sketch of site-specific system architecture.
 - .8 Specification sheets for each item including memory provided, programming language, speed, type of data transmission.
 - .9 Descriptive brochures.
 - .10 Sample CDL and graphics (systems schematics).
 - .11 Response time for each type of command and report.
 - .12 Item-by-item statement of compliance.
 - .13 Proof of demonstrated ability of system to communicate utilizing BACnet.

1.4 SUBMITTALS

- .1 Submittals in accordance with Section 01 33 00 - Submittal Procedure and coordinate with requirements in this Section.
- .2 Submit preliminary design document within 5 working days after tender closing and before contract award, for review by Departmental Representative.

- .3 Shop Drawings to consist of 3 hard copies of design documents, shop drawings, product data and software.
- .4 Hard copy to be completely indexed and coordinated package to assure compliance with contract requirements and arranged in same sequence as specification and cross-referenced to specification section and paragraph number.

1.5 PRELIMINARY SHOP DRAWING REVIEW

- .1 Submit preliminary shop drawings within 30 working days of award of contract and include following:
 - .1 Specification sheets for each item. To include manufacturer's descriptive literature, manufacturer's installation recommendations, specifications, drawings, diagrams, performance and characteristic curves, catalogue cuts, manufacturer's name, trade name, catalogue or model number, nameplate data, size, layout, dimensions, capacity, other data to establish compliance.
 - .2 Detailed system architecture showing all points associated with each controller including, signal levels, pressures where new EMCS ties into existing control equipment.
 - .3 Spare point capacity of each controller by number and type.
 - .4 Controller locations.
 - .5 Auxiliary control cabinet locations.
 - .6 Single line diagrams showing cable routings, conduit sizes, spare conduit capacity between control centre, field controllers and systems being controlled.
 - .7 Dampers: sketches showing module assembly, interconnecting hardware, operator locations, operator spring range, pilot range, required torque, actual torque.

1.6 DETAIL SHOP DRAWING REVIEW

- .1 Submit detailed shop drawings within 60 working days after award of contract and before start of installation and include following:
 - .1 Corrected and updated versions (hard copy only) of submissions made during preliminary review.
 - .2 Wiring diagrams.
 - .3 Piping diagrams and hook-ups.
 - .4 Interface wiring diagrams showing termination connections and signal levels.
 - .5 Shop drawings for each input/output point, sensors, transmitters, showing information associated with each particular point including:
 - .1 Sensing element type and location.
 - .2 Transmitter type and range.
 - .3 Associated field wiring schematics, schedules and terminations.
 - .4 Complete Point Name Lists.
 - .5 Setpoints, curves or graphs and alarm limits (high and low, 3 types critical, cautionary and maintenance), signal range.
 - .6 Software and programming details associated with each point.
 - .7 Manufacturer's recommended installation instructions and procedures.

- .8 Input and output signal levels or pressures where new system ties into existing control equipment.
- .6 Control schematics, narrative description, CDL's fully showing and describing automatic and manual procedure required to achieve proper operation of project, including under complete failure of EMCS.
- .7 Graphic system schematic displays of air and water systems with point identifiers and textual description of system, and typical floor plans.
- .8 Listing of time of day schedules.
- .9 Mark up to-scale construction drawing to detail control room showing location of equipment and operator work space.
- .10 Type and size of memory with statement of spare memory capacity.
- .11 Full description of software programs provided.
- .12 Sample of "Operating Instructions Manual" to be used for training purposes.
- .13 Outline of proposed start-up and verification procedures. Refer to Section 25 01 11 - EMCS: Start-up, Verification and Commissioning.

1.7 QUALITY ASSURANCE

- .1 Preliminary Design Review Meeting: Convene meeting within 45 working days of award of contract to:
 - .1 Undertake functional review of preliminary design documents, resolve inconsistencies.
 - .2 Resolve conflicts between contract document requirements and actual items (e.g.: points list inconsistencies).
 - .3 Review interface requirements of materials supplied by others.
 - .4 Review "Sequence of Operations".
- .2 Departmental Representative retains right to revise sequence or subsequent CDL prior to software finalization without cost to Departmental Representative.

Part 2 Products

2.1 NOT USED

- .1 Not Used.

Part 3 Execution

3.1 NOT USED

- .1 Not Used.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes.
 - .1 Requirements and procedures for final control diagrams and operation and maintenance (O&M) manual and Control System (EMCS) Work.
- .2 Related Sections.
 - .1 Section 01 78 00 - Closeout Submittals.
 - .2 Section 25 05 01 - EMCS: General Requirements.
 - .3 Section 25 05 02 - EMCS: Submittals and Review Process.
 - .4 Section 25 01 11 - EMCS: Start-up, Verification and Commissioning.

1.2 DEFINITIONS

- .1 For acronyms and definitions refer to Section 25 05 01 - EMCS: General Requirements.

1.3 SUBMITTALS

- .1 Submittals in accordance with Section 01 78 00 - Closeout Procedures, supplemented and modified by requirements of this Section.
- .2 Submit Record Documents, As-built drawings, Operation and Maintenance Manual to Departmental Representative in English.
- .3 Provide soft copies and hard copies in hard-back, 50 mm 3 ring, D-ring binders.
 - .1 Binders to be 2/3 maximum full.
 - .2 Provide index to full volume in each binder.
 - .3 Identify contents of each manual on cover and spine.
 - .4 Provide Table of Contents in each manual.
 - .5 Assemble each manual to conform to Table of Contents with tab sheets placed before instructions covering subject.

1.4 AS-BUILTS

- .1 Provide 1 copy of detailed shop drawings generated in Section 25 05 02 - EMCS: Submittals and Review Process and include:
 - .1 Changes to contract documents as well as addenda and contract extras.
 - .2 Changes to interface wiring.
 - .3 Routing of conduit and wiring associated with EMCS installation.
 - .4 Locations of obscure devices to be indicated on drawings.
 - .5 Listing of alarm messages.
 - .6 Panel/circuit breaker number for sources of normal/emergency power.

- .7 Names, addresses, telephone numbers of each sub-contractor having installed equipment, local representative for each item of equipment, each system.
- .8 Test procedures and reports: provide records of start-up procedures, test procedures, checkout tests and final commissioning reports as specified in Section 25 01 11 - EMCS: Start-up, Verification and Commissioning.
- .9 Basic system design and full documentation on system configuration.
- .2 Submit for final review by Departmental Representative.
- .3 Provide before acceptance 3 Hard and 1 soft copy incorporating changes made during final review.

1.5 O&M MANUALS

- .1 Custom design O&M Manuals (both hard and soft copy) to contain material pertinent to this project only, and to provide full and complete coverage of subjects referred to in this Section.
- .2 Provide 2 complete sets of hard and soft copies prior to system or equipment tests
- .3 Include complete coverage in concise language, readily understood by operating personnel using common terminology of functional and operational requirements of system. Do not presume knowledge of computers, electronics or in-depth control theory.
- .4 Functional description to include:
 - .1 Functional description of theory of operation.
 - .2 Design philosophy.
 - .3 Specific functions of design philosophy and system.
 - .4 Full details of data communications, including data types and formats, data processing and disposition data link components, interfaces and operator tests or self-test of data link integrity.
 - .5 Explicit description of hardware and software functions, interfaces and requirements for components in functions and operating modes.
 - .6 Description of person-machine interactions required to supplement system description, known or established constraints on system operation, operating procedures currently implemented for implementation in automatic mode.
- .5 System operation to include:
 - .1 Complete step-by-step procedures for operation of system including required actions at each OWS.
 - .2 Operation of computer peripherals, input and output formats.
 - .3 Emergency, alarm and failure recovery.
 - .4 Step-by-step instructions for start-up, back-up equipment operation, execution of systems functions and operating modes, including key strokes for each command so that operator need only refer to these pages for keystroke entries required to call up display or to input command.
- .6 Software to include:

- .1 Documentation of theory, design, interface requirements, functions, including test and verification procedures.
- .2 Detailed descriptions of program requirements and capabilities.
- .3 Data necessary to permit modification, relocation, reprogramming and to permit new and existing software modules to respond to changing system functional requirements without disrupting normal operation.
- .4 Software modules, fully annotated source code listings, error free object code files ready for loading via peripheral device
- .5 Complete program cross reference plus linking requirements, data exchange requirements, necessary subroutine lists, data file requirements, other information necessary for proper loading, integration, interfacing and program execution.
- .6 Software for each Controller and single section referencing Controller common parameters and functions.
- .7 Maintenance: document maintenance procedures including inspection, periodic preventive maintenance, fault diagnosis, repair or replacement of defective components, including calibration, maintenance, repair of sensors, transmitters, transducers, controller and interface firmware's, plus diagnostics and repair/replacement of system hardware.
- .8 System configuration document:
 - .1 Provisions and procedures for planning, implementing and recording hardware and software modifications required during operating lifetime of system.
 - .2 Information to ensure co-ordination of hardware and software changes, data link or message format/content changes, sensor or control changes in event that system modifications are required.
- .9 Programmer control panel documentation: provide where panels are independently interfaced with BECC, including interfacing schematics, signal identification, timing diagrams and fully commented source listing of applicable driver/handler.

Part 2 Products

2.1 NOT USED

- .1 Not Used.

Part 3 Execution

3.1 NOT USED

- .1 Not Used.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes.
 - .1 Requirements and procedures for identification of devices, sensors, wiring tubing, conduit and equipment, for building Energy Monitoring and Control System (EMCS) Work and nameplates materials, colours and lettering sizes.
- .2 Related Sections.
 - .1 Section 01 33 00 - Submittal Procedures.
 - .2 Section 25 05 01 - EMCS: General Requirements.

1.2 REFERENCES

- .1 Canadian Standards Association (CSA International).
 - .1 CSA C22.1-15, The Canadian Electrical Code, Part I (19th Edition), Safety Standard for Electrical Installations.

1.3 DEFINITIONS

- .1 For acronyms and definitions refer to Section 25 05 01 - EMCS: General Requirements.

1.4 SYSTEM DESCRIPTION

- .1 Language Operating Requirements: provide identification for control items in English.

1.5 SUBMITTALS

- .1 Submittals in accordance with Section 01 33 00 - Submittal Procedures supplemented and modified by requirements of this Section.
- .2 Submit to Departmental Representative for approval samples of nameplates, identification tags and list of proposed wording.

Part 2 Products

2.1 NAMEPLATES FOR PANELS

- .1 Identify by Plastic laminate, 3 mm thick Melamine, matt white finish, black core, square corners, lettering accurately aligned and engraved into core.
- .2 Sizes: 25 x 67 mm minimum.
- .3 Lettering: minimum 7 mm high, black.
- .4 Inscriptions: machine engraved to identify function.

2.2 NAMEPLATES FOR FIELD DEVICES

- .1 Identify by plastic encased cards attached by plastic tie.
- .2 Sizes: 50 x 100 mm minimum.
- .3 Lettering: minimum 5 mm high produced from laser printer in black.
- .4 Data to include: point name and point address.
- .5 Companion cabinet: identify interior components using plastic enclosed cards with point name and point address.

2.3 NAMEPLATES FOR ROOM SENSORS

- .1 Identify by stick-on labels using point identifier.
- .2 Letter size: to suit, clearly legible.

2.4 WARNING SIGNS

- .1 Equipment including motors, starters under remote automatic control: supply and install orange coloured signs warning of automatic starting under control of EMCS.
- .2 Sign to read: "Caution: This equipment is under automatic remote control of EMCS".

2.5 WIRING

- .1 Supply and install numbered tape markings on wiring at panels, junction boxes, splitters, cabinets and outlet boxes.
- .2 Colour coding: to CSA C22.1. Use colour coded wiring in communications cables, matched throughout system.
- .3 Power wiring: identify circuit breaker panel/circuit breaker number inside each EMCS panel.

2.6 CONDUIT

- .1 Colour code EMCS conduit.
- .2 Pre-paint box covers and conduit fittings.
- .3 Coding: use paint and confirm colour with Departmental Representative during "Preliminary Design Review".

Part 3 Execution

3.1 NAMEPLATES AND LABELS

- .1 Ensure that manufacturer's nameplates, CSA labels and identification nameplates are visible and legible at all times.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes.
 - .1 Requirements and procedures for warranty and activities during warranty period and service contracts, for building Energy Monitoring and Control System (EMCS).
- .2 Related Sections.
 - .1 Section 01 33 00 - Submittal Procedures.
 - .2 Section 01 78 00 - Closeout Submittals.
 - .3 Section 25 05 01 - EMCS: General Requirements.

1.2 DEFINITIONS

- .1 BC(s) - Building Controller(s).
- .2 OWS - Operator Work Station.
- .3 For additional acronyms and definitions refer to Section 25 05 01 - EMCS: General Requirements.

1.3 SUBMITTALS

- .1 Submittals in accordance with Section 01 33 00 - Submittal Procedures.
- .2 Submit detailed preventative maintenance schedule for system components to Departmental Representative.
- .3 Submit detailed inspection reports to Departmental Representative.
- .4 Submit dated, maintenance task lists to Departmental Representative and include the following sensor and output point detail, as proof of system verification:
 - .1 Point name and location.
 - .2 Device type and range.
 - .3 Measured value.
 - .4 System displayed value.
 - .5 Calibration detail
 - .6 Indication if adjustment required,
 - .7 Other action taken or recommended.
- .5 Submit network analysis report showing results with detailed recommendations to correct problems found.
- .6 Records and logs: in accordance with Section 01 78 00 - Closeout Submittals.
 - .1 Maintain records and logs of each maintenance task on site.

- .2 Organize cumulative records for each major component and for entire EMCS chronologically.
- .3 Submit records to Departmental Representative, after inspection indicating that planned and systematic maintenance have been accomplished.
- .7 Revise and submit to Departmental Representative in accordance with Section 01 78 00 - Closeout Submittals, "As-built drawings" documentation and commissioning reports to reflect changes, adjustments and modifications to EMCS made during warranty period.

1.4 MAINTENANCE SERVICE DURING WARRANTY PERIOD

- .1 Provide services, materials, and equipment to maintain EMCS for specified warranty period. Provide detailed preventative maintenance schedule for system components as described in Submittal article.
- .2 Emergency Service Calls:
 - .1 Initiate service calls when EMCS is not functioning correctly.
 - .2 Qualified control personnel to be available during warranty period to provide service to "CRITICAL" components whenever required at no extra cost.
 - .3 Furnish Departmental Representative with telephone number where service personnel may be reached at any time.
 - .4 Service personnel to be on site ready to service EMCS within 2 hours after receiving request for service.
 - .5 Perform Work continuously until EMCS restored to reliable operating condition.
- .3 Operation: foregoing and other servicing to provide proper sequencing of equipment and satisfactory operation of EMCS based on original design conditions and as recommended by manufacturer.
- .4 Work requests: record each service call request, when received separately on approved form and include:
 - .1 Serial number identifying component involved.
 - .2 Location, date and time call received.
 - .3 Nature of trouble.
 - .4 Names of personnel assigned.
 - .5 Instructions of work to be done.
 - .6 Amount and nature of materials used.
 - .7 Time and date work started.
 - .8 Time and date of completion.
- .5 Provide system modifications in writing.
 - .1 No system modification, including operating parameters and control settings, to be made without prior written approval of Departmental Representative.

1.5 SERVICE CONTRACTS

- .1 Provide in-depth technical expertise and assistance to Departmental Representative and Commissioning Manager in preparation and implementation of service contracts and in-house preventive maintenance procedures.

Part 2 Products

2.1 NOT USED

- .1 Not Used.

Part 3 Execution

3.1 FIELD QUALITY CONTROL

- .1 Perform as minimum (3) three minor inspections and one major inspection (more often if required by manufacturer) per year. Provide detailed written report to Departmental Representative as described in Submittal article.
- .2 Perform inspections during regular working hours, 0800 to 1630 h, Monday through Friday, excluding statutory holidays.
- .3 Following inspections are minimum requirements and should not be interpreted to mean satisfactory performance:
 - .1 Perform calibrations using test equipment having traceable, certifiable accuracy at minimum 50% greater than accuracy of system displaying or logging value.
 - .2 Check and Calibrate each field input/output device.
 - .3 Provide dated, maintenance task lists, as described in Submittal article, as proof of execution of complete system verification.
- .4 Minor inspections to include, but not limited to:
 - .1 Perform visual, operational checks to BC's, peripheral equipment, interface equipment and other panels.
 - .2 Check equipment cooling fans as required.
 - .3 Visually check for mechanical faults, air leaks and proper pressure settings on pneumatic components.
 - .4 Review system performance with Operations Supervisor to discuss suggested or required changes.
- .5 Major inspections to include, but not limited to:
 - .1 Minor inspection.
 - .2 Clean OWS(s) peripheral equipment, BC(s), interface and other panels, micro-processor interior and exterior surfaces.
 - .3 Check signal, voltage and system isolation of BC(s), peripherals, interface and other panels.

- .4 Verify calibration/accuracy of each input and output device and recalibrate or replace as required.
- .5 Provide mechanical adjustments, and necessary maintenance on printers.
- .6 Run system software diagnostics as required.
- .7 Install software and firmware enhancements to ensure components are operating at most current revision for maximum capability and reliability.
 - .1 Perform network analysis and provide report as described in Submittal article.
- .6 Rectify deficiencies revealed by maintenance inspections and environmental checks.
- .7 Continue system debugging and optimization.
- .8 Testing/verification of occupancy and seasonal-sensitive systems to take place during four (4) consecutive seasons, after facility has been accepted, taken over and fully occupied.
 - .1 Test weather-sensitive systems twice: first at near winter design conditions and secondly under near summer design conditions.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes:
 - .1 System requirements for Local Area Network (LAN) for Building Energy Monitoring and Control System (EMCS).

1.2 REFERENCES

- .1 Canadian Standards Association (CSA International).
 - .1 CSA T529-95(R2000), Telecommunications Cabling Systems in Commercial Buildings (Adopted ANSI/TIA/EIA-568-A with modifications).
 - .2 CSA T530-[99(R2004)], Commercial Building Standard for Telecommunications Pathways and Spaces (Adopted ANSI/TIA/EIA-569-A with modifications).
- .2 Institute of Electrical and Electronics Engineers (IEEE)/Standard for Information technology - Telecommunications and information exchange between systems - Local and metropolitan area networks - Specific requirements.
 - .1 IEEE Std 802.3-2015, Standard for Ethernet.
- .3 Telecommunications Industries Association (TIA)/Electronic Industries Alliance (EIA)
 - .1 TIA/EIA-568-2009, Commercial Building Telecommunications Cabling Standards Set, Part 1 General Requirements Part 2 Balanced Twisted-Pair Cabling Components Part 3 Optical Fiber Cabling Components Standard.
 - .2 TIA/EIA-569-A-2001, Commercial Building Standard for Telecommunications Pathways and Spaces.
- .4 Treasury Board Information Technology Standard (TBITS).
 - .1 TBITS 6.9-2000, Profile for the Telecommunications Wiring System in Government Owned and Leased Buildings - Technical Specifications.

1.3 DEFINITIONS

- .1 Acronyms and definitions: refer to Section 25 05 01 - EMCS - General Requirements.

1.4 SYSTEM DESCRIPTION

- .1 Data communication network to link Operator Workstations and Master Control Units (MCU) in accordance with TIA/EIA-568, TIA/EIA-569-A, TBITS 6.9.
 - .1 Provide reliable and secure connectivity of adequate performance between different sections (segments) of network.
 - .2 Allow for future expansion of network, with selection of networking technology and communication protocols.
- .2 Data communication network to include, but not limited to:
 - .1 EMCS-LAN.
 - .2 Modems.

- .3 Network interface cards.
- .4 Network management hardware and software.
- .5 Network components necessary for complete network.

1.5 DESIGN REQUIREMENTS

- .1 EMCS Local Area Network (EMCS-LAN).
 - .1 High speed, high performance, local area network over which MCUs and OWSs communicate with each other directly on peer to peer basis in accordance with IEEE 802.3/Ethernet Standard.
 - .2 EMCS-LAN to: BACnet.
 - .3 Each EMCS-LAN to be capable of supporting at least 50 devices.
 - .4 Support of combination of MCUs and OWSs directly connected to EMCS-LAN.
 - .5 High speed data transfer rates for alarm reporting, quick report generation from multiple controllers, upload/download information between network devices. Bit rate to be 10 Megabits per second minimum.
 - .6 Detection and accommodation of single or multiple failures of either OWSs, MCUs or network media. Operational equipment to continue to perform designated functions effectively in event of single or multiple failures.
 - .7 Commonly available, multiple sourced, networking components and protocols to allow system to co-exist with other networking applications including office automation.
- .2 Dynamic Data Access.
 - .1 LAN to provide capabilities for OWSs, either network resident or connected remotely, to access point status and application report data or execute control functions for other devices via LAN.
 - .2 Access to data to be based upon logical identification of building equipment.
- .3 Network Medium.
 - .1 Network medium: twisted cable, shielded twisted cable, fibre optic cable compatible with network protocol to be used within buildings.

Part 2 Products

2.1 NOT USED

- .1 Not Used.

Part 3 Execution

3.1 NOT USED

- .1 Not Used.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes:
 - .1 Hardware and software requirements for an Operator Work Station (OWS) in a Building Energy Monitoring and Control System (EMCS).

1.2 DEFINITIONS

- .1 Acronyms and definitions: refer to Section 25 05 01 - EMCS: General Requirements.

1.3 OWS SYSTEM DESCRIPTION

- .1 Consists of commercially available personal computer in current production, with sufficient memory and processor capacity to perform functions specified.
- .2 Primary OWS to include:
 - .1 Colour graphics printer.
 - .2 Modem.
 - .3 Desks, furniture.

1.4 ACTION AND INFORMATIONAL SUBMITTALS

- .1 Make submittals in accordance with Section 25 05 02 - EMCS: Shop Drawings, Product Data and Review Process.

1.5 ENVIRONMENTAL CONDITIONS

- .1 OWS to operate in conditions of 10 degrees C to 32 degrees C and 20 % to 90 % non-condensing RH.

1.6 MAINTENANCE

- .1 Provide maintenance in accordance with Section 25 05 03 - EMCS: Project Record Documents.

Part 2 Products

2.1 OWS HARDWARE

- .1 PC system to include:
 - .1 Processor: Intel Pentium micro-processor, operating at minimum clock speed of 2.3 Gigahertz, capable of supporting software necessary to perform functions specified in this section.
 - .2 Internal clock.
 - .1 Uninterruptible clock: accuracy of plus or minus 5 seconds/month, capable of deriving year / month / day / hour / minute / second.

- .2 Rechargeable batteries: to provide minimum 48 h clock operation in event of power failure.
- .3 Asynchronous interfaces for connection to listed peripheral devices including LAN and remote devices.
- .2 Power supply unit to accept 120 V / 60 Hz source and include line surge and low voltage protection for processor and its peripherals.
- .3 Include UPS to provide 5 minutes minimum operation of PC, CRT and communication and peripheral devices; applies to fixed (non-portable) OWS and peripherals.

2.2 OWS PC COMPONENTS

- .1 Primary OWS: PC compatible with following as minimum:
 - .1 IDE Disk drive controller to support:
 - .1 1 TB hard disk drive, 5400 RPM.
 - .2 Optical drive, read/write DVD/CD.
 - .2 2 MB cache, 2.3 GHz processor.
 - .3 8 GB, DDR4, 2400 MHz memory.
 - .4 Windows 10, 64 Bit English operating system.
 - .5 Intel HD graphics video card.
 - .6 Waves MaxxAudio Pro sound card for Windows.
 - .7 802.11 ac + Bluetooth 4.2, dual band 2.4 & 5 GHz wireless.
 - .8 Enhanced keyboard.
 - .9 Dual button wired mouse.
 - .10 Colour monitor: 21.5 inch FHD, anti-glare LED backlit Display with wide viewing angle (IPS), non-touch.
 - .11 Parallel Ports to support printer.
 - .12 2 USB ports.
 - .13 Include two 2 spare expansion slots in system for PWGSC's use.
 - .14 PCI Ethernet LAN Adapter to connect to local Ethernet LAN network.
 - .15 power supply.

2.3 PRINTERS

- .1 Colour graphics printer include following features:
 - .1 Ink-jet technology capable of printing high quality colour images at speed of 4 pages per minute.
 - .2 Black cartridge to be separate cartridge from red green blue cartridge.
 - .3 Minimum colour resolution 2400 by 1200 dpi.
 - .4 Minimum black and white resolution 1200 by 1200 dpi.
 - .5 Minimum 8 MB RAM.
- .2 Include one box of 8.5 X 11" and one box of 8.5 X 14" paper.

2.4 CONTROL DESK CONSOLE

- .1 Capable of accommodating OWS and peripheral equipment specified with provision for operator desk work space.
- .2 Provide printer rack or separate desk for printer as directed by Departmental Representative.
- .3 Layout: as directed by Departmental Representative.
- .4 Desk: steel office type, standard sizes 1 m x 2 m, factory-made, computer type, for equipment mounting, with drawers on one side.
 - .1 Keyboards to be in separate pull-out drawer.
 - .2 Include above desk shelving to support contractor supplied manuals.
- .5 Chair: upholstered, swivel type, with adjustable arms, back and seat, pneumatic seat height adjustment and 5 castors.

2.5 OPERATING SYSTEM (OS) OR EXECUTIVE

- .1 OS to support complement of hardware terminals and software programs specified.
- .2 OS to be true multitasking operating environment.
 - .1 MS DOS or PC DOS based software platforms not permitted.
- .3 OWS software to operate in "Windows" based operating environment: Windows XP or Unix "X" Windows based system.

2.6 OWS CONTROL SOFTWARE

- .1 OWS is not to form part of real-time control functions either directly or indirectly or as part of communication link. Real-time control functions to reside in MCUs, LCUs, and TCUs with peer to peer communication occurring at MCU to MCU device level.
- .2 Time Synchronization Module.
 - .1 System to provide Time Synchronization of real-time clocks in controllers.
 - .2 System to perform this feature on regular scheduled basis and on operator request.
- .3 User Display Interface Module.
 - .1 OWS software to support "Point Names" as defined in Section 25 05 01 - EMCS: General Requirements.
 - .2 Upon operator's request in either text, graphic or table mode, system to present condition of single point, system, area, or connected points on system to OWS. Display analog values digitally to 1 place of decimal with negative sign as required. Update displayed analog values and status when new values received. Flag points in alarm by blinking, reverse video, different colour, bracketed or other means to differentiate from points not in alarm. For systems supporting COSV, refresh rate of screen data not to exceed 5 seconds from time of field change and system is to execute supervisory background scan every 20 seconds to verify point data value. For other systems refresh rate not to exceed 5 seconds for points displayed. Initial display of new system graphic display (with up to 30

active points), including presentation of associated dynamic data not to exceed 8 seconds.

- .4 General Event Log Module: to record system activities occurring at OWS or elsewhere in system including:
 - .1 Operator Log-in from user interface device.
 - .2 Communication messages: errors, failures and recovery.
 - .3 Event notifications and alarms by category.
 - .4 Record of operator initiated commands.
- .5 General Event Log:
 - .1 Hold minimum of 4 months' information and be readily accessible to operator.
 - .2 Able to be archived as necessary to prevent loss of information.
- .6 Operator Control Software Module: to support entry of information into system from keyboard and mouse, disk, or from another network device. Display of information to user; dynamic displays, textual displays, and graphic displays to display logging and trending of system information and following tasks:
 - .1 Automatic logging of digital alarms and change of status messages.
 - .2 Automatic logging of analog alarms.
 - .3 System changes: alarm limits, set-points, alarm lockouts.
 - .4 Display specific point values, states as selected.
 - .5 Provide reports as requested and on scheduled basis when required.
 - .6 Display graphics as requested, and on alarm receptions (user's option).
 - .7 Display list of points within system.
 - .8 Display list of systems within building.
 - .9 Direct output of information to selected peripheral device.
 - .10 On-line changes:
 - .1 Alarm limits.
 - .2 Setpoints.
 - .3 Deadbands.
 - .4 Control and change of state changes.
 - .5 Time, day, month, year.
 - .6 Control loop configuration changes for controller-based CDLs.
 - .7 Control loop tuning changes.
 - .8 Schedule changes.
 - .9 Changes, additions, or deletions, of points, graphics, for installed and future systems.
 - .11 According to assigned user privileges (password definition) following functions are to be supported:
 - .1 Permit operator to terminate automatic (logic based) control and set value of field point to operator selected value. These values or settings to remain in effect until returned to automatic (logic based) control by operator.

- .2 Requests for status, analog values, graphic displays, logs and controls to be through user interface screens.
- .12 Software and tools utilized to generate, modify and configure building controllers to be installed and operational on the OWS.
- .7 Dial-up host Module for off site OWSs.
 - .1 Operators at dial-up OWS to be able to perform control functions, report functions, data base generation and modification functions as described for OWS's connected via LAN. Provide routines to automatically answer calls and either file or display information sent from remote panels.
 - .2 Operator to be able to access remote buildings by selection of facility by its logical name. Dial-up module to maintain user-definable cross-reference of buildings and associated telephone numbers without manual dialing.
 - .3 Local OWS may serve as dial-up host for remotely connecting OWSs, remote controllers or networks. Alarms and data file transfers handled via dial-up transactions must not interfere with local LAN activity. LAN activity not to prevent work-station from handling incoming calls.
- .8 Message Handling Module - and Error Messages: to provide message handling for following conditions:
 - .1 Message and alarm buffering to prevent loss of information.
 - .2 Error detection correction and retransmission to guarantee data integrity.
 - .3 Informative messages to operator for data error occurrences, errors in keyboard entry, failure of equipment to respond to requests or commands and failure of communications between EMCS devices.
 - .4 Default device definition to be implemented to ensure alarms are reported as quickly as possible in event of faulty designated OWS.
- .9 Access Control Module.
 - .1 Minimum 5 levels of password access protection to limit control, display, or data base manipulation capabilities. Following is preferred format of progression of password levels:
 - .1 Guest: no password data access and display only.
 - .2 Operator Level: full operational commands including automatic override.
 - .3 Technician: data base modifications.
 - .4 Programmer: data base generation.
 - .5 Highest Level: system administration - password assignment addition, modification.
 - .2 User-definable, automatic log-off timers from 1 to 60 min. to prevent operators leaving devices on-line inadvertently. Default setting = 3 minutes.
- .10 Trend Data Module: includes historical data collection utility, trend data utility, control loop plot utility. Each utility to permit operator to add trend point, delete trend point, set scan rate.
 - .1 Historical data collection utility: collect concurrently operator selected real or calculated point values at operator selectable rate [30-480] minutes. Samples to include for each time interval (time-stamped), minimum present value, maximum

- present value, and average present value for point selected. Rate to be individually selectable for each point. Data collection to be continuous operation, stored in temporary storage until removed from historical data list by operator. Temporary storage to have at least 6-month capacity.
- .2 Trend data utility: continuously collect point object data variables for variables from building controllers as selected by operator, including at minimum; present value of following point object types - DI, DO, AI, AO set points value, calculated values. Trend data utility to have capacity to trend concurrently points at operator-selectable rate of 05 seconds to 3600 seconds, individually selectable for selected value, or use of COSV detection. Collected trend data to be stored on minimum 96 h basis in temporary storage until removed from trend data list by operator. Option to archive data before overwriting to be available.
 - .3 Control loop plot utility: for AO Points provide for concurrent plotting of Measured value input - present value, present value of output, and AO setpoint. Operator selectable sampling interval to be selectable between 1 second to 20 seconds. Plotting utility to scroll to left as plot reaches right side of display window. Systems not supporting control loop plot as separate function must provide predefined groups of values. Each group to include values for one control loop display.
 - .4 Trend data Module to include display of historical or trend data to OWS screen in X Y plot presentation. Plot utility to display minimum of 6 historical points or 6 trend points concurrently or 1 Control Loop Plot. For display output of real time trend data, display to automatically index to left when window becomes full. Provide plotting capabilities to display collected data based on range of selected value for (Y) component against time/date stamp of collected data for (X) component.
 - .5 Provide separate reports for each trend utility. Provide operator feature to specify report type, by point name and for output device. Reports to include time, day, month, year, report title, and operator's initials. Implement reports using report module. Ensure trend data is exportable to third party spreadsheet or database applications for PCs.
- .11 Report Module: reports for energy management programs, function totalization, analog/pulse totalization and event totalization features available at MCU level. Refer also to Section 25 30 01 - EMCS: Building Controllers.
- .1 Reports to include time, day, month, year, report title, operator's initials.
 - .2 Software to provide capability to:
 - .1 Generate and format reports for graphical and numerical display from real time and stored data.
 - .2 Print and store reports as selected by operator.
 - .3 Select and assign points used in such reports.
 - .4 Sort output by area, system, as minimum.
 - .3 Periodic/automatic report:
 - .1 Generate specified report(s) automatically including options of start time and date, interval between reports (hourly, daily, weekly, monthly), output device. Software to permit modifying periodic/automatic reporting profile at any time.

- .2 Reports to include:
 - .1 Power demand and duty cycle summary: see application program for same.
 - .2 Disabled "Locked-out" point summary: include point name, whether disabled by system or by operator.
 - .3 Run time summary: summary of accumulated running time of selected equipment. Include point name, run time to date, alarm limit setting. Run time to accumulate until reset individually by operator.
 - .4 Summary of run time alarms: include point name, run time to date, alarm limit.
 - .5 Summary of start/stop schedules: include start/stop times and days, point name.
 - .6 Motor status summary.
- .4 Report types:
 - .1 Dynamic reports: system to printout or display of point object data value requested by operator. System to indicate status at time of request, when displayed, updated at operator selected time interval. Provide option for operator selection of report type, by point name, and/or output device. Ensure reports are available for following point value combinations:
 - .2 Points in accessible from this OWS (total connected for this location), multiple "areas".
 - .3 Area (points and systems in Area).
 - .4 Area, system (points in system).
 - .5 System (points by system type).
 - .6 System point (points by system and point object type).
 - .7 Area point (points by system and point object type).
 - .8 Point (points by point object type).
 - .5 Summary report: printout or display of point object data value selected by operator. Report header to indicate status at time of request. Ensure reports are available on same basis as dynamic reports. Provide option as to report type, point name, output device.
 - .6 Include preformatted reports as listed in Event/Alarm Module.
- .12 Graphics Display Module: graphics software utility to permit user to create, modify, delete, file, and recall graphics required by Section 25 90 01 - EMCS: Site Requirements, Applications and Systems Sequences of Operation.
 - .1 Provide capacity for 100% expansion of system graphics. Graphic interface to provide user with multiple layered diagrams for site, building in plan view, floor furniture plan view and building systems, overlaid with dynamic data appropriately placed and permitting direct operator interaction. Graphic interface to permit operator to start and stop equipment, change set points, modify alarm limits, override system functions and points from graphic system displays by use of mouse or similar pointing device.

- .2 Display specific system graphics: provide for manual and/or automatic activation (on occurrence of an alarm). Include capability to call up and cancel display of graphic picture.
- .3 Library of pre-engineered screens and symbols depicting standard air handling components (fans, coils, filters, dampers), complete mechanical system components, electrical symbols.
- .4 Graphic development, creation, modification package to use mouse and drawing utility to permit user to:
 - .1 Modify portion of graphic picture/schematic background.
 - .2 Delete graphic picture.
 - .3 Call up and cancel display of graphic picture.
 - .4 Define symbols.
 - .5 Position and size symbols.
 - .6 Define background screens.
 - .7 Define connecting lines, curves.
 - .8 Locate, orient, size descriptive text.
 - .9 Define, display colours of elements.
 - .10 Establish co-relation between symbols or text and associated system points or other graphic displays.
- .5 User to be able to build graphic displays showing on-line point data from multiple MCU panels. Graphic displays to represent logical grouping of system points or calculated data based upon building function, mechanical system, building layout, other logical grouping of points which aids operator in analysis of facility operation. Data to be refreshed on screen as "changed data" without redrawing of entire screen or row on screen.
- .6 Dynamic data (temperature, humidity, flow, status) to be shown in actual schematic locations, to be automatically updated to show current values without operator intervention.
- .7 Windowing environment to allow user to view several graphics simultaneously to permit analysis of building operation, system performance, display of graphic associated with alarm to be viewed without interrupting work in progress.
- .8 Utilize graphics package to generate system schematic diagrams as required in Section 25 90 01 - EMCS: Site Requirements, Applications and System Sequences of Operation, and as directed by Departmental Representative. In addition, provide graphics for schematic depicted on mechanical plan flow diagrams, point lists and system graphics. Provide graphic for floor depicting room sensors and control devices located in their actual location. For floor graphic include secondary diagram to show TCU-VAV box actuator and, flow sensor. Diagram to be single line schematic of ductwork as well as associated heating coil or radiation valve. Departmental Representative to provide CAD floor layouts. Provide display of TCU -VAV's in table form, include following values as minimum; space temp, setpoint, mode, actual flow, min flow setpoint, max flow setpoint, cooling signal value, and heating signal value. Organize table by rooms and floor groupings.

- .9 Provide complete directory of system graphics, including other pertinent system information. Utilize mouse or pointing device to "point and click" to activate selected graphic.
- .10 Provide unique sequence of operation graphic or pop-up window for each graphic that is depicted on OWS. Provide access to sequence of operation graphic by link button on each system graphic. Provide translation of sequence of operation, a concise explanation of systems operation, from control descriptive logic into plain English and/or French language.
- .13 Event/Alarm Module: displays in window alarms as received and stored in General Event Log.
 - .1 Classify alarms as "critical", "cautionary", "maintenance". Alarms and alarm classifications to be designated by personnel requiring password level.
 - .2 Presentation of alarms to include features identified under applicable report definitions of Report Module paragraph.
 - .3 Alarm reports.
 - .1 Summary of points in critical, cautionary or maintenance alarm. Include at least point name, alarm type, current value, limit exceeded.
 - .2 Analog alarm limit summary: include point name, alarm limits, deviation limits.
 - .3 Summary of alarm messages: include associated point name, alarm description.
 - .4 Software to notify operator of each occurrence of alarm conditions. Each point to have its own secondary alarm message.
 - .5 EMCS to notify operator of occurrence of alarms originating at field device within following time periods of detection:
 - .1 Critical – 5 seconds.
 - .2 Cautionary – 10 seconds.
 - .3 Maintenance – 10 seconds.
 - .6 Display alarm messages in English and French.
 - .7 Primary alarm message to include as minimum: point identifier, alarm classification, time of occurrence, type of alarm. Provide for initial message to be automatically presented to operator whenever associated alarm is reported. Assignment of secondary messages to point to be operator-editable function. Provide secondary messages giving further information (telephone lists, maintenance functions) on per point basis.
 - .8 System reaction to alarms: provide alarm annunciation by dedicated window (activated to foreground on receipt of new alarm or event) of OWS with visual and audible hardware indication. Acknowledgement of alarm to change visual indicator from flashing to steady state and to silence audible device. Acknowledgment of alarm to be time, date and operator stamped and stored in General Event Log. Steady state visual indicator to remain until alarm condition is corrected but must not impede reporting of new alarm conditions. Notification of alarm not to impede notification of subsequent alarms or function of Controller's/CDL. Do not allow random occurrence of alarms to cause loss of

- alarm or over-burden system. Do not allow acknowledgment of one alarm as acknowledgement of other alarms.
- .9 Controller network alarms: system supervision of controllers and communications lines to provide following alarms as minimum:
- .1 Controller not responding - where possible delineate between controller and communication line failure.
 - .2 Controller responding - return to normal.
 - .3 Controller communications bad - high error rate or loss of communication.
 - .4 Controller communications normal - return to normal.
- .10 Digital alarm status to be interrogated every 2 seconds as minimum or be direct interrupting non-polling type (COV). Annunciate each non-expected status with alarm message.
- .14 Archiving and Restoration Module.
- .1 Primary OWS to include services to store back-up copies of controller databases. Perform complete backup of OWS software and data files at time of system installation and at time of final acceptance. Provide backup copies before and after Controller's revisions or major modifications.
 - .2 Provide continuous integrity supervision of controller data bases. When controller encounters database integrity problems with its data base, system to notify operator of need to download copy data base to restore proper operation.
 - .3 Ensure data base back-up and downloading occurs over LAN without specialized operator technical knowledge. Provide operator with ability to manually download entire controller data base, or parts thereof as required.
- .15 CDL Generator and Modifier Module.
- .1 CDL Generator module to permit generation and modification of CDLs.
 - .2 Provide standard reference modules for text based systems module that will permit modification to suit site specific applications. Module to include cut, paste, search and compare utilities to permit easy CDL modification and verification.
 - .3 Provide full library of symbols used by manufacturer for system product installed accessible to operators for systems using graphical environment for creation of CDLs Module to include graphic tools required to generate and create new object code for downloading to building controllers.
 - .4 Module to permit testing of code before downloading to building controllers.

2.7 ADDITIONAL UTILITY SOFTWARE

- .1 Supply and install on primary OWS, following CAD software products by Autodesk Inc. and include:
- .1 AutoCAD LT latest version.
 - .2 Include special drivers, fonts, to ensure complete and proper functioning of software packages specified. Deliver system complete with full set of User Manuals.

- .3 Enter soft copy submissions, including "Record" drawings specified in Section 25 05 03 - EMCS: Project Record Documents in OWS.
- .4 Enter soft copy of Architectural, Electrical, Mechanical systems plans and "Record" drawings in OWS. Plans and drawings to be provided by Departmental Representative.

Part 3 Execution

3.1 INSTALLATION REQUIREMENTS

- .1 Provide necessary power as required from local 120 V emergency power branch circuit panels for OWS's and peripheral equipment.
 - .1 Install tamper locks on breakers of circuit panels.
 - .2 Refer to UPS requirements stated under OWS Hardware in PART 2.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes:
 - .1 Materials and installation for building automation controllers including:
 - .1 Master Control Unit (MCU).
 - .2 Local Control Unit (LCU).
 - .3 Equipment Control Unit (ECU).

1.2 REFERENCES

- .1 American Society of Heating, Refrigeration and Air-Conditioning Engineers, Inc. (ASHRAE).
 - .1 ASHRAE Applications Handbook, SI Edition.
- .2 Canadian Standards Association (CSA International).
 - .1 C22.2 No.205, Signal Equipment.
- .3 Institute of Electrical and Electronics Engineers (IEEE).
 - .1 IEEE C37.90.1, Surge Withstand Capabilities (SWC) Tests for Relays and Relay Systems Associated with Electric Power Apparatus.
- .4 Public Works and Government Services Canada (PWGSC)/Real Property Branch/Architectural and Engineering Services.
 - .1 MD13800, Energy Management and Control Systems (EMCS) Design Manual.
English: <ftp://ftp.pwgsc.gc.ca/rps/docentre/mechanical/me214-e.pdf>

1.3 DEFINITIONS

- .1 Acronyms and definitions: refer to Section 25 05 01 - EMCS: General Requirements.

1.4 DESCRIPTION

- .1 General: Network of controllers comprising of MCU('s), LCU('s), ECU('s) or TCU('s) to be provided as indicated in System Architecture Diagram to support building systems and associated sequence(s) of operations as detailed in these specifications.
 - .1 Provide sufficient controllers to meet intents and requirements of this section.
 - .2 Controller quantity, and point contents to be approved by Departmental Representative at time of preliminary design review.
- .2 Controllers: stand-alone intelligent Control Units.
 - .1 Incorporate programmable microprocessor, non-volatile program memory, RAM, power supplies, as required to perform specified functions.
 - .2 Incorporate communication interface ports for communication to LANs to exchange information with other Controllers.
 - .3 Capable of interfacing with operator interface device.

- .4 Execute its logic and control using primary inputs and outputs connected directly to its onboard input/output field terminations or slave devices, and without need to interact with other controller. Secondary input used for reset such as outdoor air temperature may be located in other Controller(s).
 - .1 Secondary input used for reset such as outdoor air temperature may be located in other Controller(s).
- .3 Interface to include provisions for use of dial-up modem for interconnection with remote modem.
 - .1 Dial-up communications to use 56 Kbit modems and voice grade telephone lines.
 - .2 Each stand-alone panel may have its own modem or group of stand-alone panels may share modem.

1.5 DESIGN REQUIREMENTS

- .1 To include:
 - .1 Scanning of AI and DI connected inputs for detection of change of value and processing detection of alarm conditions.
 - .2 Perform On-Off digital control of connected points, including resulting required states generated through programmable logic output.
 - .3 Perform Analog control using programmable logic, (including PID) with adjustable dead bands and deviation alarms.
 - .4 Control of systems as described in sequence of operations.
 - .5 Execution of optimization routines as listed in this section.
- .2 Total spare capacity for MCUs and LCUs: at least 25 % of each point type distributed throughout the MCUs and LCUs.
- .3 Field Termination and Interface Devices:
 - .1 To: CSA C22.2 No.205.
 - .2 Electronically interface sensors and control devices to processor unit.
 - .3 Include, but not be limited to, following:
 - .1 Programmed firmware or logic circuits to meet functional and technical requirements.
 - .2 Power supplies for operation of logics devices and associated field equipment.
 - .3 Lockable wall cabinet.
 - .4 Required communications equipment and wiring (if remote units).
 - .5 Leave controlled system in "fail-safe" mode in event of loss of communication with, or failure of, processor unit.
 - .6 Input Output interface to accept as minimum AI, AO, DI, DO functions as specified.
 - .7 Wiring terminations: use conveniently located screw type or spade lug terminals.
 - .4 AI interface equipment to:

- .1 Convert analog signals to digital format with 10 bit analog-to-digital resolution.
- .2 Provide for following input signal types and ranges:
 - .1 4 - 20 mA;
 - .2 0 - 10 V DC;
 - .3 100/1000 ohm RTD input;
- .3 Meet IEEE C37.90.1 surge withstand capability.
- .4 Have common mode signal rejection greater than 60 dB to 60 Hz.
- .5 Where required, dropping resistors to be certified precision devices which complement accuracy of sensor and transmitter range specified.
- .5 AO interface equipment:
 - .1 Convert digital data from controller processor to acceptable analog output signals using 8 bit digital-to-analog resolution.
 - .2 Provide for following output signal types and ranges:
 - .1 4 - 20 mA.
 - .2 0 - 10 V DC.
 - .3 Meet IEEE C37.90.1 surge withstand capability.
- .6 DI interface equipment:
 - .1 Able to reliably detect contact change of sensed field contact and transmit condition to controller.
 - .2 Meet IEEE C37.90.1 surge withstand capability.
 - .3 Accept pulsed inputs up to 2 kHz.
- .7 DO interface equipment:
 - .1 Respond to controller processor output, switch respective outputs. Each DO hardware to be capable of switching up to 0.5 amps at 24 V AC.
 - .2 Switch up to 5 amps at 220 V AC using optional interface relay.
- .4 Controllers and associated hardware and software: operate in conditions of 0 degrees C to 44 degrees C and 20 % to 90 % non-condensing RH.
- .5 Controllers (MCU, LCU): mount in wall mounted cabinet with hinged, keyed-alike locked door.
 - .1 Provide for conduit entrance from top, bottom or sides of panel.
 - .2 ECUs and TCUs to be mounted in equipment enclosures or separate enclosures.
 - .3 Mounting details as approved by Departmental Representative for ceiling mounting.
- .6 Cabinets to provide protection from water dripping from above, while allowing sufficient airflow to prevent internal overheating.
- .7 Provide surge and low voltage protection for interconnecting wiring connections.

1.6 ACTION AND INFORMATIONAL SUBMITTALS

- .1 Make submittals in accordance with Section 01 33 00 - Submittal Procedures, Section 25 05 02 - EMCS: Shop Drawings, Product Data and Review Process.

- .1 Submit product data sheets for each product item proposed for this project.

1.7 MAINTENANCE

- .1 Provide manufacturers recommended maintenance procedures for insertion in Section 25 05 03 - EMCS: Project Record Documents.

Part 2 Products

2.1 MASTER CONTROL UNIT (MCU)

- .1 General: primary function of MCU is to provide co-ordination and supervision of subordinate devices in execution of optimization routines such as demand limiting or enthalpy control.
- .2 Include high speed communication LAN Port for Peer to Peer communications with OWS(s) and other MCU level devices.
 - .1 MCU must support BACnet.
- .3 MCU local I/O capacity as follows:
 - .1 MCU I/O points as allocated in I/O Summary Table referenced in MD13800.
 - .2 LCUs may be added to support system functions.
- .4 Central Processing Unit (CPU).
 - .1 Processor to consist of minimum 16 bit microprocessor capable of supporting software to meet specified requirements.
 - .2 CPU idle time to be more than 30 % when system configured to maximum input and output with worst case program use.
 - .3 Minimum addressable memory to be at manufacturer's discretion but to support at least performance and technical specifications to include but not limited to:
 - .1 Non-volatile EEPROM to contain operating system, executive, application, sub-routine, other configurations definition software. Tape media not acceptable.
 - .2 Battery backed (72-hour minimum capacity) RAM (to reduce the need to reload operating data in event of power failure) to contain CDLs, application parameters, operating data or software that is required to be modifiable from operational standpoint such as schedules, setpoints, alarm limits, PID constants and CDL and hence modifiable on-line through operator panel or remote operator's interface. RAM to be downline loadable from OWS.
 - .4 Include uninterruptible clock accurate to plus or minus 5 secs/month, capable of deriving year/month/day/hour/minute/second, with rechargeable batteries for minimum 72 hour operation in event of power failure.
- .5 Local Operator Terminal (OT): Provide OT for each MCU unless otherwise specified in Section 25 90 01 - EMCS: Site Requirements, Applications and System Sequences of Operation.
 - .1 Mount access/display panel in MCU or in suitable enclosure beside MCU as approved by Departmental Representative.

- .2 Support operator's terminal for local command entry, instantaneous and historical data display, programs, additions and modifications.
- .3 Display simultaneously minimum of 16 point identifiers to allow operator to view single screen dynamic displays depicting entire mechanical systems. Point identifiers to be in English.
- .4 Functions to include, but not be limited to, following:
 - .1 Start and stop points.
 - .2 Modify setpoints.
 - .3 Modify PID loop parameters.
 - .4 Override PID control.
 - .5 Change time/date.
 - .6 Add/modify/start/stop weekly scheduling.
 - .7 Add/modify setpoint weekly scheduling.
 - .8 Enter temporary override schedules.
 - .9 Define holiday schedules.
 - .10 View analog limits.
 - .11 Enter/modify analog warning limits.
 - .12 Enter/modify analog alarm limits.
 - .13 Enter/modify analog differentials.
- .5 Provide access to real and calculated points in controller to which it is connected or to other controller in network. This capability not to be restricted to subset of predefined "global points" but to provide totally open exchange of data between OT and other controller in network.
- .6 Operator access to OTs: same as OWS user password and password changes to automatically be downloaded to controllers on network.
- .7 Provide prompting to eliminate need for user to remember command format or point names. Prompting to be consistent with user's password clearance and types of points displayed to eliminate possibility of operator error.
- .8 Identity of real or calculated points to be consistent with network devices. Use same point identifier as at OWS's for access of points at OT to eliminate cross-reference or look-up tables.

2.2 LOCAL CONTROL UNIT (LCU)

- .1 Provide multiple control functions for typical built-up and package HVAC systems, hydronic systems and electrical systems.
- .2 Minimum of 16 I/O points of which minimum be 4 AOs, 4 AIs, 4 DIs, 4 DOs.
- .3 Points integral to one Building System to be resident on only one controller.
- .4 Microprocessor capable of supporting necessary software and hardware to meet specified requirements as listed in previous MCU article with following additions:
 - .1 Include minimum 2 interface ports for connection of local computer terminal.
 - .2 Design so that shorts, opens or grounds on input or output will not interfere with other input or output signals.

- .3 Physically separate line voltage (70V and over) circuits from DC logic circuits to permit maintenance on either circuit with minimum hazards to technician and equipment.
- .4 Include power supplies for operation of LCU and associated field equipment.
- .5 In event of loss of communications with, or failure of, MCU, LCU to continue to perform control. Controllers that use defaults or fail to open or close positions not acceptable.
- .6 Provide conveniently located screw type or spade lug terminals for field wiring.

2.3 SOFTWARE

- .1 General.
 - .1 Include as minimum: operating system executive, communications, application programs, operator interface, and systems sequence of operation - CDL's.
 - .2 Include "firmware" or instructions which are programmed into ROM, EPROM, EEPROM or other non-volatile memory.
 - .3 Include initial programming of Controllers, for entire system.
- .2 Program and data storage.
 - .1 Store executive programs and site configuration data in ROM, EEPROM or other non-volatile memory.
 - .2 Maintain CDL and operating data including setpoints, operating constants, alarm limits in battery-backed RAM or EEPROM for display and modification by operator.
- .3 Programming languages.
 - .1 Program Control Description Logic software (CDL) using English like or graphical, high level, general control language.
 - .2 Structure software in modular fashion to permit simple restructuring of program modules if future software additions or modifications are required. GO TO constructs not allowed unless approved by Departmental Representative.
- .4 Operator Terminal interface.
 - .1 Operating and control functions include:
 - .1 Multi-level password access protection to allow user/manager to limit workstation control.
 - .2 Alarm management: processing and messages.
 - .3 Operator commands.
 - .4 Reports.
 - .5 Displays.
 - .6 Point identification.
- .5 Pseudo or calculated points.
 - .1 Software to provide access to value or status in controller or other networked controller in order to define and calculate pseudo point. When current pseudo point value is derived, normal alarm checks must be performed or value used to totalize.

- .2 Inputs and outputs for process: include data from controllers to permit development of network-wide control strategies. Processes also to permit operator to use results of one process as input to number of other processes (e.g. cascading).
- .6 Control Description Logic (CDL):
 - .1 Capable of generating on-line project-specific CDLs which are software based, programmed into RAM or EEPROM and backed up to OWS. Owner must have access to these algorithms for modification or to be able to create new ones and to integrate these into CDLs on BC(s) from OWS.
 - .2 Write CDL in high level language that allows algorithms and interlocking programs to be written simply and clearly. Use parameters entered into system (e.g. setpoints) to determine operation of algorithm. Operator to be able to alter operating parameters on-line from OWS and BC(s) to tune control loops.
 - .3 Perform changes to CDL on-line.
 - .4 Control logic to have access to values or status of points available to controller including global or common values, allowing cascading or inter-locking control.
 - .5 Energy optimization routines including enthalpy control, supply temperature reset, to be LCU or MCU resident functions and form part of CDL.
 - .6 MCU to be able to perform following pre-tested control algorithms:
 - .1 Two position control.
 - .2 Proportional Integral and Derivative (PID) control.
 - .7 Control software to provide ability to define time between successive starts for each piece of equipment to reduce cycling of motors.
 - .8 Provide protection against excessive electrical-demand situations during start-up periods by automatically introducing time delays between successive start commands to heavy electrical loads.
 - .9 Power Fail Restart: upon detection of power failure system to verify availability of Emergency Power as determined by emergency power transfer switches and analyze controlled equipment to determine its appropriate status under Emergency power conditions and start or stop equipment as defined by I/O Summary. Upon resumption of normal power as determined by emergency power transfer switches, MCU to analyze status of controlled equipment, compare with normal occupancy scheduling, turn equipment on or off as necessary to resume normal operation.
- .7 Event and Alarm management: use management by exception concept for Alarm Reporting. This is system wide requirement. This approach will insure that only principal alarms are reported to OWS. Events which occur as direct result of primary event to be suppressed by system and only events which fail to occur to be reported. Such event sequence to be identified in I/O Summary and sequence of operation. Examples of above are, operational temperature alarms limits which are exceeded when main air handler is stopped, or General Fire condition shuts air handlers down, only Fire alarm status shall be reported. Exception is, when air handler which is supposed to stop or start fails to do so under event condition.
- .8 Energy management programs: include specific summarizing reports, with date stamp indicating sensor details which activated and or terminated feature.

- .1 MCU in coordination with subordinate LCU, TCU, ECU to provide for the following energy management routines:
 - .1 Time of day scheduling.
 - .2 Calendar based scheduling.
 - .3 Holiday scheduling.
 - .4 Temporary schedule overrides.
 - .5 Optimal start stop.
 - .6 Night setback control.
 - .7 Enthalpy (economizer) switchover.
 - .8 Peak demand limiting.
 - .9 Temperature compensated load rolling.
 - .10 Fan speed/flow rate control.
 - .11 Cold deck reset.
 - .12 Hot deck reset.
 - .13 Hot water reset.
 - .14 Chilled water reset.
 - .15 Condenser water reset.
 - .16 Chiller sequencing.
 - .17 Night purge.
- .2 Programs to be executed automatically without need for operator intervention and be flexible enough to allow customization.
- .3 Apply programs to equipment and systems as specified or requested by the Departmental Representative.
- .9 Function/Event Totalization: features to provide predefined reports which show daily, weekly, and monthly accumulating totals and which include high rate (time stamped) and low rate (time stamped) and accumulation to date for month.
 - .1 MCUs to accumulate and store automatically run-time for binary input and output points.
 - .2 MCU to automatically sample, calculate and store consumption totals on daily, weekly or monthly basis for user-selected analog or binary pulse input-type points.
 - .3 MCU to automatically count events (number of times pump is cycled off and on) daily, weekly or monthly basis.
 - .4 Totalization routine to have sampling resolution of 1 min or less for analog inputs.
 - .5 Totalization to provide calculations and storage of accumulations up to [99,999.9] units (eg. kWh, litres, tonnes, etc.).
 - .6 Store event totalization records with minimum of 9,999,999 events before reset.
 - .7 User to be able to define warning limit and generate user-specified messages when limit reached.

2.4 LEVELS OF ADDRESS

- .1 Upon operator's request, EMCS to present status of any single 'point', 'system' or point group, entire 'area', or entire network on printer or OWS as selected by operator.
 - .1 Display analog values digitally to 1 place of decimals with negative sign as required.
 - .2 Update displayed analog values and status when new values received.
 - .3 Flag points in alarm by blinking, reverse video, different colour, bracketed or other means to differentiate from points not in alarm.
 - .4 Updates to be change-of-value (COV)-driven or if polled not exceeding 2 second intervals.

2.5 POINT NAME SUPPORT

- .1 Controllers (MCU, LCU) to support PWGSC point naming convention as defined in Section 25 05 01 - EMCS: General Requirements.

Part 3 Execution

3.1 LOCATION

- .1 Location of Controllers to be approved by Departmental Representative.

3.2 INSTALLATION

- .1 Install Controllers in secure locking enclosures as directed by Departmental Representative
- .2 Provide necessary power from local 120V branch circuit panel for equipment.
- .3 Install tamper locks on breakers of circuit breaker panel.
- .4 Use uninterruptible Power Supply (UPS) and emergency power when equipment must operate in emergency and co-ordinating mode.

END OF SECTION

Part 1 General

1.1 SUMMARY

- .1 Section Includes:
 - .1 Control devices integral to the Building Energy Monitoring and Control System (EMCS): transmitters, sensors, controls, meters, switches, dampers, damper operators, low voltage current transformers.
 - .2 Related Sections:
 - .1 Section 07 84 00 - Firestopping.
 - .2 Section 25 01 11 - EMCS: Start-Up, Verification and Commissioning.
 - .3 Section 25 05 01 - EMCS: General Requirements.
 - .4 Section 25 05 02 - EMCS: Shop Drawings, Product Data and Review Process.
 - .5 Section 25 05 54 - EMCS: Identification.
 - .6 Section 25 90 01 - EMCS: Site Requirements Applications and Systems Sequences of Operation.
 - .7 Section 26 05 00 - Common Work Results for Electrical.
 - .8 Section 26 27 26 - Wiring Devices.

1.2 REFERENCES

- .1 National Electrical Manufacturer's Association (NEMA).
 - .1 NEMA 250-2014, Enclosures for Electrical Equipment (1000 Volts Maximum).
- .2 Air Movement and Control Association, Inc. (AMCA).
 - .1 AMCA Standard 500-D-2012, Laboratory Method of Testing Dampers For Rating.
- .3 Canadian Standards Association (CSA International).
 - .1 CAN/CSA-C61869-2014, Instrument Transformers.
 - .2 CSA-C22.1-15, Canadian Electrical Code, Part 1 (19th Edition), Safety Standard for Electrical Installations.

1.3 DEFINITIONS

- .1 Acronyms and Definitions: refer to Section 25 05 01 - EMCS: General Requirements.

1.4 ACTION AND INFORMATIONAL SUBMITTALS

- .1 Submit shop drawings and manufacturer's installation instructions in accordance with Section 25 05 02 - EMCS: Submittals and Review Process.
- .2 Pre-Installation Tests.
 - .1 Submit samples at random from equipment shipped, as requested by Departmental Representative for testing before installation. Replace devices not meeting specified performance and accuracy.

- .3 Manufacturer's Instructions:
 - .1 Submit manufacturer's installation instructions for specified equipment and devices.

Part 2 Products

2.1 GENERAL

- .1 Control devices of each category to be of same type and manufacturer.
- .2 External trim materials to be corrosion resistant. Internal parts to be assembled in watertight, shockproof, vibration-proof assembly.
- .3 Operating conditions: 0 - 32 degrees C with 10 - 90% RH (non-condensing) unless otherwise specified.
- .4 Terminations: use standard conduit box with slot screwdriver compression connector block unless otherwise specified.
- .5 Transmitters and sensors to be unaffected by external transmitters including walkie talkies.
- .6 Account for hysteresis, relaxation time, maximum and minimum limits in applications of sensors and controls.
- .7 Outdoor installations: use weatherproof construction in NEMA 4 enclosures.
- .8 Devices installed in user occupied space not exceed Noise Criteria (NC) of 35. Noise generated by any device must not be detectable above space ambient conditions.
- .9 Range: including temperature, humidity, pressure, as indicated in I/O summary in Section 25 90 01 - EMCS: Site Requirements, Applications and System Sequences of Operation.

2.2 TEMPERATURE SENSORS

- .1 General: except for room sensors to be resistance or thermocouple type to following requirements:
 - .1 Thermocouples: limit to temperature range of 200 degrees C and over.
 - .2 RTD's: 100 or 1000 ohm at 0 degrees C (plus or minus 0.2 ohms) platinum element with strain minimizing construction, 3 integral anchored leadwires. Coefficient of resistivity: 0.00385 ohms/ohm degrees C.
 - .3 Sensing element: hermetically sealed.
 - .4 Stem and tip construction: copper or type 304 stainless steel.
 - .5 Time constant response: less than 3 seconds to temperature change of 10 degrees C.
- .2 Room temperature sensors and display wall modules (Type S2 on drawings).
 - .1 Temperature sensing and display wall module.
 - .1 LCD display to show space temperature and temperature set point.
 - .2 Buttons for occupant selection of temperature set point and occupied/unoccupied mode.

- .3 Jack connection for plugging in laptop personal computer for access to zone bus.
- .4 Integral thermistor sensing element 10,000 ohm at 24 degrees.
- .5 Accuracy 0.2 degrees C over range of 0 to 70 degrees C.
- .6 Stability 0.02 degrees C drift per year.
- .7 Separate mounting base for ease of installation.
- .2 Room temperature sensors (Type S1 on Drawings).
 - .1 Wall mounting, in slotted type covers having manufacturer's standard finish, with guard.
 - .2 Element 10-50mm long RTD with ceramic tube or equivalent protection or thermistor, 10,000 ohm, accuracy of plus or minus 0.2 degrees C.
- .3 Duct temperature sensors:
 - .1 General purpose duct type: suitable for insertion into ducts at various orientations, insertion length 460 mm.
 - .2 Averaging duct type: incorporates numerous sensors inside assembly which are averaged to provide one reading. Minimum insertion length 6000 mm. Bend probe at field installation time to 100 mm radius at point along probe without degradation of performance.
- .4 Outdoor air temperature sensors:
 - .1 Outside air type: complete with probe length 100 - 150 mm long, non-corroding shield to minimize solar and wind effects, threaded fitting for mating to 13 mm conduit, weatherproof construction in NEMA 4 enclosure.

2.3 TEMPERATURE TRANSMITTERS

- .1 Requirements:
 - .1 Input circuit: to accept 3-lead, 100 or 1000 ohm at 0 degrees C, platinum resistance detector type sensors.
 - .2 Power supply: 24 V DC into load of 575 ohms. Power supply effect less than 0.01 degrees C per volt change.
 - .3 Output signal: 4 - 20 mA into 500 ohm maximum load.
 - .4 Input and output short circuit and open circuit protection.
 - .5 Output variation: less than 0.2 % of full scale for supply voltage variation of plus or minus 10 %.
 - .6 Combined non-linearity, repeatability, hysteresis effects: not to exceed plus or minus 0.5 % of full scale output.
 - .7 Maximum current to 100 or 1000 ohm RTD sensor: not to exceed 25 mA.
 - .8 Integral zero and span adjustments.
 - .9 Temperature effects: not to exceed plus or minus 1.0 % of full scale/50 degrees C.
 - .10 Long term output drift: not to exceed 0.25 % of full scale/6 months.
 - .11 Transmitter ranges: select narrowest range to suit application from following:
 - .1 Minus 50 degrees C to plus 50 degrees C, plus or minus 0.5 degrees C.

2.4 HUMIDITY SENSORS

- .1 Duct Requirements:
 - .1 Range: 5 -90 % RH minimum.
 - .2 Operating temperature range: 0 - 60 degrees C.
 - .3 Absolute accuracy:
 - .1 Duct sensors: plus or minus 3 %.
 - .4 Sheath: stainless steel with integral shroud for specified operation in air streams of up to 10 m/s.
 - .5 Maximum sensor non-linearity: plus or minus 2% RH with defined curves.
 - .6 Duct mounted sensors: locate so that sensing element is in air flow in duct.
- .2 Outdoor Humidity Requirements:
 - .1 Range: 0 - 100 % RH minimum.
 - .2 Operating temperature range: -40 - 50 degrees C.
 - .3 Absolute accuracy: plus or minus 2%.
 - .4 Temperature coefficient: plus or minus 0.03%RH/ degrees C over 0 to 50 degrees C.
 - .5 Must be unaffected by condensation or 100% saturation.
 - .6 No routine maintenance or calibration is required.

2.5 HUMIDITY TRANSMITTERS

- .1 Requirements:
 - .1 Input signal: from RH sensor.
 - .2 Output signal: 4 -20 mA onto 500 ohm maximum load.
 - .3 Input and output short circuit and open circuit protection.
 - .4 Output variations: not to exceed 0.2 % of full scale output for supply voltage variations of plus or minus 10 %.
 - .5 Output linearity error: plus or minus 1.0% maximum of full scale output.
 - .6 Integral zero and span adjustment.
 - .7 Temperature effect: plus or minus 1.0 % full scale/6 months.
 - .8 Long term output drift: not to exceed 0.25 % of full scale output/6 months.

2.6 SOLID STATE RELAYS

- .1 General:
 - .1 Relays to be socket or rail mounted.
 - .2 Relays to have LED Indicator
 - .3 Input and output Barrier Strips to accept 14 to 28 AWG wire.
 - .4 Operating temperature range to be -20 degrees C to 70 degrees C.
 - .5 Relays to be CSA Certified.
 - .6 Input/output Isolation Voltage to be 4000 VAC at 25 degrees C for 1 second maximum duration.

- .7 Operational frequency range, 45 to 65 HZ.
- .2 Input:
 - .1 Control voltage, 3 to 32 VDC.
 - .2 Drop out voltage, 1.2 VDC.
 - .3 Maximum input current to match AO (Analog Output) board.
- .3 Output.
 - .1 AC or DC Output Model to suit application.

2.7 CURRENT SENSING RELAYS

- .1 Requirements:
 - .1 Suitable to detect belt loss or motor failure.
 - .2 Trip point adjustment, output status LED.
 - .3 Split core for easy mounting.
 - .4 Induced sensor power.
 - .5 Relay contacts: capable of handling 0.5 amps at 30 VAC / DC. Output to be NO solid state.
 - .6 Suitable for single or 3 phase monitoring. For 3-Phase applications: provide for discrimination between phases.
 - .7 Adjustable latch level.

2.8 THERMALLY INSULATED CONTROL DAMPERS

- .1 Extruded aluminum (6063-T5) damper frame shall not be less than 2.03 mm thick. Damper frame shall be 101.6 mm deep x 25.4 mm, with duct mounting flanges on both sides of frame. Damper frame shall have a 50.8 mm mounting flange on the rear of the damper, when installed as Extended Rear Flange install type. Frame to be assembled using zinc-plated steel mounting fasteners. Welded frames shall not be acceptable.
- .2 Blades shall be maximum 162.6 mm deep extruded aluminum (6063-T5) air-foil profiles with a minimum wall thickness of 1.52mm. Blades shall be internally insulated with expanded polyurethane foam and shall be thermally broken. Complete blade shall have an insulating factor of R-2.29. All blades shall be symmetrically pivoted.
- .3 Blade seals shall be extruded EPDM, secured in an integral slot within the aluminum blade extrusions and shall be mechanically fastened to prevent shrinkage and movement over the life of the damper.
- .4 Frame seals shall be extruded silicone, secured in an integral slot within the aluminum frame extrusions and shall be mechanically fastened to prevent shrinkage and movement over the life of the damper.
- .5 Bearings shall be a dual bearing system composed of a Celcon inner bearing (fixed around a 11.11 mm aluminum hexagon blade pivot pin), rotating within a polycarbonate outer bearing inserted in the frame.
- .6 Hexagonal control shaft shall be 11.11 mm. It shall have an adjustable length and shall be an integral part of the blade axle. All parts shall be zinc-plated steel.

- .7 Linkage hardware shall be aluminum and corrosion-resistant zinc-plated steel, installed in the frame side, out of the airstream, and accessible after installation. Linkage hardware shall be complete with cup-point trunnion screws to prevent linkage slippage and a Celcon bearing between moving parts to reduce wear and increase longevity.
- .8 Dampers shall be designed for operation in temperatures ranging from -40°C to 100°C.
- .9 Dampers shall be AMCA rated for Leakage Class 1A at 0.25 kPa static pressure differential. Standard air leakage data to be certified under the AMCA Certified Ratings Program.
- .10 Dampers shall be custom made to required size, with blade stops not exceeding 31.7 mm in height. The blade stop shall be a continuous and integral part of the head/sill. Welded and caulked blade stops shall not be acceptable.
- .11 Dampers shall be opposed blade action or parallel blade action.
- .12 Dampers shall be installed in the following manner: Flanged to Duct.

2.9 ELECTRONIC CONTROL DAMPER ACTUATORS

- .1 Requirements:
 - .1 Direct mount proportional type as indicated.
 - .2 Spring return for "fail-safe" in Normally Open or Normally Closed position as indicated.
 - .3 Operator: size to control dampers against maximum pressure and dynamic closing/opening pressure, whichever is greater.
 - .4 Power requirements: 5 VA maximum at 24 V AC.
 - .5 Operating range: 0 - 10 V DC or 4 - 20 mA DC.
 - .6 For VAV box applications floating control type actuators may be used.
 - .7 Damper actuator to drive damper from full open to full closed in less than 120 seconds.

2.10 CARBON MONOXIDE DETECTOR

- .1 Carbon monoxide detector using an electrochemical sensor to monitor the carbon monoxide level and outputs a selectable 4-20 mA or voltage signal. UL Recognized Component for ANSI/UL-2034, UL-2075, E240671.
- .2 Front panel LCD standard to ensure easy setup and operation.
- .3 Requirements:
 - .1 Measurement Range (selectable): 0-100, 150, 300, 400, or 500 PPM.
 - .2 Accuracy: ± 5 PPM or 5% of reading (whichever is greater).
 - .3 Accuracy rated: 0° to 50°C, 15 to 95% RH
 - .4 Life Expectancy: 5-7 years in air
 - .5 Typical Coverage Area: 700 m² or 15 m radius
 - .6 Operating Conditions: -4° to 122°F, 15 to 95% RH, 0.9 to 1.1 atm
 - .7 Stability: <5% signal loss/year
 - .8 Response Time: <35 seconds for 90% step change

- .9 Power Supply: 24 Vdc \pm 20% or 24 Vac \pm 10% (non-isolated half-wave rectied)
- .10 Consumption: 00 mA max. with all options on
- .11 Protection Circuitry: Reverse voltage protected and output limited
- .12 Output Signal: 4-20 mA (Active), 0-5 or 0-10 Vdc (Selectable)
- .13 LCD Display: Displays PPM and menu parameters, 1 PPM resolution, 35 mm W x 15 mm H Alpha-numeric 2 line X 8 character with backlight
- .14 Test Switch: Performs I/O tests, front panel and remote connection
- .15 Buzzer Alarm: 85 db @ 10 feet.
- .16 Buzzer Trip Point: Programmable 20-500 ppm in 10 ppm increments
- .17 Buzzer Delay: Programmable 0-10 minutes in 1 minute increments
- .18 Relay Output: two Form C contact (N.O. and N.C.) 5 amps @ 250 Vac, 5 amps @ 30 Vdc, p.f. = 1
 - .1 Relay 1 Trip Point - Programmable 20-500 PPM in 10 PPM increments
 - .2 Relay 2 Trip Point - Programmable 20-500 PPM in 10 PPM increments
 - .3 Relay Hysteresis - Programmable 10-100 PPM in 5 PPM increments
 - .4 Relay Delay - Programmable 0-10 minutes in 1 minute increments
- .19 Communications: BACNet
- .20 Enclosure Ratings: Space (4) - ABS - UL94-V - IP65 (NEMA 4X)

2.11 NITROGEN DIOXIDE DETECTOR

- .1 Nitrogen dioxide detector using electrochemical sensor for reliability and accuracy, 3-wire sourcing 4-20 mA output, alarm relay with three jumper selectable trip level settings.
- .2 Requirements:
 - .1 Sample Method: Diffusion
 - .2 Measurement Range: 0-10 PPM
 - .3 Accuracy: \pm 0.2 PPM or 5% of reading (whichever is greater)
 - .4 Life Expectancy: >2 years
 - .5 Typical Coverage Area: 700 m² or 15m radius
 - .6 Operating Temperature: -20° to 50°C
 - .7 Operating Humidity: 15 to 90% RH (0 to 99% intermittent)
 - .8 Pressure: Atmospheric \pm 10%
 - .9 Power Supply: 24 Vdc \pm 20% (non-isolated half-wave rectified) or 24 Vac \pm 10%
 - .10 Consumption: 50 mA max.
 - .11 Output Signal: 4-20 mA sourcing
 - .12 Output Drive at Capability: 550 ohms max. @ 24 Vac/Vdc
 - .13 Relay Output: SPDT, Form C contact (N.O. and N.C.), 5 amps @ 30 Vdc, p.f. = 1, Trip Point - Low = 1, Mid = 3 or High = 5 PPM, jumper selectable, Hysteresis - 3%
 - .14 Wiring Connections: Screw terminal block (14 to 22 AWG)
 - .15 External Dimensions: 71 x 104 x 48 mm

.16 Enclosure Ratings: ABS - UL94-5VB - IP65, (NEMA 4X)

2.12 PANELS

- .1 Wall mounted enamelled steel cabinets with hinged and key-locked front door.
- .2 Multiple panels as required to handle requirements with additional space to accommodate 25% additional capacity as required by Departmental Representative without adding additional cabinets.
- .3 Panels to be lockable with same key.

2.13 WIRING

- .1 In accordance with Section 26 27 26 - Wiring Devices.
- .2 For wiring under 70 volts use FT6 rated wiring where wiring is not run in conduit. Other cases use FT4 wiring.
- .3 Wiring must be continuous without joints.
- .4 Sizes:
 - .1 Field wiring to digital device: #18AWG or 20AWG stranded twisted pair.
 - .2 Analog input and output: shielded #18 minimum solid copper or #20 minimum stranded twisted pair.

Part 3 Execution

3.1 INSTALLATION

- .1 Install equipment, components so that manufacturer's and CSA labels are visible and legible after commissioning is complete.
- .2 Install field control devices in accordance with manufacturers recommended methods, procedures and instructions.
- .3 Temperature transmitters, humidity transmitters, current-to-pneumatic transducers, solenoid air valves, controllers, relays: install in NEMA I enclosure or as required for specific applications. Provide for electrolytic isolation in cases when dissimilar metals make contact.
- .4 Support field-mounted panels, transmitters and sensors on pipe stands or channel brackets.
- .5 Fire stopping: provide space for fire stopping in accordance with Section 07 84 00 - Firestopping. Maintain fire rating integrity.
- .6 Electrical:
 - .1 Complete installation in accordance with Section 26 05 00 - Common Work Results for Electrical.
 - .2 Modify existing starters to provide for EMCS as indicated in I/O Summaries and as indicated.
 - .3 Terminate wires with screw terminal type connectors suitable for wire size, and number of terminations.

- .4 Install communication wiring in conduit.
 - .1 Provide complete conduit system to link Building Controllers, field panels and OWS(s).
 - .2 Conduit sizes to suit wiring requirements and to allow for future expansion capabilities specified for systems.
 - .3 Maximum conduit fill not to exceed 40%.
 - .4 Design drawings do not show conduit layout.
- .5 Do not run exposed conduits in normally occupied spaces unless otherwise indicated or unless impossible to do otherwise. Department Representative to review before starting Work. Wiring in mechanical rooms, wiring in service rooms and exposed wiring must be in conduit.

3.2 TEMPERATURE AND HUMIDITY SENSORS

- .1 Stabilize to ensure minimum field adjustments or calibrations.
- .2 Readily accessible and adaptable to each type of application to allow for quick easy replacement and servicing without special tools or skills.
- .3 Outdoor installation:
 - .1 Protect from solar radiation and wind effects by non-corroding shields.
 - .2 Install in NEMA 4 enclosures.
- .4 Duct installations:
 - .1 Do not mount in dead air space.
 - .2 Locate within sensor vibration and velocity limits.
 - .3 Securely mount extended surface sensor used to sense average temperature.
 - .4 Thermally isolate elements from brackets and supports to respond to air temperature only.
 - .5 Support sensor element separately from coils, filter racks.
- .5 Averaging duct type temperature sensors.
 - .1 Install averaging element horizontally across the ductwork starting 300 mm from top of ductwork. Each additional horizontal run to be no more than 300 mm from one above it. Continue until complete cross sectional area of ductwork is covered. Use multiple sensors where single sensor does not meet required coverage.
 - .2 Wire multiple sensors in series for low temperature protection applications.
 - .3 Wire multiple sensors separately for temperature measurement.
 - .4 Use software averaging algorithm to derive overall average for control purposes.
- .6 Thermowells: install for piping installations.
 - .1 Locate well in elbow where pipe diameter is less than well insertion length.
 - .2 Thermowell to restrict flow by less than 30%.
 - .3 Use thermal conducting paste inside wells.

3.3 PANELS

- .1 Arrange for conduit and tubing entry from top, bottom or either side.
- .2 Wiring and tubing within panels: locate in trays or individually clipped to back of panel.
- .3 Identify wiring and conduit clearly.

3.4 MAGNEHELIC PRESSURE INDICATORS

- .1 Install adjacent to fan system static pressure sensor and duct system velocity pressure sensor as reviewed by Departmental Representative.
- .2 Locations: as specified.

3.5 PRESSURE AND DIFFERENTIAL PRESSURE SWITCHES AND SENSORS

- .1 Install isolation valve and snubber on sensors between sensor and pressure source where code allows.
 - .1 Protect sensing elements on steam and high temperature hot water service with pigtail syphon between valve and sensor.

3.6 I/P TRANSDUCERS

- .1 Install air pressure gauge on outlet.

3.7 AIR PRESSURE GAUGES

- .1 Install pressure gauges on pneumatic devices, I/P, pilot positioners, motor operators, switches, relays, valves, damper operators, valve actuators.
- .2 Install pressure gauge on output of auxiliary cabinet pneumatic devices.

3.8 IDENTIFICATION

- .1 Identify field devices in accordance with Section 25 05 54 - EMCS: Identification.

3.9 AIR FLOW MEASURING STATIONS

- .1 Protect air flow measuring assembly until cleaning of ducts is completed.

3.10 TESTING AND COMMISSIONING

- .1 Calibrate and test field devices for accuracy and performance in accordance with Section 25 01 11 - EMCS: Start-up, Verification and Commissioning.

END OF SECTION

Part 1 General

1.1 SUMMARY

.1 Section Includes:

- .1 At minimum detailed narrative description of Sequence of Operation of each system including ramping periods and reset schedules.
 - .1 Control Description Logic (CDL) for each system.
 - .2 Input/Output Point Summary Tables for each system.
 - .3 System Diagrams consisting of the following: EMCS System architectural diagram, Control Design Schematic for each system (as viewed on OWS), System flow diagram for each system with electrical ladder diagram for MCC starter interface.

1.2 SEQUENCING

.1 Sequencing of operations for systems as follows:

.1 AHU-1 (typical of 1)

Run Conditions - Scheduled: The unit shall run according to a user definable time schedule in the following modes:

- Occupied Mode: The unit shall maintain
 - A 24°C (adj.) cooling setpoint
 - A 21°C (adj.) heating setpoint.
- Unoccupied Mode (night setback): The unit shall maintain
 - A 29.5°C (adj.) cooling setpoint.
 - A 13°C (adj.) heating setpoint.

Alarms shall be provided as follows:

- High Zone Temp: If the zone temperature is greater than the cooling setpoint by a user definable amount (adj.).
- Low Zone Temp: If the zone temperature is less than the heating setpoint by a user definable amount (adj.).

Demand Limiting - Zone Setpoint Optimization:

To lower power consumption, the zone setpoints shall automatically relax when the facility power consumption exceeds definable thresholds. The amount of relaxation shall be individually configurable for each zone. The zone setpoints shall automatically return to their previous settings when the facility power consumption drops below the thresholds.

Zone Optimal Start:

The unit shall use an optimal start algorithm for morning start-up. This algorithm shall minimize the unoccupied warm-up or cool-down period while still achieving comfort conditions by the start of scheduled occupied period.

Zone Unoccupied Override:

A timed local override control shall allow an occupant to override the schedule and place the

unit into an occupied mode for an adjustable period of time. At the expiration of this time, control of the unit shall automatically return to the schedule.

Emergency Shutdown:

The unit shall shut down and generate an alarm upon receiving an emergency shutdown signal.

Freeze Protection:

The unit shall shut down and generate an alarm upon receiving a freezestat status.

Supply Air Smoke Detection:

The unit shall shut down and generate an alarm upon receiving a supply air smoke detector status.

Supply Fan:

The supply fan shall run anytime the unit is commanded to run, unless shutdown on safeties. To prevent short cycling, the supply fan shall have a user definable (adj.) minimum runtime.

Alarms shall be provided as follows:

- Supply Fan Failure: Commanded on, but the status is off.
- Supply Fan in Hand: Commanded off, but the status is on.
- Supply Fan Runtime Exceeded: Status runtime exceeds a user definable limit (adj.).

Return Fan:

The return fan shall run whenever the supply fan runs.

Alarms shall be provided as follows:

- Return Fan Failure: Commanded on, but the status is off.
- Return Fan in Hand: Commanded off, but the status is on.
- Return Fan Runtime Exceeded: Status runtime exceeds a user definable limit (adj.).

Heat Recovery Wheel - Variable Speed:

The controller shall modulate the heat recovery wheel for energy recovery as follows.

Cooling Recovery Mode:

The controller shall measure the zone temperature and modulate the heat wheel speed to maintain a setpoint 1°C (adj.) less than the zone cooling setpoint. The heat wheel shall run for cool recovery whenever:

- Return air temperature is 3°C (adj.) or more below the outside air temperature.
- AND the zone temperature is above cooling setpoint.
- AND the economizer (if present) is off.
- AND the supply fan is on.

Heating Recovery Mode:

The controller shall measure the zone temperature and modulate the heat wheel speed to maintain a setpoint 1°C (adj.) greater than the zone heating setpoint. The heat wheel shall run for heat recovery whenever:

- Return air temperature is 3°C (adj.) or more above the outside air temperature.
- AND the zone temperature is below heating setpoint.
- AND the economizer (if present) is off.
- AND the supply fan is on.

Periodic Self-Cleaning:

The heat wheel shall run at 5% speed (adj.) for 10sec (adj.) every 4hr (adj.) the unit runs.

Frost Protection:

The heat wheel shall run at 5% speed (adj.) whenever:

- Outside air temperature drops below -9°C (adj.)
- OR the exhaust air temperature drops below -6°C (adj.).

The heat wheel bypass dampers will open whenever the heat wheel is disabled.

Alarms shall be provided as follows:

- Heat Wheel Rotation Failure: Commanded on, but the status is off.
- Heat Wheel in Hand: Commanded off, but the status is on.
- Heat Wheel Runtime Exceeded: Status runtime exceeds a user definable limit (adj.).
- Heat Wheel VFD Fault

Gas Heating Stages:

The controller shall measure the zone temperature and stage the heating to maintain its heating setpoint. To prevent short cycling, there shall be a user definable (adj.) delay between stages, and each stage shall have a user definable (adj.) minimum runtime.

The heating shall be enabled whenever:

- Outside air temperature is less than 18.5°C (adj.).
- AND the zone temperature is below heating setpoint.
- AND the supply fan status is on.
- AND the cooling is not active.

Minimum Outside Air Ventilation - Fixed Percentage:

The outside air dampers shall maintain a minimum position (adj.) during building occupied hours and be closed during unoccupied hours.

Prefilter Differential Pressure Monitor:

The controller shall monitor the differential pressure across the prefilter.

Alarms shall be provided as follows:

- Prefilter Change Required: Prefilter differential pressure exceeds a user definable limit (adj.).

Return Air Carbon Dioxide (CO2) Concentration Monitoring:

The controller shall measure the return air CO2 concentration.

Alarms shall be provided as follows:

- High Return Air Carbon Dioxide Concentration: If the return air CO2 concentration is greater than 1000ppm (adj.) when in the occupied mode.

Return Air Humidity:

The controller shall monitor the return air humidity and use as required for economizer control (if present) or humidity control (if present).

Alarms shall be provided as follows:

- High Return Air Humidity: If the return air humidity is greater than 70% (adj.).
- Low Return Air Humidity: If the return air humidity is less than 35% (adj.).

Return Air Temperature:

The controller shall monitor the return air temperature and use as required for economizer control (if present).

Alarms shall be provided as follows:

- High Return Air Temp: If the return air temperature is greater than 32°C (adj.).
- Low Return Air Temp: If the return air temperature is less than 7°C (adj.).

Supply Air Temperature:

The controller shall monitor the supply air temperature.

Alarms shall be provided as follows:

- High Supply Air Temp: If the supply air temperature is greater than 49°C (adj.).
- Low Supply Air Temp: If the supply air temperature is less than 7°C (adj.).

Environmental Index:

When the zone is occupied, the controller will monitor the deviation of the zone temperature from the heating or cooling setpoint. The controller will also monitor the carbon dioxide concentration and compare it to comfort conditions. This data will be used to calculate a 0 - 100% Environmental Index which gives an indication of how well the zone is maintaining comfort. The controller will also calculate the percentage of time since occupancy began that the Environmental Index is 70% or higher. Optionally, a weighting factor can be configured to adjust the contribution of the zone to the rollup average index based upon the floor area of the zone, importance of the zone, or other static criteria.

Point Name	Hardware Points				Software Points						Show On Graphic
	AI	AO	BI	BO	AV	BV	Loop	Sched	Trend	Alarm	
Exhaust Air Temp	x								x		x
Heat Wheel Discharge Air Temp	x								x		x
Mixed Air Temp	x								x		x
Outside Air Temp	x								x		x
Prefilter Differential Pressure	x								x		
Return Air Carbon Dioxide PPM	x								x		x
Return Air Humidity	x								x		x
Return Air Temp	x								x		x
Supply Air Temp	x								x		x
Zone Temp	x								x		x
Heat Wheel VFD Speed		x							x		x
Freezestat			x						x	x	x
Heat Wheel Status			x						x		x
Heat Wheel VFD Fault			x						x	x	x

[illegible]

Point Name	Hardware Points				Software Points						Show On Graphic
	AI	AO	BI	BO	AV	BV	Loop	Sched	Trend	Alarm	
Return Fan in Hand										x	
Return Fan Runtime Exceeded										x	
Supply Fan Failure										x	
Supply Fan in Hand										x	
Supply Fan Runtime Exceeded										x	

.2 Cabinet Heater

Run Conditions - Scheduled:

The unit shall run according to a user definable time schedule in the following modes:

- Occupied Mode: The unit shall maintain a heating setpoint of 21°C (adj.).
- Unoccupied Mode (night setback): The unit shall maintain a heating setpoint of 18.5°C (adj.).

Alarms shall be provided as follows:

- Low Zone Temp: If the zone temperature is less than the heating setpoint by a user definable amount (adj.).

Zone Setpoint Adjust:

The occupant shall be able to adjust the zone temperature heating and cooling setpoints at the zone sensor.

Zone Optimal Start:

The unit shall use an optimal start algorithm for morning start-up. This algorithm shall minimize the unoccupied warm-up or cool-down period while still achieving comfort conditions by the start of scheduled occupied period.

Fan:

The fan shall run anytime the zone temperature is below heating setpoint, unless shutdown on safeties.

Electric Heating Stage:

The controller shall measure the zone temperature and stage the heating to maintain its heating setpoint. To prevent short cycling, the stage shall have a user definable (adj.) minimum runtime.

The heating shall be enabled whenever:

- Outside air temperature is less than 18.5°C (adj.).
- AND the zone temperature is below heating setpoint.
- AND the fan is on.

Environmental Index:

When the zone is occupied, the controller will monitor the deviation of the zone temperature from the heating or cooling setpoint and calculate a 0 - 100% Environmental Index which gives an indication of how well the zone is maintaining comfort. The controller will also calculate the percentage of time since occupancy began that the Environmental Index is 70% or higher. Optionally, a weighting factor can be configured to adjust the contribution of the zone to the rollup average index based upon the floor area of the zone, importance of the zone, or other static criteria.

Point Name	Hardware Points				Software Points						Show On Graphic
	AI	AO	BI	BO	AV	BV	Loop	Sched	Trend	Alarm	
Zone Setpoint Adjust	x										x
Zone Temp	x								x		x
Fan Start/Stop				x					x		x
Heating Stage 1				x					x		x
Environmental Index					x				x		
Heating Setpoint					x				x		x
Percent of Time Satisfied					x				x		
Schedule								x			
Low Zone Temp										x	

.3 Fin Tube Heater

Run Conditions - Continuous:

The unit shall run continuously and shall maintain a heating setpoint of 21°C (adj.).

Alarms shall be provided as follows:

- Low Zone Temp: If the zone temperature is less than the heating setpoint by a user definable amount (adj.).

Electric Heating Stage:

The controller shall measure the zone temperature and stage the heating to maintain its heating setpoint. To prevent short cycling, the stage shall have a user definable (adj.) minimum runtime.

The heating shall be enabled whenever:

- Outside air temperature is less than 18.5°C (adj.).
- AND the zone temperature is below heating setpoint.

Environmental Index:

When the zone is occupied, the controller will monitor the deviation of the zone temperature from the heating or cooling setpoint and calculate a 0 - 100% Environmental Index which gives an indication of how well the zone is maintaining comfort. The controller will also calculate the percentage of time since occupancy began that the Environmental Index is 70%

or higher. Optionally, a weighting factor can be configured to adjust the contribution of the zone to the rollout average index based upon the floor area of the zone, importance of the zone, or other static criteria.

Point Name	Hardware Points				Software Points						Show On Graphic
	AI	AO	BI	BO	AV	BV	Loop	Sched	Trend	Alarm	
Zone Temp	x								x		x
Heating Stage 1				x					x		x
Environmental Index					x				x		
Heating Setpoint					x				x		x
Percent of Time Satisfied					x				x		
Low Zone Temp										x	

.4 Unit Heater - electric

Run Conditions - Scheduled:

The unit shall run according to a user definable time schedule in the following modes:

- Occupied Mode: The unit shall maintain a heating setpoint of 21°C (adj.).
- Unoccupied Mode (night setback): The unit shall maintain a heating setpoint of 18.5°C (adj.).

Alarms shall be provided as follows:

- Low Zone Temp: If the zone temperature is less than the heating setpoint by a user definable amount (adj.).

Zone Setpoint Adjust:

The occupant shall be able to adjust the zone temperature heating and cooling setpoints at the zone sensor.

Zone Optimal Start:

The unit shall use an optimal start algorithm for morning start-up. This algorithm shall minimize the unoccupied warm-up or cool-down period while still achieving comfort conditions by the start of scheduled occupied period.

Zone Unoccupied Override:

A timed local override control shall allow an occupant to override the schedule and place the unit into an occupied mode for an adjustable period of time. At the expiration of this time, control of the unit shall automatically return to the schedule.

Fan:

The fan shall run anytime the zone temperature drops below heating setpoint, unless shutdown on safeties.

Electric Heating Stage:

The controller shall measure the zone temperature and stage the heating to maintain its

heating setpoint. To prevent short cycling, the stage shall have a user definable (adj.) minimum runtime.

The heating shall be enabled whenever:

- Outside air temperature is less than 18.5°C (adj.).
- AND the zone temperature is below heating setpoint.
- AND the fan is on.

Environmental Index:

When the zone is occupied, the controller will monitor the deviation of the zone temperature from the heating or cooling setpoint and calculate a 0 - 100% Environmental Index which gives an indication of how well the zone is maintaining comfort. The controller will also calculate the percentage of time since occupancy began that the Environmental Index is 70% or higher. Optionally, a weighting factor can be configured to adjust the contribution of the zone to the rollup average index based upon the floor area of the zone, importance of the zone, or other static criteria.

	Hardware Points				Software Points						
Point Name	AI	AO	BI	BO	AV	BV	Loop	Sched	Trend	Alarm	Show On Graphic
Zone Setpoint Adjust	x										x
Zone Temp	x								x		x
Zone Override			x						x		x
Fan Start/Stop				x					x		x
Heating Stage 1				x					x		x
Environmental Index					x				x		
Heating Setpoint					x				x		x
Percent of Time Satisfied					x				x		
Schedule								x			
Low Zone Temp										x	

.5 Unit Heater - Propane

Run Conditions - Scheduled:

The unit shall run according to a user definable time schedule in the following modes:

- Occupied Mode: The unit shall maintain a heating setpoint of 21°C (adj.).
- Unoccupied Mode (night setback): The unit shall maintain a heating setpoint of 18.5°C (adj.).

Alarms shall be provided as follows:

- Low Zone Temp: If the zone temperature is less than the heating setpoint by a user definable amount (adj.).

Zone Setpoint Adjust:

The occupant shall be able to adjust the zone temperature heating and cooling setpoints at the zone sensor.

Zone Optimal Start:

The unit shall use an optimal start algorithm for morning start-up. This algorithm shall minimize the unoccupied warm-up or cool-down period while still achieving comfort conditions by the start of scheduled occupied period.

Zone Unoccupied Override:

A timed local override control shall allow an occupant to override the schedule and place the unit into an occupied mode for an adjustable period of time. At the expiration of this time, control of the unit shall automatically return to the schedule.

Fan:

The fan shall run anytime the zone temperature drops below heating setpoint, unless shutdown on safeties.

Gas Heating Stage:

The controller shall measure the zone temperature and stage the heating to maintain its heating setpoint. To prevent short cycling, the stage shall have a user definable (adj.) minimum runtime.

The heating shall be enabled whenever:

- Outside air temperature is less than 18.5°C (adj.).
- AND the zone temperature is below heating setpoint.
- AND the fan is on.

Environmental Index:

When the zone is occupied, the controller will monitor the deviation of the zone temperature from the heating or cooling setpoint and calculate a 0 - 100% Environmental Index which gives an indication of how well the zone is maintaining comfort. The controller will also calculate the percentage of time since occupancy began that the Environmental Index is 70% or higher. Optionally, a weighting factor can be configured to adjust the contribution of the zone to the rollup average index based upon the floor area of the zone, importance of the zone, or other static criteria.

Point Name	Hardware Points				Software Points						Show On Graphic
	AI	AO	BI	BO	AV	BV	Loop	Sched	Trend	Alarm	
Zone Setpoint Adjust	x										x
Zone Temp	x								x		x
Zone Override			x						x		x
Fan Start/Stop				x					x		x
Heating Stage 1				x					x		x
Environmental Index					x				x		
Heating Setpoint					x				x		x

[illegible]

[illegible]

Part 2 Products

2.1 NOT USED

.1 Not Used.

Part 3 Execution

3.1 NOT USED

.1 Not Used.

END OF SECTION