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**SOLICITATION AMENDMENT  
MODIFICATION DE L'INVITATION**

The referenced document is hereby revised; unless otherwise indicated, all other terms and conditions of the Solicitation remain the same.

Ce document est par la présente révisé; sauf indication contraire, les modalités de l'invitation demeurent les mêmes.

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Science Procurement Directorate/Direction de  
l'acquisition de travaux scientifiques  
Terrasses de la Chaudière, 4th Flo  
10 Wellington Street  
Gatineau  
Quebec  
K1A 0S5

<b>Title - Sujet</b> Lunar Gateway Robotics - Canadarm3	
<b>Solicitation No. - N° de l'invitation</b> 9F052-190271/A	<b>Amendment No. - N° modif.</b> 002
<b>Client Reference No. - N° de référence du client</b> 9F052-190271	<b>Date</b> 2019-08-27
<b>GETS Reference No. - N° de référence de SEAG</b> PW-\$\$\$T-004-36696	
<b>File No. - N° de dossier</b> 004st.9F052-190271	<b>CCC No./N° CCC - FMS No./N° VME</b>
<b>Solicitation Closes - L'invitation prend fin at - à 02:00 PM on - le 2019-12-31</b>	<b>Time Zone</b> Fuseau horaire Eastern Standard Time EST
<b>F.O.B. - F.A.B.</b> Specified Herein - Précisé dans les présentes <b>Plant-Usine:</b> <input type="checkbox"/> <b>Destination:</b> <input type="checkbox"/> <b>Other-Autre:</b> <input checked="" type="checkbox"/>	
<b>Address Enquiries to: - Adresser toutes questions à:</b> Bergeron, Bruno	<b>Buyer Id - Id de l'acheteur</b> 004st
<b>Telephone No. - N° de téléphone</b> (450) 926-4562 ( )	<b>FAX No. - N° de FAX</b> ( ) -
<b>Destination - of Goods, Services, and Construction:</b> <b>Destination - des biens, services et construction:</b> See herein	

**Instructions: See Herein**

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<b>Name and title of person authorized to sign on behalf of Vendor/Firm (type or print)</b> <b>Nom et titre de la personne autorisée à signer au nom du fournisseur/ de l'entrepreneur (taper ou écrire en caractères d'imprimerie)</b>	
<b>Signature</b>	<b>Date</b>



# Canadarm3

## Industry Day 1 Webinar



Public Services and  
Procurement Canada

Services publics et  
Approvisionnement Canada



Canadian Space  
Agency

Agence spatiale  
canadienne

Canada



# CANADARM3: Webinar Agenda

Time	Item	Presenter
13h00 – 13h05	Welcome	
13h05 – 13h10	Gateway and Canadarm3 Background	Stéphane Desjardins, CSA
13h10 – 13h25	Canadarm3 High-Level Requirements	Daniel Rey, CSA
13h25 – 13h35	Engagement and agile procurement approach	Bruno Bergeron, PSPC



# Webinar – Canadarm3

- The intent of this webinar is to provide information to industry on Canadarm3
- Questions:
  - Participants may reserve questions for a one-on-one briefing, or submit them directly to the PSPC Procurement Authority ([bruno.bergeron@tpsgc-pwgsc.gc.ca](mailto:bruno.bergeron@tpsgc-pwgsc.gc.ca))
- Briefings:
  - Electronic copies of the briefings will be posted on [buyandsell.gc.ca](http://buyandsell.gc.ca) following the webinar



# Context

*On February 28, 2019, the Government announced a historic investment in Canada's Space Program committing \$1.9 billion over 24 years to design, build and operate a next-generation robotic system on the Lunar Gateway, a small outpost orbiting the Moon.*

*Canada is requesting feedback in order to better understand the capabilities within industry and academia and how to best leverage this procurement to ensure strong economic benefits for Canadians.*





# Industry engagement

- Industry Engagement activities will be used to give vendors an overview of the Gateway Robotics System Concept and support Canada in the development of key requirements, sourcing strategies and project timelines optimization.



# Lunar Gateway

- Canadian Space Agency is working with other agencies to define the next steps for human spaceflight exploration
- Canada has played a pivotal role in Low Earth Orbit human spaceflight, with Canadarm on the Space Shuttle, and Canadarm2/Dextre on the International Space Station



# GATEWAY PHASE 1

Human Lunar  
Lander

Orion

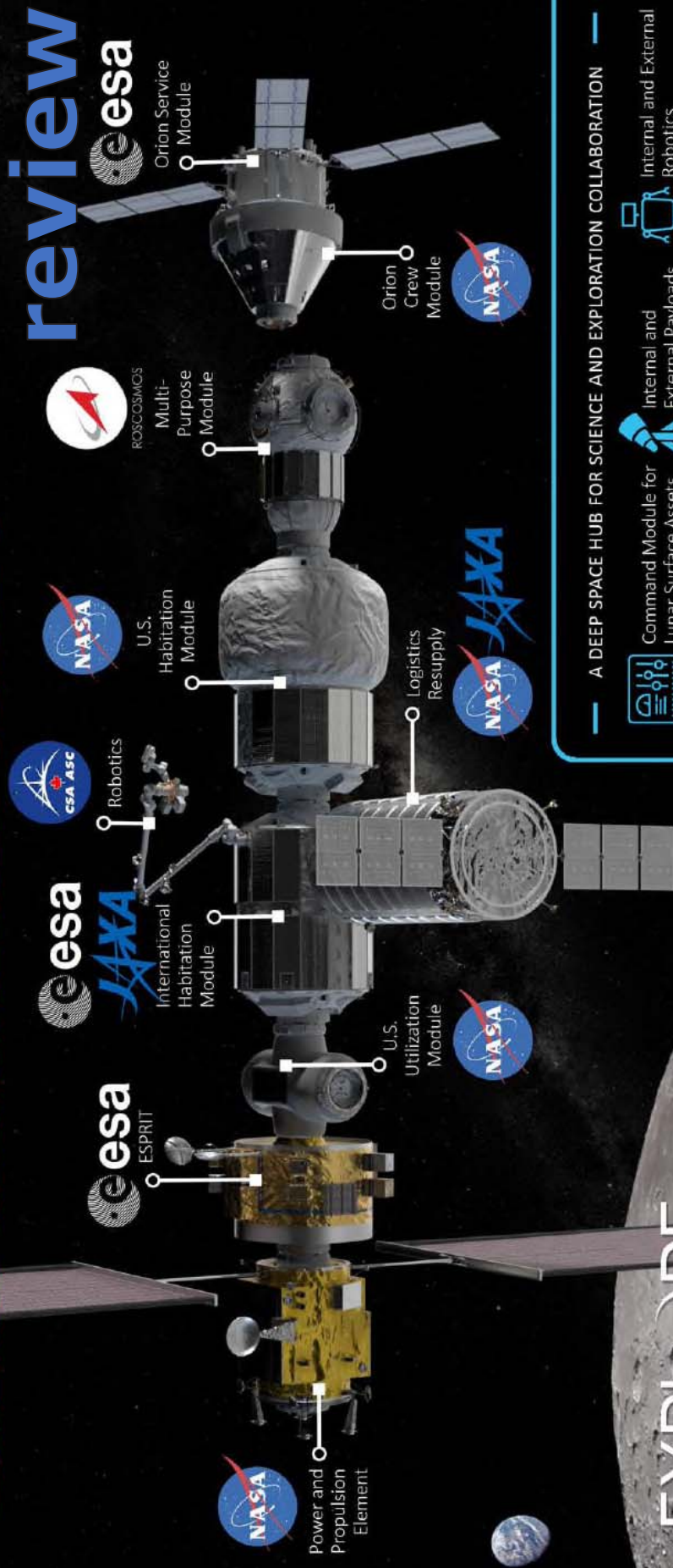
Gateway





# GATEWAY CONFIGURATION CONCEPT

# Under review



- A DEEP SPACE HUB FOR SCIENCE AND EXPLORATION COLLABORATION —
- Command Module for Lunar Surface Assets
  - Internal and External Payloads
  - Internal and External Robotics
  - Mixed Fleet Deliveries
  - Human Lunar Surface Systems
  - International Crew

EXPLORE  
MOON to MARS

# Canadian Contribution – Canadarm3

- Canada's contribution to the Gateway is an artificial intelligence (AI)-enabled Robotics system (Canadarm3) that will be operated from Canada for 15 years
- Budget: Canada is investing \$1.9B over 24 years to design, build and operate the Canadarm3 system
  - This is the complete life cycle cost and includes project cost, operation cost, overall contingency over the life of the project and during operation and government cost
- Schedule: Launch in 2026 or earlier



# Concept Overview – Canadarm3

- The eXploration Large Arm and its Tools
  - Provide external robotic functions for Gateway
- The eXploration Dexterous Arm (small arm)
  - Enhance the capabilities of the large arm and perform its maintenance, capable of supporting payload exchanges, possibly through a Gateway airlock
- Standard Robotic Interface Fixtures, Platforms and Receptacles
  - Provide robotic bases for the two arms, provide worksites and stowage capability for experiments and equipment
- Ground Segment (GS), Robotic Integration and Operations
  - Ground infrastructure that will provide planning, monitoring, commanding, and visualization functions in support of operating the Robotics system from Canada and provide training to ground controllers and crew
  - Professional services to integrate robotic interfaces across Gateway systems, and professional services for operation and sustaining engineering of Canadarm3
- Artificial Intelligence (AI) – Autonomy Capabilities
  - Autonomy and AI-driven operations are needed to achieve a much higher level of self-reliance and efficient operations



## Canadarm3 Concept

Industry solutions pending

# Canadarm Evolution

Canada is seeking to expand and/or spin-in capabilities and generate enablers for commercialization.

Enablers	Canadarm	Canadarm2	Canadarm3
Capture of spacecraft	✓	✓	✓
Assembly/maintenance	✓	✓	✓
Collaborative human-robot operations	✓	✓	✓
Safety and Mission critical operations	✓	✓	✓
Handling, operating and using tools		✓	✓
Ground Control		✓	✓
Accurate motion and contact operations		✓	✓
Self-relocatable		✓	✓
Sense of touch		✓	✓
Self-deployable			✓
Reconfigurable and on-site repair			✓
Enhanced situational awareness			✓
Autonomous planning and operations			✓
Standard Robotic Interfaces			✓



# Canadarm3 - Autonomy

- The following factors drive the need for Canadarm3 to be capable of varying levels of autonomy from Manual to Autonomous through increasing levels of automation:
  - Progressive commissioning and validation of autonomy and AI
  - The Gateway will have low (30 days/year) crew presence for direct control of the robotics
  - The Gateway distance from Earth implies time-delays that make direct control from the ground impractical
  - The Gateway will have periods of minimal communications capability, and robotics may be needed to execute in those periods
  - A deep space goal for Gateway is to demonstrate autonomy from Earth for at least 21 days
  - Operational efficiencies via autonomy



# Canadarm3 - Key Requirements

Canadarm3 shall provide the following functionalities to Gateway:

- inspection,
- installation, removal & replacement of equipment and experiments,
- transfer of systems through the science airlock,
- off-loading & re-loading of logistics vehicles,
- free-flying vehicle capture and release,
- lunar and planetary element assembly and mission equipment transfer,
- berthing & unberthing of modules and vehicles,
- crew commanded assistance to extravehicular activities (EVA).



## Canadarm3 - Key Requirements (cont.)

- The Gateway robotics have to:
  - survive launch and transit, and operate in the Gateway deep-space environment
  - deploy from the launch (stowed) configuration without EVA support
  - be maintainable in-situ without EVA support
  - operate safely (e.g. no single failure can endanger crew or the Gateway vehicle)
    - Drives need for model verification, situational awareness and proximity sensing
  - manipulate objects contaminated with lunar dust



# Canadarm3 – Robotic Interfaces

- Gateway experiments and equipment will be on robotically-compatible installations
  - CSA will procure and provide initial interface equipment for Gateway through the Gateway External Robotic Interfaces Project (GERI)
  - Additional interfaces will be needed, e.g. for larger payloads or payloads requiring fluid transfer
  - Supporting structures will be required for tool and payload stowage, relocation and utilization
  - Integration services for robotic interfaces will be required for Gateway program





# Canadarm3 - Operational Requirements

- Ground operators and Flight Crew
  - Can both control the robotics
  - Both need situational awareness
- Robotics operations need to be planned for efficiency and safety:
  - Planning and operational tools must be efficient (especially for crew) and verify safety
- Operators and Crew need to be trained
  - Crew may need training updates in flight.



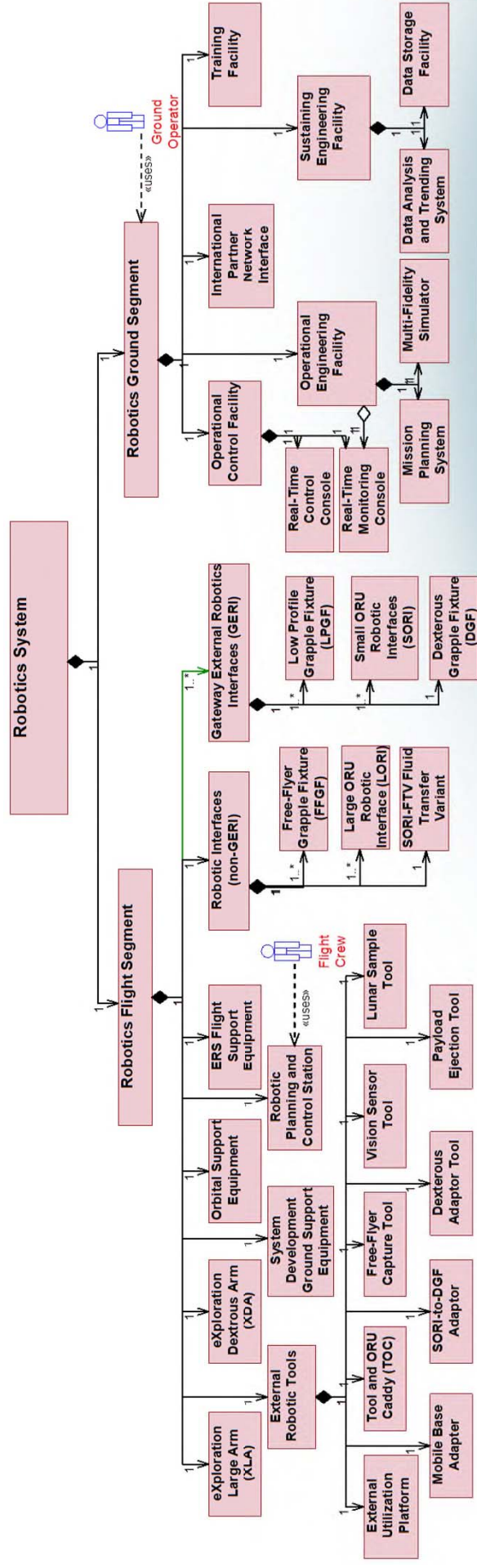
# Canadarm3 - Gateway Requirements

- Canadarm3 will need to meet Gateway mass and power budgets
  - Nominal flight system: 1600 kg
  - Launch package: 2200 kg
  - Large arm operational peak power: 2kW
- Canadarm3 will need to meet Gateway program system requirements, sub-system specifications (power, avionics, thermal, software, etc.) and design standards.



# Canadarm3 – Notional System Overview

based on the Concept Study



# Canadarm3 – AI Application Areas

- Architecture Application Areas
  - Situational Awareness (sense)
  - Task Planning (reason)
  - Task Execution (act)
- Lifecycle Application Areas
  - Engineering
  - Predictive Maintenance & Troubleshooting
  - Training
  - Public Relations
  - Big Data Handling  
(Telemetry, Inspection Data, ...)





**Canadarm3**

# **Engagement and Agile Procurement Approach**



# Guiding Procurement Principles

- Agile in approach
- Extensive collaboration and co-design
- Fair, transparent and competitive processes
- Foster Canadian space industry diversification and ensure innovation, economic and public benefits for Canada



# Agile Procurement

- **I**terative approach for deliverables, allowing for off ramps and pivots.
- Focus on **outcomes**, allowing for a range of solutions to be proposed.
- **C**ross-functional teams are involved in designing and running the procurement.
- **C**ollaborative approach with suppliers, collaborative industry dialogue on needs and outcomes.



# Agile Industry Engagement

## Formal Events

Industry Day  
Aug 2019

Industry Fair  
Sept 2019

RFP Release  
Early 2020  
or sooner

## Draft Document Review

Document Review  
Fall 2019

Draft RFP  
Review  
Late Fall 2019

## Ongoing Parallel Discussions

One-on-one meetings  
Until RFP release

Vendor Questions  
Until RFP release



# Proposed Procurement Strategy



\*Economic Benefit Plan could include, but not be limited to the following elements:

Conceptual design and cost estimates, approach to IP management, technology transfer and commercialization plan, R&D investment, risk management plan, experience and capacity to deliver on timelines, industry contribution, contractual approach, and ensuring Canadian content, and may include innovative approaches similar to the Industrial and Technological Benefits Policy's Value Proposition.

## For More Information

- All enquiries and other communications related to this Industry Engagement process shall be directed exclusively to the PSPC Procurement Authority: Bruno Bergeron (Supply Manager, PSPC) [bruno.bergeron@tpsgc-pwgsc.gc.ca](mailto:bruno.bergeron@tpsgc-pwgsc.gc.ca)
- For general information on how to do business with the Government of Canada: Office of Small and Medium Enterprises (OSME) [bpmeclient.osmeclient@tpsgc-pwgsc.gc.ca](mailto:bpmeclient.osmeclient@tpsgc-pwgsc.gc.ca)
- For all procurement and engagement notices: [www.buyandsell.gc.ca](http://www.buyandsell.gc.ca)

